KNOWLEDGE INSTITUTE OF TECHNOLOGY

(An Autonomous Institution)

Approved by AICTE, Affiliated to Anna University, Chennai. Accredited by NBA (CSE, ECE, EEE & MECH), Accredited by NAAC with 'A' Grade KIOT Campus, Kakapalayam – 637 504. Salem Dt., Tamil Nadu, India.



M.E. / M.Tech. Regulations 2023

M.E. – Embedded System Technologies

CURRICULUM and SYLLABI

(For the Students Admitted from the Academic Year 2023-24 Onwards)

Version:	1.0



KNOWLEDGE INSTITUTE OF TECHNOLOGY(AUTONOMOUS), SALEM -637504

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Website: www.kiot.ac.in

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CHAIRPERSON Board of Studies Faculty of Electrical & Electronics Engg Knowledge Institute of Technology KIOT Campus, Kakapalayam, Salem-637 504 KNOWLEDGE INSTITUTE OF TECHNOLOGY (AUTONOMOUS), SALEM



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M.E. / M.Tech. REGULATIONS 2023 (R 2023) CHOICE BASED CREDIT SYSTEM AND OUTCOME BASED EDUCATION

M.E. – Embedded System Technologies

VISION OF THE INSTITUTE

To be a world-class institution to impart value and need based professional education to the aspiring youth and carving them into disciplined world class professional who have the quest for excellence, achievement orientation and social responsibilities.

A	To promote academic growth by offering state-of-art undergraduate, postgraduate and doctoral programs and to generate new knowledge by engaging in cutting – edge research
в	To nurture talent, Innovation, entrepreneurship, all-round personality and value system among the students and to foster competitiveness among students
с	To undertake collaborative projects which offer opportunities for long-term interaction with academia and industry
D	To pursue global standards of excellence in all our endeavors namely teaching, research, consultancy, continuing education and support functions

VISION OF THE DEPARTMENT

To produce technically competent Electrical and Electronics Engineers having exemplary skills with ethical and social values.

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115510	N OF THE DEPARTMENT
M1	To provide state-of-the art facilities in Electrical and Electronics Engineering for improving the learning environment and research activities
M2	To continuously enrich the knowledge and skill of students towards the employment and creation of innovative products for society
МЗ	To develop ethical, social-valued and entrepreneurship skilled Electrical and Electronics Engineers

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PROGRA	M EDUCATIONAL OBJECTIVES (PEOs)
PEO 1	To provide students good foundation in mathematical, scientific, engineering fundamentals and hardware-software programming intelligence.
PEO 2	To develop among students, the ability to develop embedded systems based smart solutions for purpose of system automation.
PEO 3	To promote student awareness, for life-long learning and introduce them to professional ethics and code of practice.

PROGRAM OUTCOMES (POs)

PO 1	An ability to independently carry out research / investigation and development work to solve practical problems.
PO 2	An ability to write and present a substantial technical report / document.
PO 3	Student should be able to demonstrate a degree of mastery over the area as per the specialization of the program. The mastery should be at a level higher than the requirements in the appropriate bachelor program.
PO 4	Be able to design and develop Embedded system automation based on dedicated ICs that have computation, networking and control capacity.
PO 5	Skill to work on professional software languages, standard modeling and analysis tools & commercial packages with communication protocols and computation platforms for analysis and design of system automation.
PO 6	To involve in research on an industrial problem or develop an innovative smart system with automation as a consumer product through project management and finance with due concerned for socio economic values

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 OCE Campus. Che apping in
 Sugar - CVE Bits

		M.E. EMBEDDED SYSTEM	TECHNOLO	GIES	5				Ve	ersion:	1.0
	Courses	of Study and Scheme of Asse	ssment (R	egula	ation	s 20	23)		Dat	e: 06.0	07.24
sı.	Course	Course Title		Pe	riods	/ W	eek		Max	imum	Marks
No.	Code	Course litie	САТ	СР	L	Т	Р	С	IA	ESE	Tota
		SE	MESTER II	I							
THE	ORY			-		25	-		-		
1	ME23ET310	IoT for Smart Systems	PC	3	3	0	0	3	40	60	100
2	ME23ET4XX	Professional Elective-III	PE	3	3	0	0	3	40	60	100
3	ME23ET4XX	Professional Elective-IV	PE	3	3	0	0	3	40	60	100
4	ME23XX5XX	Open Elective-II	OE	3	3	0	0	3	40	60	100
PRA	CTICAL										77
5	ME23ET601	Project Work - Phase I	PW	12	0	0	12	6	60	40	100
3		Total		24	12	Ō	12	18	220	280	500
		SE	MESTER IN	ŕ.	2	2	1 212				
PRA	CTICAL	· PE					31 K. Al		a ég		
1	ME23ET602	Project Work - Phase II	PW	24	0	0	24	12	60	40	100
		Total	1 -X	24	0/	0/	24	12	60	40	100

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		M.E. EMBEDDED SYSTEM TECHNOLO	GIES	5		(II.	-		Ve	rsion	: 1.0
	Courses of	Study and Scheme of Assessment (R	Regula	atior	ıs 2	023)		Date	e: 06.	07.24
SI. No.	Course Code	Course Title	Periods / Week				M	laxim Mark			
NO.	Lode		CAT	СР	L	Т	P	C	IA	ESE	Tota
		PROFESSIONAL ELE	CTIVE	S							
		SEMESTER III (Professional Electives		& IV)						
1	ME23ET409	Computer Vision	PE	3	3	0	0	3	40	60	100
2	ME23ET410	Multimedia Communications	PE	3	3	0	0	3	40	60	100
3	ME23ET411	Embedded Networking and Automation of Electrical System	PE	3	3	0	0	3	40	60	100
4	ME23ET412	Smart System Design	PE	3	3	0	0	3	40	60	100
5	ME23ET413	Embedded Computing	PE	3	3	0	0	3	40	60	100
6	ME23ET414	Embedded Systems Security	PE	3	3	0	0	3	40	60	100
7	ME23ET415	Robotics and Automation	PE	3	3	0	0	3	40	60	100
8	ME23ET416	Reconfigurable Processor and SoC Design	PE	3	3	0	0	3	40	60	100
9	ME23ET417	MEMS and NEMS Technology	PE	3	S	0	0	3	40	60	100
10	ME23ET418	Entrepreneurship and Embedded Product Development	PE	3	3	0	0	3	40	60	100
11	ME23ET419	Embedded System for Biomedical	PE	3	3	0	0	3	40	60	100
12	ME23ET420	Python Programming for Machine Learning	PE	3	3	0	0	_3	40	60	100
13	ME23ET421	Renewable Energy and Grid Integration	PE	3	3	0	0	3	40	60	100
14	ME23ET422	Electric Vehicles and Power Management	PE	3	3	0	0	3	40	60	100
15	ME23ET423	Smart Grid	PE	3	3	0	0	3	40	60	100

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M.E./M.Tech. Regulations-2023

ME23ET310 / ME23ET501		IoT FOR SMART SYSTEM	CP L T P 3 3 0 0 1
Progra &Bran	imme	M.E. EMBEDDED SYSTEM TECHNOLOGIES	Version : 1.0
Course	e Object	ives:	
1 💎	To st	udy about Internet of Things technologies and its role in real	time applications.
2			
3	To fa	miliarize the accessories and communication techniques for Ic	рТ.
4	To pr	ovide insight about the embedded processor and sensors requ	uired for IoT
5	To fa	miliarize the different platforms and Attributes for IoT	
UNIT-	I	INTRODUCTION TO INTERNET OF THINGS	9
		ardware and software requirements for IOT(L2), Sensor and siness drivers(L2), Typical IoT applications(L3), Trends and im	
UNIT-	11	IOT ARCHITECTURE	9
Commu	ference inication ds(L2), (, Powering, Networking(L2) - Topologies(L2), Layer/Stack Cloud computing for IoT(L2), Bluetooth(L2), Bluetooth Low Er	architecture(L2), Ionergy beacons(L2).
UNIT-	111	PROTOCOLS AND WIRELESS TECHNOLOGIES FOR IOT PROTOCOLS	9
small c		Wireless technologies for IoT: WiFi (IEEE 802.11), Blueto	oth/Bluetooth Smart
ZigBee/	ZigBee S	Smart, UWB (IEEE 802.15.4), 6LoWPAN, Proprietary systems-	Recent trends. (L3).
ZigBee/ UNIT -	ZigBee S	Smart, UWB (IEEE 802.15.4), 6LoWPAN, Proprietary systems- IOT PROCESSORS	Recent trends. (L3).
ZigBee/ UNIT – Service Maintair	ZigBee S IV s/Attrit nability (Smart, UWB (IEEE 802.15.4), 6LoWPAN, Proprietary systems-	Recent trends. (L3). 9 operability, Security
ZigBee/ UNIT – Service Maintair	ZigBee S IV s/Attrit ability (IOT with	Smart, UWB (IEEE 802.15.4), 6LoWPAN, Proprietary systems- IOT PROCESSORS Dutes: Big-Data Analytics for IOT, Dependability, Intere L2). Embedded processors for IOT :Introduction to Pytho	Recent trends. (L3). 9 operability, Security
ZigBee/ UNIT – Service Maintair Building UNIT– ¹ Industri	ZigBee S IV s/Attrite ability (IOT with IOT with V ial IoT, I	Smart, UWB (IEEE 802.15.4), 6LoWPAN, Proprietary systems- IOT PROCESSORS Dutes: Big-Data Analytics for IOT, Dependability, Interd L2). Embedded processors for IOT :Introduction to Pytho n RASPERRY PI and Arduino (L3).	Precent trends. (L3). 9 9 9 9 9 10 9 10 10 10 10 10 10 10 10 10 10
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ZigBee/ UNIT – Service Maintair Building UNIT– ¹ Industri chargin	ZigBee S IV s/Attrite ability (IOT with V ial IOT, I g, Enviro Outcon	Smart, UWB (IEEE 802.15.4), 6LoWPAN, Proprietary systems- IOT PROCESSORS outes: Big-Data Analytics for IOT, Dependability, Interduction L2). Embedded processors for IOT :Introduction to Pythom RASPERRY PI and Arduino (L3). CASE STUDIES Home Automation, smart cities, Smart Grid, connected vehomment, Agriculture, Productivity Applications, IOT Defense(L3)	Recent trends. (L3). 9 operability, Security n programming(L2) 9 icles, electric vehicle 3). Total : 45 Periods BLOOM'S
ZigBee/ UNIT – Service Maintair Building UNIT– ¹ Industri chargin	ZigBee S IV s/Attrite ability (IOT with IOT with IOT with g, Enviro end of thi	Smart, UWB (IEEE 802.15.4), 6LoWPAN, Proprietary systems- IOT PROCESSORS Dutes: Big-Data Analytics for IOT, Dependability, Interd L2). Embedded processors for IOT :Introduction to Pytho In RASPERRY PI and Arduino (L3). CASE STUDIES Home Automation, smart cities, Smart Grid, connected vehomment, Agriculture, Productivity Applications, IOT Defense(L3)	Precent trends. (L3). 9 9 9 9 9 10 10 10 10 10 10 10 10 10 10
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ZigBee/ UNIT – Service Maintair Building UNIT– Industri chargin Course At the e CO1 CO2	ZigBee S IV s/Attrite ability (IOT with V ial IOT, I g, Enviro Outcon end of thi Analyze Compar availab Explain IoT	IOT PROCESSORS IOT PROCESSORS Dutes: Big-Data Analytics for IOT, Dependability, Interduction to Python RASPERRY PI and Arduino (L3). CASE STUDIES Home Automation, smart cities, Smart Grid, connected vehomment, Agriculture, Productivity Applications, IOT Defense(L3) nes: is course, the students will have the ability to the concepts of IoT and its present developments. re and contrast different platforms and infrastructures le for IoT	Percent trends. (L3). 9 operability, Security n programming(L2) 9 icles, electric vehicle 3). Total : 45 Periods BLOOM'S Taxonomy L3 - Apply L2 - Understand
ZigBee/ UNIT – Service Maintair Building UNIT– UNIT– Industri chargin Course At the e CO1 CO2 CO3	ZigBee S IV s/Attril ability (IOT with IOT with IOT with g, Enviro dal IoT, I g, Enviro Outcon end of thi Analyze Explain IoT Analyze	INTERPORT STUDIES Smart, UWB (IEEE 802.15.4), 6LoWPAN, Proprietary systems- IOT PROCESSORS Dutes: Big-Data Analytics for IOT, Dependability, Intere L2). Embedded processors for IOT :Introduction to Pytho n RASPERRY PI and Arduino (L3). CASE STUDIES Home Automation, smart cities, Smart Grid, connected veh nment, Agriculture, Productivity Applications, IOT Defense(L3) nes: is course, the students will have the ability to a the concepts of IOT and its present developments. re and contrast different platforms and infrastructures le for IoT different protocols and communication technologies used in	Percent trends. (L3). 9 operability, Security n programming(L2) 9 icles, electric vehicles). Total : 45 Periods BLOOM'S Taxonomy L3 - Apply L2 - Understand L2 - Understand
ZigBee/ UNIT – Service Maintain Building UNIT– Industri chargin Course At the e CO1 CO2 CO3 CO4 CO5	ZigBee S IV s/Attril ability (IOT with IOT with IOT with g, Enviro dal IoT, I g, Enviro Outcon end of thi Analyze Explain IoT Analyze	IOT PROCESSORS Dutes: Big-Data Analytics for IOT, Dependability, Interduct). Embedded processors for IOT :Introduction to Python RASPERRY PI and Arduino (L3). CASE STUDIES Home Automation, smart cities, Smart Grid, connected vehomment, Agriculture, Productivity Applications, IOT Defense(L3) nes: is course, the students will have the ability to the the concepts of IoT and its present developments. re and contrast different platforms and infrastructures le for IoT different protocols and communication technologies used in the big data analytic and programming of IoT ment IoT solutions for smart applications	Recent trends. (L3). 9 operability, Security n programming(L2) 9 icles, electric vehicles, 10001:30. Total : 45 Periods BLOOM'S Taxonomy L3 - Apply L2 - Understand L3 - Apply L2 - Understand L3 - Apply
ZigBee/ UNIT – Service Maintain Building UNIT– Industri chargin Course At the e CO1 CO2 CO3 CO4 CO5	ZigBee S IV s/Attrite ability (IOT with V ial IOT, I g, Enviro Outcon end of thi Analyze Comparavailab Explain IOT Analyze Implem	IOT PROCESSORS Dutes: Big-Data Analytics for IOT, Dependability, Interd L2). Embedded processors for IOT :Introduction to Pytho RASPERRY PI and Arduino (L3). CASE STUDIES Home Automation, smart cities, Smart Grid, connected veh mment, Agriculture, Productivity Applications, IOT Defense(L3) nes: is course, the students will have the ability to the concepts of IoT and its present developments. re and contrast different platforms and infrastructures le for IoT different protocols and communication technologies used in the big data analytic and programming of IoT ment IoT solutions for smart applications DOKS: epBahga and VijaiMadisetti : A Hands-on Approach "Internet of	Recent trends. (L3). 9 operability, Security n programming(L2) 9 sicles, electric vehicles, 3). Total : 45 Periods BLOOM'S Taxonomy L3 - Apply L2 - Understand L3 - Apply
ZigBee/ UNIT – Service Maintain Building UNIT– Industri chargin Course At the e CO1 CO2 CO3 CO4 CO5 REFERI	ZigBee S IV s/Attrite ability (IOT with IOT with IOT with g, Enviro G, Enviro Comparation availab Explain IoT Analyze Implem ENCE BC Arshdee Press 2 Oliver Wiley,2	Smart, UWB (IEEE 802.15.4), 6LoWPAN, Proprietary systems- IOT PROCESSORS Dutes: Big-Data Analytics for IOT, Dependability, Interduction to Python RASPERRY PI and Arduino (L3). CASE STUDIES Home Automation, smart cities, Smart Grid, connected vehonment, Agriculture, Productivity Applications, IOT Defense(L3) nes: is course, the students will have the ability to e the concepts of IoT and its present developments. re and contrast different platforms and infrastructures le for IoT different protocols and communication technologies used in e the big data analytic and programming of IoT nent IoT solutions for smart applications DOKS: epBahga and VijaiMadisetti : A Hands-on Approach "Internet o 015. Hersent , David Boswarthick and Omar Elloumi " The	Bit Programming (L2) P P Operability, Security n programming (L2) P icles, electric vehicle BLOOM'S Taxonomy L3 - Apply L2 - Understand L3 - Apply L3 - Apply
ZigBee/ UNIT – Service Maintain Building UNIT– Industri chargin Course At the e CO1 CO2 CO3 CO4 CO5 REFERI 1.	ZigBee S IV s/Attrite ability (IOT with IOT with IOT with g, Enviro G, Enviro Comparation availab Explain IoT Analyze Implem ENCE BC Arshdee Press 2 Oliver Wiley,2	Smart, UWB (IEEE 802.15.4), 6LoWPAN, Proprietary systems- IOT PROCESSORS Dutes: Big-Data Analytics for IOT, Dependability, Interduction to Python RASPERRY PI and Arduino (L3). CASE STUDIES Home Automation, smart cities, Smart Grid, connected vehonment, Agriculture, Productivity Applications, IOT Defense(L3) nes: is course, the students will have the ability to a the concepts of IoT and its present developments. re and contrast different platforms and infrastructures le for IoT different protocols and communication technologies used in a the big data analytic and programming of IoT nent IoT solutions for smart applications DOKS: epBahga and VijaiMadisetti : A Hands-on Approach "Internet of 015. Hersent , David Boswarthick and Omar Elloumi " The	Bit Programming (L2) P P Operability, Security n programming (L2) P icles, electric vehicle BLOOM'S Taxonomy L3 - Apply L2 - Understand L3 - Apply L3 - Apply
ZigBee/ UNIT – Service Maintain Building UNIT– Industrichargin Course At the e CO1 CO2 CO3 CO4 CO5 REFERI 1. 2.	ZigBee S IV s/Attrite ability (IOT with V ial IoT, I g, Enviro Outcon and of thi Analyze Compar availab Explain IoT Analyze Implem ENCE BC Arshdee Press 2 Oliver Wiley,2 Samuel Adrian	Smart, UWB (IEEE 802.15.4), 6LoWPAN, Proprietary systems- IOT PROCESSORS Dutes: Big-Data Analytics for IOT, Dependability, Interd L2). Embedded processors for IOT :Introduction to Pythom RASPERRY PI and Arduino (L3). CASE STUDIES Home Automation, smart cities, Smart Grid, connected vehomment, Agriculture, Productivity Applications, IOT Defense(L3) nes: is course, the students will have the ability to a the concepts of IoT and its present developments. re and contrast different platforms and infrastructures le for IoT different protocols and communication technologies used in e the big data analytic and programming of IoT nent IoT solutions for smart applications DOKS: epBahga and VijaiMadisetti : A Hands-on Approach "Internet of 015. Hersent , David Boswarthick and Omar Elloumi " The 016. Greengard, " The Internet of Things", The MIT press, 2015.	Recent trends. (L3). 9 operability, Security n programming(L2) 9 icles, electric vehicles, electric vehicles). Total : 45 Periods BLOOM'S Taxonomy L3 - Apply L2 - Understand L3 - Apply CHAIRPERSON BOWHEY Straigs

6.	Adrian McEwen and Hakim Cassimally, "Designing the Internet of Things", John Wiley and sons, 2014.
7.	Lingyang Song/DusitNiyato/ Zhu Han/Ekram Hossain,"Wireless Device-to-Device Communications and Networks, CAMBRIDGE UNIVERSITY PRESS,2015.
8.	OvidiuVermesan and Peter Friess (Editors), "Internet of Things: Converging Technologies for Smart Environments and I ntegrated Ecosystems", River Publishers Series in Communication, 2013.
9.	Vijay Madisetti , ArshdeepBahga, "Internet of Things (A Hands on-Approach)", 2014.
10.	Lars T.Berger and Krzysztof Iniewski, "Smart Grid applications, communications and security", Wiley, 2015.
11.	JanakaEkanayake, KithsiriLiyanage, Jianzhong Wu, Akihiko Yokoyama and Nick Jenkins, " Smart Grid Technology and Applications", Wiley, 2015.
12.	UpenaDalal,"Wireless Communications & Networks,Oxford,2015.
WEB R	EFERENCES:
1.	https://archive.nptel.ac.in/courses/106/105/106105166/
2.	https://www.geeksforgeeks.org/architecture-of-internet-of-things-iot/
ONLIN	E COURSES:
1.	https://onlinecourses.nptel.ac.in/noc22_cs53/
2.	https://www.udemy.com/course/internet-of-things-iot-fundamentals
VIDEO	REFERENCES:

1.	https://www.youtube.com/watch?v=WUYAjxnwjU4&list=PLE7VH8RC_N3bpVn- e8QzOAHziEgmjQ2qE
2.	https://www.youtube.com/watch?v=urUBLmXFKI0&list=PLgMDNELGJ1CaBrefq- 0eYatfOnoncW0y-
3.	https://www.youtube.com/watch?v=hdZzNOQV5vU

	2	Mapping	of COs with	POs	8	
		_ S	PO	and a second sec		0123
со	PO1	PO2	PO3	PO4	P05	POG
CO1	1	2	1			
CO2	1	2	r. T.	l l		
CO3	1	2	F 3 X C F	1	3	
CO4	2		3	3	3	
CO5	3	2	3	3	3	
Avg.	1.75	2	2.33	2.33	3	
		1-Low, 2	-Medium, 3-H	ligh.		

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ME23	23ET601 PROJECT WORK - PHASE I			CP 12	L	T O	P 12	С 6						
	rogramme & M.E. EMBEDDED SYSTEM TECHNOLOGIES										: 1.0			
Cour	se Objectives:		at e .							110.00		1		
1	To identify relev	vant reseau	rch prob	lems by s	searchin	ng acade	emic da	tabases	and li	iterat	ure.			
2 -	To design and c	conduct pre	eliminary	y studies	to explo	ore iden	tified p	roblems						
3 -	To compile and	present re	search f	findings e	effectivel	ely.								
c	OURSE CONT	ENT:		5 a a 1	· · · ·		0.12.8	/ = 1	8-14					
	Student will ide									surve	у. ті	he s	tuder	t
shou Thre com The	uld submit a pro ee reviews will b mittee during t report for PHAS	oposal and be conduct he review	get it ap ed by Pr and suge	pproved roject rev gestions	by the H /iew com will be o	Head of t nmittee. offered b	the dep . Stude by men	bartmen nts will nbers.	t. be eva	aluate	d by	/ the		t
shou Thre com The	uld submit a pro ee reviews will b mittee during t	oposal and be conduct he review SE -I shoul	get it a ed by Pr and sug d be sub	pproved roject rev gestions omitted b	by the H view com will be o by the st	Head of mittee.	the dep Stude by men at the	bartmen nts will nbers.	t. be eva	aluate		/ the		t
shou Thre com The	uld submit a pro ee reviews will b mittee during t report for PHAS se Outcomes: completion o	oposal and be conduct he review SE -I shoul of this cou	get it a ed by Pr and suge d be sub rse, the	pproved roject rev gestions omitted b	by the H view com will be o by the st	Head of mittee.	the dep Stude by men at the	bartmen nts will nbers.	t. be eva	BLC Tax	d by	' the		.t
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shou Thre com The Cours Upon	uld submit a pro e reviews will b mittee during t report for PHAS se Outcomes: completion o Identify the r Collect, analyz	oposal and be conduct the review SE -I shoul of this cou research pr ze the relev xperiment,	get it a ed by Pr and suge d be sub rse, the roblem. vant lite	pproved roject rev gestions omitted b e studen rature ar	by the H view com will be o by the st ts will t nd finaliz	Head of nmittee. offered t tudents be able ze the re	the dep Stude by men at the to: esearch	oartmen nts will nbers. end of c	t. be eva ourse n.	BLC Tax L3 -	ono App	y the ' S omy oly alyze	2	t

		Mapping	of COs with F	POs		
		+ ***	PO			
COs	PO1	PO2	PO3	PO4	P05	PO6
CO1	2	3	- 3	1		
CO2	3	3	3	2	2	
CO3	3	A 3	-3 / -	, 3,	2	
CO4		Dr. 113 mel	CARIE!	Northe		1
Avg.	3	3	3	2	2	1

CHAIRPERSON Board of Studies Faculty of Electrical & Electronics Engg Knowledge Institute of Technology KIOT Campus, Kakapalayam, Salem-637 504

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ME2	23ET602	PROJECT WORK - PHASE II	СР 24	L O	T O	P 24	C 12
	rogramme & M.E. EMBEDDED SYSTEM TECHNOLOGIES					1: 1.()
Cou	rse Object	ives:					
`1	To provide	a hands on skills by training on domains of embedded systems tech	nolog	gies			
2	To improve	e the design ability and the oral, written presentation skills of the stu	dent	s	- 11. Color		
3	To provide	an insight of developing optimized embedded solution for system au	Itom	atior	n		
4	To emphas	size the need of Hardware &Software design tools usage for real time	e app	licat	ions		
5	To enhanc	e capacity to compete for placement and developing ability for entrep	orene	eurs	hips		
	COURSE C	ONTENT:		1000			
me At	embers. least one p	be evaluated by the committee during the review and suggestions aper should be published by the student in an international / natio be submitted by the students at the end of course.					
	rse Outcor on complet	nes: ion of this course, the students will be able to:		OM			
со		tion for a process through Hardware & Software Tools	L4 -	Ana	alyze	9	11.255
со		eting Pre-Requisites insists choice of project title from the enlisted omain of research topics for Project work:	L3 -	App	oly		
со	Bemons	strate project work to enhance students' capacity to work in the Areas of the Department interests or of Industrial importance	L5 -	Eva	luat	e	
со	A Demons	strate the skill in Oral and Written Communication as presented in sis Book via Viva-Voce Examination	L3 -	Арр	oly	1 1	
со	5 gradatio develop	ed Employability and entrepreneurship capacity due to knowledge up on with getting skilled up through learning & practicing in Design / ment through simulation/ experimental analysis with project report sion (relevant to the candidates project area) by individuals	1	Eva	luat	e	

Calific the

	/	Mapping	of COs with	POs		
c0.			PO			
COs	PO1	PO2	PO3	PO4	PO5	POG
CO1	3	3	3	3	3	3.
CO2	3					
CO3	3			ž.		
CO4	3	3	3	3	3	3
CO5	2	3	3	° 3	3	3
Avg.	2.8	3	3	3	3	3

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NO TOTAL SALES Econtro di Ciertifical e Preditanes Erigo Recortença Indito ne el Technology POTOs Ecos, Cologojayam, Sotem-607.054

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	ET409	COMPUTER VISION	CP L T P C 3 3 0 0 3
Progr Branc	amme &	M.E. EMBEDDED SYSTEM TECHNOLOGIES	Version : 1.0
	se Object	ives:	
1	To introdu	ce the fundamentals of Human and Computer Vision	
2	To introdu	ce the major ideas, concepts, methods and techniques in Co	omputer Vision.
3 -	To impart	Computer Vision knowledge by way of learning related algo	rithms.
4	To make t Images.	hem familiar with both the Theoretical and Practical aspect	ts of Computing wit
5		the student with programming experience for implementing	Computer Vision an
		INTRODUCTION TO COMPUTER VISION	9
Applic Comp Image	ations of o uter Visio Formatio	I Image Processing (L2) – Components of an Image Proc Computer Vision (L2) – Recent Research in Computer Vision n and Basic Concepts of Image Formation(L2): Introduct on and Radiometry(L2) – Geometric Transformation (L2)- nage Reconstruction from a Series of Projections(L3).	(L2). Introduction t ion and Goals (L2)
	-11	IMAGE PROCESSING CONCEPTS AND IMAGE FEATURES	9
		y and Shape Representation(L2) - Interest or Cornet Po	oint Detectors(L3)
UNIT- Introd	– III uction to	Inted Gradients(L3) – Scale Invariant Feature Transform(L2) IMAGE PROCESSING WITH OPENCV OpenCV and Python: Setting up OpenCV(L2) – Image Bas	9 ics in OpenCV(L2)
UNIT- Introd Handli OpenC	- III uction to ing Files a CV(L2): In	IMAGE PROCESSING WITH OPENCY	ics in OpenCV(L2) Image Processing in
UNIT- Introd Handli OpenC Thresh	- III uction to ing Files a CV(L2): In nolding Te	IMAGE PROCESSING WITH OPENCV OpenCV and Python: Setting up OpenCV(L2) – Image Bas nd Images(L2) – Constructing Basic Shapes in OpenCV(L2). nage Processing Techniques(L2) – Constructing and Buildin	ics in OpenCV(L2) Image Processing in
UNIT- Introd Handli OpenC Thresh UNIT Models - Basic Cases Conne	- III uction to ing Files a CV(L2): In holding Te - IV s and type c Structure and App ecting Cam	IMAGE PROCESSING WITH OPENCV OpenCV and Python: Setting up OpenCV(L2) – Image Bas nd Images(L2) – Constructing Basic Shapes in OpenCV(L2). nage Processing Techniques(L2) – Constructing and Buildin chniques(L3).	ics in OpenCV(L2) Image Processing in ng Histograms(L3) 9 puts and outputs(L2 on the Edge(L2). Use Embedded Boards
UNIT- Introd Handli OpenC Thresh UNIT Models – Basic Cases	- III uction to ing Files a CV(L2): In holding Te - IV s and type c Structure and App scting Cam s(L3).	IMAGE PROCESSING WITH OPENCV OpenCV and Python: Setting up OpenCV(L2) – Image Bas nd Images(L2) – Constructing Basic Shapes in OpenCV(L2). nage Processing Techniques(L2) – Constructing and Buildin chniques(L3). OBJECT DETECTION s (L2) – Importance of Object Detection(L2). The Working: In e(L2) – Model Architecture Overview (L2) – Object Detection lications: Video Surveillance(L3) – Self-driving Cars(L3).	ics in OpenCV(L2) Image Processing in ng Histograms(L3) 9 puts and outputs(L2 on the Edge(L2). Use Embedded Boards
UNIT- Introd Handli OpenC Thresh UNIT Models - Basic Cases Conne Videos UNIT- Applica Segme Recogn	- III uction to ing Files a CV(L2): In holding Te - IV s and type c Structure and App ecting Cam s(L3). -V ations: N entation(L nition(L3)	IMAGE PROCESSING WITH OPENCV OpenCV and Python: Setting up OpenCV(L2) – Image Bass nd Images(L2) – Constructing Basic Shapes in OpenCV(L2). nage Processing Techniques(L2) – Constructing and Buildin chniques(L3). OBJECT DETECTION s (L2) – Importance of Object Detection(L2). The Working: In e(L2) – Model Architecture Overview (L2)– Object Detection lications: Video Surveillance(L3) – Self-driving Cars(L3). heras to Embedded Boards(L3) – Simple algorithms for pro-	ics in OpenCV(L2) Image Processing in ng Histograms(L3) 9 puts and outputs(L2) on the Edge(L2). Us Embedded Boards ocessing Images and 9 in Medical Imagen nd Facial Expression
UNIT- Introd Handli OpenC Thresh UNIT Models - Basic Cases Conne Videos UNIT- Applica Segme Recogne Eye Tr	 III uction to ing Files a CV(L2): In holding Te IV and type c Structure and App ecting Came (L3). V ations: Mentation(L nition(L3) acking (L3) 	IMAGE PROCESSING WITH OPENCV OpenCV and Python: Setting up OpenCV(L2) – Image Bass nd Images(L2) – Constructing Basic Shapes in OpenCV(L2). nage Processing Techniques(L2) – Constructing and Buildin chniques(L3). OBJECT DETECTION s (L2) – Importance of Object Detection(L2). The Working: In e(L2) – Model Architecture Overview (L2) – Object Detection of lications: Video Surveillance(L3) – Self-driving Cars(L3). heras to Embedded Boards(L3) – Simple algorithms for pro- APPLICATIONS AND CASE STUDIES Machine Learning algorithms and their Applications 3) – Motion Estimation and Object Tracking(L3) – Face an – Image Fusion(L2). Case Studies: Face Detection(L3) – (3) – Handwriting Recognition with HoG (L3).	ics in OpenCV(L2) Image Processing in ng Histograms(L3) 9 puts and outputs(L2) on the Edge(L2). Us Embedded Boards ocessing Images an 9 in Medical Imagend Facial Expression Object Tracing(L3) Total : 45 Period
UNIT- Introd Handli OpenC Thresh UNIT Models - Basic Cases Conne Videos UNIT- Applica Segme Recogne Eye Tr	 III uction to ing Files a CV(L2): In holding Te IV and type control type	IMAGE PROCESSING WITH OPENCV OpenCV and Python: Setting up OpenCV(L2) - Image Bass nd Images(L2) - Constructing Basic Shapes in OpenCV(L2). nage Processing Techniques(L2) - Constructing and Buildin chniques(L3). OBJECT DETECTION s (L2) - Importance of Object Detection(L2). The Working: In e(L2) - Model Architecture Overview (L2) - Object Detection of lications: Video Surveillance(L3) - Self-driving Cars(L3). heras to Embedded Boards(L3) - Simple algorithms for pro- APPLICATIONS AND CASE STUDIES Machine Learning algorithms and their Applications 3) - Motion Estimation and Object Tracking(L3) - Face and - Image Fusion(L2). Case Studies: Face Detection(L3) - (3) - Handwriting Recognition with HoG (L3).	ics in OpenCV(L2) Image Processing in ng Histograms(L3) 9 puts and outputs(L2 on the Edge(L2). Use Embedded Boards ocessing Images and 9 in Medical Image nd Facial Expression Object Tracing(L3) Total : 45 Periods BLOOM'S
UNIT- Introd Handli OpenC Thresh UNIT Models - Basic Cases Conne Videos UNIT- Applica Segme Recogne Eye Tr	 III uction to ing Files a CV(L2): In holding Te IV s and type c Structure and App ecting Cam s(L3). V ations: N entation(L nition(L3) racking (L3) e Outcon completi Understar 	IMAGE PROCESSING WITH OPENCV OpenCV and Python: Setting up OpenCV(L2) – Image Bas nd Images(L2) – Constructing Basic Shapes in OpenCV(L2). nage Processing Techniques(L2) – Constructing and Buildin chniques(L3). OBJECT DETECTION s (L2) – Importance of Object Detection(L2). The Working: In e(L2) – Model Architecture Overview (L2) – Object Detection of lications: Video Surveillance(L3) – Self-driving Cars(L3). heras to Embedded Boards(L3) – Simple algorithms for proc APPLICATIONS AND CASE STUDIES Machine Learning algorithms and their Applications 3) – Motion Estimation and Object Tracking(L3) – Face an – Image Fusion(L2). Case Studies: Face Detection(L3) – G B)– Handwriting Recognition with HoG (L3).	ics in OpenCV(L2) Image Processing in ng Histograms(L3) 9 puts and outputs(L2 on the Edge(L2). Use Embedded Boards ocessing Images and 9 in Medical Image of Facial Expression Object Tracing(L3) Total : 45 Periods
UNIT- Introd Handli OpenC Thresh UNIT Models - Basic Cases Conne Videos UNIT- Applica Segme Recogne Eye Tr Cours Upon	- III uction to ing Files a CV(L2): In holding Te - IV s and type c Structure and App ecting Cam s(L3). -V ations: N entation(L nition(L3) racking (L3) racking (L3) re Outcon completi Understar and imag	IMAGE PROCESSING WITH OPENCV OpenCV and Python: Setting up OpenCV(L2) – Image Bas nd Images(L2) – Constructing Basic Shapes in OpenCV(L2). nage Processing Techniques(L2) – Constructing and Buildin chniques(L3). OBJECT DETECTION s (L2) – Importance of Object Detection(L2). The Working: In e(L2) – Model Architecture Overview (L2) – Object Detection of lications: Video Surveillance(L3) – Self-driving Cars(L3). heras to Embedded Boards(L3) – Simple algorithms for pro- APPLICATIONS AND CASE STUDIES Machine Learning algorithms and their Applications 3) – Motion Estimation and Object Tracking(L3) – Face an – Image Fusion(L2). Case Studies: Face Detection(L3) – C 3) – Handwriting Recognition with HoG (L3).	ics in OpenCV(L2) Image Processing in ng Histograms(L3) 9 puts and outputs(L2 on the Edge(L2). Use Embedded Boards ocessing Images and 9 in Medical Image nd Facial Expression Object Tracing(L3) Total : 45 Periods BLOOM'S Taxonomy
UNIT- Introd Handli OpenC Thresh UNIT Models - Basic Cases Conne Videos UNIT- Applica Segme Recogne Eye Tr Cours Upon CO1 CO2	 III uction to ing Files a CV(L2): In holding Te IV s and type c Structure and App ecting Carres (L3). V ations: N ations: N entation(L nition(L3)) acking (L3) e Outcon completi Understan and imag Infer know 	IMAGE PROCESSING WITH OPENCV OpenCV and Python: Setting up OpenCV(L2) – Image Bas nd Images(L2) – Constructing Basic Shapes in OpenCV(L2). nage Processing Techniques(L2) – Constructing and Buildin chniques(L3). OBJECT DETECTION s (L2) – Importance of Object Detection(L2). The Working: In e(L2) – Model Architecture Overview (L2) – Object Detection of lications: Video Surveillance(L3) – Self-driving Cars(L3). heras to Embedded Boards(L3) – Simple algorithms for pro- APPLICATIONS AND CASE STUDIES Machine Learning algorithms and their Applications 3) – Motion Estimation and Object Tracking(L3) – Face an – Image Fusion(L2). Case Studies: Face Detection(L3) – (B) – Handwriting Recognition with HoG (L3). mes: on of this course the students will be able to: nd the major concepts and techniques in computer vision e processing	ics in OpenCV(L2) Image Processing in ng Histograms(L3) 9 puts and outputs(L2 on the Edge(L2). Use Embedded Boards ocessing Images and 9 in Medical Image nd Facial Expression Object Tracing(L3) Total : 45 Periods BLOOM'S Taxonomy L2 - Understand

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C04	Develop real-life Computer Visions Applications	L2 - Understand
C05	Build design of a Computer Vision System for a specific problem.	L3 - Apply
REFE	RENCE BOOKS:	
1.	"Digital Image Processing", 4th Edition (Global Edition), Rafael C Go Woods, Pearson Education Limited, 2018.	onzalez and Richard E
2.	"Computer Vision and Image Processing - Fundamentals and Applic Bhuyan, CRC Press, 2020.	
3.	"Mastering OpenCV 4 with Python", Alberto Fernández Villán, Packt	
4.	"Practical Python and Open CV: Case Studies", 3rd Edition, Adrian Search, 2016.	Rosebrock, PyImage
WEB	REFERENCES:	-
1.	https://archive.nptel.ac.in/courses/106/105/106105216/	
2.	https://www.researchgate.net/publication/358823508_Computer- Vision_Based_Object_Detection_and_Recognition_for_Service_Robo ment	ot_in_Indoor_Environ
ONL	INE COURSES:	
1.	https://onlinecourses.nptel.ac.in/noc21_cs101	
2.	https://onlinecourses.nptel.ac.in/noc23_ee39	
VIDE	O REFERENCES:	
1.	https://www.youtube.com/watch?v=3LaVxEX3F0o&list=PLwdnzIV3c 6gHv1QoAo	ogoVsma5GmBSsgJM
2.	https://www.youtube.com/watch?v=a4yd0Au8QLg&list=PLyqSpQzT GFFEZIpKf	E6M8X3Veh5ijSQ2U

	Mapping of COs with POs										
		And a former	PC	D							
со	PO1	PO2	S PO3	PO4	P05	POG					
CO1	2	3	2								
CO2	2	2	2	2							
CO3	3	12 3	1 -3 7/	3 /	3.						
CO4	3	3011	3	3 4 9	3						
CO5	3	3	3	3	3						
Avg.	2.6	2.8	2.6	2.75	3						
		1–Low,	2 -Medium, 3	-High.							

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	MULTIMEDIA COMMUNICATIONS	CP L T P C 3 3 0 0 3
Programme 8 Branch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	Version : 1.0
Course Object	tives:	- x
1 To define	the Multimedia Communication Models	1
2 To explain	Multimedia Transport in Wireless Networks	
3 To Solve t	he Security issues in multimedia networks	
4 To Illustra	te real-time multimedia network applications.	
5 To explain	different network layer based application	
UNIT-I	INTRODUCTION TO MULTIMEDIA COMMUNICATIONS	9
multimedia ap	L2), multimedia information representation(L2), mul plications(L2), Application and networking terminology(S(L2), Digitization principles(L2), Text, images, audio and v	L2), network QoS and
UNIT-II	COMPRESSION TECHNIQUES FOR TEXT AND IMAGE	9
Huffman, LZW	e compression(L2), compression principles(L2), text co /(L2), Document Image compression using T2 and GIF, TIFF and JPEG(L3) COMPRESSION TECHNIQUES FOR AUIDO AND	T3coding(L3), image
UNIT- III	VIDEO	9
and Linear pre	o compression(L2), audio compression – principles(L2), D dictive coding(L2), Code-Excited LPC, Perceptual coding ompression, video compression principles(L3).	PCM, ADPCM, Adaptive (L2), MPEG and Dolby
	STANDARDS AND FRAMEWORK	-
UNIT – IV	STANDARDS AND FRAMEWORK	9
Video compres Reversible VLC	sion standards (L2): H.261, H.263, MPEG, MPEG 1, MPEs, MPEG 7 standardization process of multimedia conten	G 2, MPEG-4 (L2) and
Video compres Reversible VLC multimedia frar	sion standards (L2): H.261, H.263, MPEG, MPEG 1, MPEs, MPEG 7 standardization process of multimedia conten	G 2, MPEG-4 (L2) and
Video compres Reversible VLC multimedia fran UNIT-V Notion of synch Introduction to	sion standards (L2): H.261, H.263, MPEG, MPEG 1, MPE s, MPEG 7 standardization process of multimedia conten- mework(L3). SYNCHRONIZATION AND MANAGEMENT pronization, presentation requirements(L2), reference mode of SMIL(L2), Multimedia operating systems, Resource	G 2, MPEG-4 (L2) and t description, MPEG 21 9 del for synchronization, management, process
Video compres Reversible VLC multimedia frar UNIT-V Notion of synch Introduction to management to	sion standards (L2): H.261, H.263, MPEG, MPEG 1, MPE s, MPEG 7 standardization process of multimedia conten- mework(L3). SYNCHRONIZATION AND MANAGEMENT pronization, presentation requirements(L2), reference mode o SMIL(L2), Multimedia operating systems, Resource echniques(L3).	G 2, MPEG-4 (L2) and t description, MPEG 21 9 del for synchronization, management, process Total : 45 Periods
Video compress Reversible VLC multimedia fran UNIT-V Notion of synch Introduction to management to Course Outcon	sion standards (L2): H.261, H.263, MPEG, MPEG 1, MPE s, MPEG 7 standardization process of multimedia conten- mework(L3). SYNCHRONIZATION AND MANAGEMENT pronization, presentation requirements(L2), reference mode o SMIL(L2), Multimedia operating systems, Resource echniques(L3).	G 2, MPEG-4 (L2) and t description, MPEG 21 9 del for synchronization, management, process
Video compress Reversible VLC multimedia fran UNIT-V Notion of synch Introduction to management to Course Outcon Upon complet	sion standards (L2): H.261, H.263, MPEG, MPEG 1, MPE s, MPEG 7 standardization process of multimedia conten mework(L3). SYNCHRONIZATION AND MANAGEMENT pronization, presentation requirements(L2), reference mode o SMIL(L2), Multimedia operating systems, Resource echniques(L3).	G 2, MPEG-4 (L2) and t description, MPEG 21 9 del for synchronization, management, process Total : 45 Periods BLOOM'S
Video compress Reversible VLC multimedia fran UNIT–V Notion of synch Introduction to management to Course Outcon Upon complet CO1 Deploy to CO2 Apply Qu	sion standards (L2): H.261, H.263, MPEG, MPEG 1, MPE s, MPEG 7 standardization process of multimedia conten- mework(L3). SYNCHRONIZATION AND MANAGEMENT nronization, presentation requirements(L2), reference mo- be SMIL(L2), Multimedia operating systems, Resource echniques(L3). mes: ion of this course the students will be able to: the right multimedia communication models. DS to multimedia network applications with efficient routing	G 2, MPEG-4 (L2) and t description, MPEG 21 9 del for synchronization, management, process Total : 45 Periods BLOOM'S Taxonomy
Video compress Reversible VLC multimedia fran UNIT–V Notion of synch Introduction to management te Course Outcon Upon complet CO1 Deploy to techniqu	sion standards (L2): H.261, H.263, MPEG, MPEG 1, MPE s, MPEG 7 standardization process of multimedia conten- mework(L3). SYNCHRONIZATION AND MANAGEMENT nronization, presentation requirements(L2), reference mo- be SMIL(L2), Multimedia operating systems, Resource echniques(L3). mes: ion of this course the students will be able to: the right multimedia communication models. DS to multimedia network applications with efficient routing	G 2, MPEG-4 (L2) and t description, MPEG 21 9 del for synchronization, management, process Total : 45 Periods BLOOM'S Taxonomy L2 – Understand
Video compress Reversible VLC multimedia fran UNIT-V Notion of synch Introduction to management to Course Outcon Upon complet CO1 Deploy to CO2 Apply Qu techniqu CO3 Solve th	sion standards (L2): H.261, H.263, MPEG, MPEG 1, MPE s, MPEG 7 standardization process of multimedia conten- mework(L3). SYNCHRONIZATION AND MANAGEMENT pronization, presentation requirements(L2), reference mode of SMIL(L2), Multimedia operating systems, Resource echniques(L3). mes: tion of this course the students will be able to: the right multimedia communication models. So to multimedia network applications with efficient routing tes.	G 2, MPEG-4 (L2) and t description, MPEG 21 9 del for synchronization, management, process Total : 45 Periods BLOOM'S Taxonomy L2 – Understand L3 – Apply
Video compress Reversible VLC multimedia fran UNIT-V Notion of synch Introduction to management to Course Outcon Upon complet CO1 Deploy to CO2 Apply Qu techniqu CO3 Solve th CO4 Develop	sion standards (L2): H.261, H.263, MPEG, MPEG 1, MPE s, MPEG 7 standardization process of multimedia conten- mework(L3). SYNCHRONIZATION AND MANAGEMENT pronization, presentation requirements(L2), reference mode o SMIL(L2), Multimedia operating systems, Resource echniques(L3). mes: ion of this course the students will be able to: the right multimedia communication models. S to multimedia network applications with efficient routing ues. e security threats in the multimedia networks	G 2, MPEG-4 (L2) and t description, MPEG 21 9 del for synchronization, management, process Total : 45 Periods BLOOM'S Taxonomy L2 - Understand L3 - Apply L2 - Understand
Video compress Reversible VLC multimedia fran UNIT-V Notion of synch Introduction to management to Course Outcon Upon complet CO1 Deploy to techniqu CO2 Apply Qo techniqu CO3 Solve th CO4 Develop CO5 Improve	sion standards (L2): H.261, H.263, MPEG, MPEG 1, MPE s, MPEG 7 standardization process of multimedia conten- nework(L3). SYNCHRONIZATION AND MANAGEMENT monization, presentation requirements(L2), reference mon o SMIL(L2), Multimedia operating systems, Resource echniques(L3). mes: ion of this course the students will be able to: the right multimedia communication models. DS to multimedia network applications with efficient routing les. the real-time multimedia network applications the real-time multimedia network applications to synchronize and manage the multimedia systems OOKS:	G 2, MPEG-4 (L2) and t description, MPEG 21 9 del for synchronization, management, process Total : 45 Periods BLOOM'S Taxonomy L2 - Understand L3 - Apply L2 - Understand L3 - Apply L2 - Understand
Video compress Reversible VLC multimedia fran UNIT-V Notion of synch Introduction to management to Course Outcon Upon complet CO1 Deploy to CO2 Apply Qo techniqu CO3 Solve th CO4 Develop CO5 Improve REFERENCE Bo 1. Fred Hal	sion standards (L2): H.261, H.263, MPEG, MPEG 1, MPE s, MPEG 7 standardization process of multimedia conten- mework(L3). SYNCHRONIZATION AND MANAGEMENT nronization, presentation requirements(L2), reference mo- b SMIL(L2), Multimedia operating systems, Resource echniques(L3). mes: ion of this course the students will be able to: the right multimedia communication models. DS to multimedia network applications with efficient routing les. e security threats in the multimedia networks the real-time multimedia network applications e to synchronize and manage the multimedia systems OOKS: sall, "Multimedia Communications", Pearson education,200	G 2, MPEG-4 (L2) and t description, MPEG 21 9 del for synchronization, management, process Total : 45 Periods BLOOM'S Taxonomy L2 - Understand L3 - Apply L2 - Understand L3 - Apply L2 - Understand
Video compress Reversible VLC multimedia fran UNIT-V Notion of synch Introduction to management to Course Outcor Upon complet CO1 Deploy to CO2 Apply Qo techniqu CO3 Solve th CO4 Develop CO5 Improve REFERENCE B 1. Fred Hal	sion standards (L2): H.261, H.263, MPEG, MPEG 1, MPE s, MPEG 7 standardization process of multimedia conten- nework(L3). SYNCHRONIZATION AND MANAGEMENT monization, presentation requirements(L2), reference mon o SMIL(L2), Multimedia operating systems, Resource echniques(L3). mes: ion of this course the students will be able to: the right multimedia communication models. DS to multimedia network applications with efficient routing les. the real-time multimedia network applications the real-time multimedia network applications to synchronize and manage the multimedia systems OOKS:	9 del for synchronization, management, process Total : 45 Periods BLOOM'S Taxonomy L2 - Understand L3 - Apply L2 - Understand L3 - Apply L2 - Understand D1. Communications and
Video compress Reversible VLC multimedia fran UNIT-V Notion of synch Introduction to management to Course Outcon Upon complet CO1 Deploy to CO2 Apply Qo techniqu CO3 Solve th CO4 Develop CO5 Improve REFERENCE Bo 1. Fred Hal 2. Raif St Applicati	sion standards (L2): H.261, H.263, MPEG, MPEG 1, MPE s, MPEG 7 standardization process of multimedia conten mework(L3). SYNCHRONIZATION AND MANAGEMENT monization, presentation requirements(L2), reference mono- or SMIL(L2), Multimedia operating systems, Resource echniques(L3). mes: ion of this course the students will be able to: the right multimedia communication models. oS to multimedia network applications with efficient routing les. e security threats in the multimedia networks the real-time multimedia network applications e to synchronize and manage the multimedia systems OOKS: sall, "Multimedia Communications", Pearson education,200 einmetz, Klara Nahrstedt, "Multimedia: Computing, ons",Pearsoneducation,2002.	G 2, MPEG-4 (L2) and t description, MPEG 21 9 del for synchronization, management, process Total : 45 Periods BLOOM'S Taxonomy L2 - Understand L3 - Apply L2 - Understand L3 - Apply L2 - Understand L3 - Apply L2 - Understand 01. Communications and CHAIRPERSON Board of Studies

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KIOT Campus, Kakapalayam, M.E./M.Tech. Regulation Regulation 80 https://archive.nptel.ac.in/courses/117/105/117105083/

ONLINE COURSES:

https://archive.nptel.ac.in/courses/105/107/105107160/

https://archive.nptel.ac.in/courses/117/105/117105083/

VIDEO REFERENCES:

https://www.youtube.com/watch?v=4-AsEtIpEWg

https://www.youtube.com/watch?v=Dz3Du5jod90

		Mappi	ing of COs wit	h POs		
			PC)		- 1840 - 1859 - 1870 - 1870 - 1870 - 1870 - 1870 - 1870 - 1870 - 1870 - 1870 - 1870 - 1870 - 1870 - 1870 - 1870
со	PO1	PO2	PO3	PO4	PO5	POG
CO1	2	-	1		3	
CO2	2		1	3	2	2
CO3	3					
CO4				2	3	2
CO5	2					
Avg.	2.25			2.5	2.66	2

1-Low, 2 -Medium, 3-High.



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ME23ET411	EMBEDDED NETWORKING AND AUTOMATION OF ELECTRICAL SYSTEM		L T 3 0	Р 0	C 3
Programme &Branch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	V	ersion	: 1.	0
Course Obje	ctives:		a second a s		
1 To discuss	the fundamentals building blocks of a digital instrument.			1.29	
2 Introduce	wired, WSN for configuring metering network				-
3 Discuss re	quirements for grid automation using meters.		9	5	012 DOMAS 12
4 To discuss	networking configuration to develop PAN			-	
5 To discuss	the functions of digital instrument Power quality monitoring	g		÷	
UNIT-I	BUILDING SYSTEM AUTOMATION		9	1015-161	
Based & PC appliances(L2	r(L2) - Data acquisition system(L2)- Signal conditioning of based data acquisition (L2)- uC for automation and p)-processor based digital controllers for switching Actuator system automation with multi-channel Instrumentation and EMBEDDED NETWORKING OF INSTRUMENT CLUSTER	orotecti s(I2):	ion of Steppe	elec er mo	trica
to WSN(L2)	 RS 232C- embedded ethernet - MOD bus and CAN bus, LIN Commercially available sensor nodes-Zigbee protocol(L2)-Ne	twork	Тор	olog
Energy efficie networks(L3)·	nt MAC protocols(L2) – SMAC – Data Centric routing(L2)- Database perspective on sensor networks- IoT Applications	Applic s(L3).	ations	of s	enso
networks(L3)· UNIT– III	Database perspective on sensor networks- IoT Applications AUTOMATION OF SUBSTATION	s(L3).	9	3	
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networks(L3)- UNIT- III Substation au for smart Su Interoperabilit Energy Stora monitoring ele UNIT - IV Characteristic Challenges in for EV plug in	Database perspective on sensor networks- IoT Applications AUTOMATION OF SUBSTATION tomation- Distribution SCADA system principles(L2) -role of bstation automation(L2)- Introduction to Role of IEC 61 ty and IEC 61850(L2)-challenges of Substations in Smart G ge and Distribution Systems monitoring(L2) - Commune ectric utility asset (L3).	of PMU, 850,IE irid(L2) hication ces bas ith AM	9 RTU, I EEC37) - cha n Chal 9 sed on I -Sma	EDs, .118 llenge lenge sola	BU: std es o es i r grid
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KIOT Campus Kakapalayan Salem -637 504

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C04	Deployment of PAN for metering networked commercial L3 – Apply
C05	Improved Employability and entrepreneurship capacity due to knowledge up gradation on recent trends in embedded L2 - Understand networked communications
REFER	RENCE BOOKS:
1.	Control and automation of electrical power distribution systems, James Northcote-Green Robert Wilson, CRC, Taylor and Francis, 2006
2.	Krzysztof Iniewski, "Smart Grid , Infrastructure & Networking", TMcGH, 2012
3.	Robert Faludi, "Building Wireless Sensor Networks, O'Reilly, 2011
4.	Mohammad Ilyas And ImadMahgoub, 'Handbook of sensor Networks: Compact wireles and wired sensing systems', CRC Press, 2005
5.	Shih-Lin Wu,Yu-Chee Tseng,{"Wireless Ad Hoc Networking,PAN,LAN,SAN,Aurebac Pub,2012
6.	Sanjay Gupta, "Virtual Instrumentation, LABVIEW", TMH, New Delhi, 2003
7.	Ernest O. Doeblin and Dhanesh N Manik, "Measrement Systems – Application ar Design", 5th Edn, TMH, 2007.
8.	BhaskarKrishnamachari, 'Networking wireless sensors', Cambridge press 2005
WEB F	REFERENCES:
1	https://genuspower.com/how-to-ensure-power-quality-monitoring-and-control-using- smart-metering-solutions
2	https://energy.ec.europa.eu/topics/markets-and-consumers/smart-grids-and-meter
ONLIN	NE COURSES:
1	https://onlinecourses.nptel.ac.in/noc21_ee68/
-	https://onlinecourses.nptel.ac.in/noc21_ee32/
2	
	DREFERENCES:
	D REFERENCES:

	Mapping of COs with POs										
		Provide State	SALENP	0							
со	PO1	PO2	PO3	PO4	PO5	P06					
CO1	3	1	2	1	2	11					
CO2	1	1/ 38 131 11	1 72/	1 11 2 1/100	3						
CO3	3	1	2	- 7							
CO4	2		2	3	3						
CO5	2	1	2								
Avg.	2.2	1	2	2	2.66	•					
	-	1-Low	, 2 –Medium, 3	-High.		The second					

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	SMART SYSTEM DESIGN	3 3 0 0 3					
Programme &Branch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	Version : 1.0					
Course Obje	ctives:						
1 To unders	tand about the smart system technologies and its role in real time	applications.					
2 To expose	students to different open-source platforms and attributes						
3 To teach t	he architecture and requirements of Home Automation						
4 To provide	e an insight into smart appliances and energy management concep	epts.					
5 To familia	To familiarize the design and development of embedded system based sy						
UNIT-I	INTRODUCTION	9					
(L2)- Data Ai (IFTTT & Thin	Smart sensors and Actuators(L2) – Communication protocols us nalytics: Need & Types (L2)– Open-source Analytics Platform for gspeak) (L2)– Smart Microcontrollers - Embedded system for Sr L3) – Recent trends(L2).	r embedded systems					
Data Security	ation - Design Considerations: Control Unit, Sensing Requireme - System Architecture - Essential Components - Linux and Raspb implementation(L3)	nts, Communication, erry Pi (L2) - Design					
UNIT– III Energy Manag	SMART APPLIANCES AND ENERGY MANAGEMENT ement: Demand-side Load Management: Energy scheduling(L2) -	9 Significance of smart					
Energy Manag appliances ir Management(Smart Networ	ement: Demand-side Load Management: Energy scheduling(L2) – energy management(L2) - Embedded and Integrated Pla L2) - Smart Meters: Significance, Architecture & Energy Measurem ks for Embedded Appliances(L3) – Security Considerations(L3).	Significance of smart atforms for Energy nent Technique (L3) -					
Energy Manag appliances ir Management(Smart Networ UNIT – IV	ement: Demand-side Load Management: Energy scheduling(L2) – energy management(L2) - Embedded and Integrated Pla L2) - Smart Meters: Significance, Architecture & Energy Measurem ks for Embedded Appliances(L3) – Security Considerations(L3).	Significance of smart atforms for Energy nent Technique (L3) - 9					
Energy Manag appliances in Management(Smart Networ UNIT – IV Application of Selection of b suitable comr	ement: Demand-side Load Management: Energy scheduling(L2) – energy management(L2) - Embedded and Integrated Pla L2) - Smart Meters: Significance, Architecture & Energy Measurem ks for Embedded Appliances(L3) – Security Considerations(L3).	Significance of smart atforms for Energy tent Technique (L3) - 9 tional requirements- m(L2) - Selection of					
Energy Manag appliances in Management(Smart Networ UNIT – IV Application of Selection of b suitable comr	ement: Demand-side Load Management: Energy scheduling(L2) – energy management(L2) - Embedded and Integrated PL L2) - Smart Meters: Significance, Architecture & Energy Measurem ks for Embedded Appliances(L3) – Security Considerations(L3). SMART WEARABLE DEVICES Smart Wearables in Healthcare & Activity Monitoring (L2)- Func- ody sensors(L2), Hardware platform(L2), OS and Software platfor- nunication protocol(L3). Case Study: Design of a wearable, c	Significance of smart atforms for Energy tent Technique (L3) - 9 tional requirements- m(L2) - Selection of					
Energy Manag appliances in Management(Smart Networ UNIT – IV Application of Selection of b suitable comr temperature a UNIT–V Robots and Co	ement: Demand-side Load Management: Energy scheduling(L2) – energy management(L2) - Embedded and Integrated PL L2) - Smart Meters: Significance, Architecture & Energy Measurem ks for Embedded Appliances(L3) – Security Considerations(L3). SMART WEARABLE DEVICES Smart Wearables in Healthcare & Activity Monitoring (L2)- Func- ody sensors(L2), Hardware platform(L2), OS and Software platfor nunication protocol(L3). Case Study: Design of a wearable, of and monitoring health status using a smartphone application(L3). EMBEDDED SYSTEMS AND ROBOTICS	Significance of smart atforms for Energy nent Technique (L3) - 9 tional requirements- m(L2) – Selection of collecting heart-beat, 9					
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REF	ERENCE BOOKS:
1.	Thomas Bräunl, Embedded Robotics, Springer, 2003.
2.	Grimm, Christoph, Neumann, Peter, Mahlknech and Stefan, Embedded Systems for Smart Appliances and Energy Management, Springer 2013.
3.	Raj Kamal, Embedded Systems - Architecture, Programming and Design, McGraw- Hill, 2008
4.	NilanjanDey, Amartya Mukherjee, Embedded Systems and Robotics with Open-Source Tools, CRC press, 2016.
5.	Steven Goodwin, Smart Home Automation with Linux and Raspberry Pi, Apress, 2013
6.	Karim Yaghmour, Embedded Android, O'Reilly, 2013
7.	C.K.Toh, AdHoc mobile wireless networks, Prentice Hall, Inc, 2002. 50
8.	KazemSohraby, Daniel Minoli and TaiebZnati, Wireless Sensor Networks Technology, Protocols, and Applications, John Wiley & Sons, 2007.
9.	Anna Ha'c, Wireless Sensor Network Designs, John Wiley & Sons Ltd, 2003.
10.	Robert Faludi, Wireless Sensor Networks, O'Reilly, 2011.
WEE	REFERENCES:
1.	https://nptel.ac.in/courses/108105063
2.	https://medium.com/@muflorentine3/smart-sensors-and-actuators-3e5c0d37fde6
ONL	INE COURSES:
1.	https://onlinecourses.nptel.ac.in/noc21_me76/
2.	https://nptel.ac.in/courses/107106090
VID	EO REFERENCES:
1.	https://www.youtube.com/watch?v=xrwz9IxpMJg
2.	https://www.youtube.com/watch?v=j8vYClEnyk0

		Mapping	of COs with	POs		
со		1	P	0		
0	PO1	PO2	PO3	PO4	PO5	POG
CO1		3	2			
CO2	2		LTER .		2	
CO3			VAA.	2	3	
CO4		13	\$7.75	1 1		
CO5	1	Senund	CKm	Weiter		
Avg.	2	3	2	2	2.5	= 1
Depresenter (1-Low, 2	-Medium, 3-	High.		1

CHAIRPERSON Board of Studies Faculty of Electrical & Electronics Engg Knowledge Institute of Technology KIOT Campus, Kakapalayam, Salem-637 504

ME23ET	413	EMBEDDED COMPUTING	CP L T P C 3 3 0 0 3
Program &Branch	1	M.E. EMBEDDED SYSTEM TECHNOLOGIES	Version : 1.0
Course (Objecti	ves:	
1 To ex	pose tl	ne students to the fundamentals of Network communication te	chnologies.
2 To te	ach the	fundamentals of Java , Internet and Java card	<i>B</i> = 2
3 To de	evelop o	listributed embedded system with Java	
4 To te	ach the	smart card and Apps development	
		Discussions/ Practice in familiarizing the concepts acquired ov mproved employability skills.	er the 5 Units of th
UNIT-I		NETWORK INFRASTRUCTURE	9
Broad Ba Network	ind Tra diagrar	nsmission facilities(L2) -Open Interconnection standards(L2) n(L2) -Network management (L2)- Network Security(L3) - Cl	 networking device uster computers(L3)
UNIT-II	(L. 197	AVA TECHNOLOGY FOR EMBEDDED SYSTEMS	9
Threading	g – RM	of Java(L2) - IO streaming(L2) - Object serialization(L2) I (L2)- distributed databases(L2) Advantages and limitati e for embedded systems(L3) - security model for embedded s	ons of Internet (L2)
UNIT-I	11 :	SMART CARD TECHNIQUES	9
Smart Ca	rd Micr	cs(L2) – Java card technology overview(L2) – Java card Types(L ocontrollers(L2) - Contactless Cards(L2) - Smart Card Operating chniques(L3).	2) - Card component g Systems(L2)– sma
UNIT – I	v l		9
Android communi	cation(2) – Access to Hardware(L2) - Framework developme L2)-Android security design and architecture (L2)– Case study	nt(L2)- Peer-to-Pee (L3)
UNIT-V		DEVELOPING DISTRIBUTED REAL-TIME SYSTEM APPLICATIONS	9
		LAB Real-Time Targets(L2) - Using the xPC Target(L2) - Buildin ations(L3).	ng various Distribute
		. Brougenet Chanenberleye	Total : 45 Period
Course C		그는 것 같은 것 같	BLOOM'S
		on of this course the students will be able to: insight into involving JAVA concepts& internet based	Taxonomy
CO1 0		Insight the involving JAVA concepts internet pased	
		nication to establish decentralized control mechanism of	L2 - Understand
CO2 I	system nterpre	nication to establish decentralized control mechanism of t the software and hardware architecture for distributed	L2 - Understand L2 - Understand
	system nterpre comput	nication to establish decentralized control mechanism of t the software and hardware architecture for distributed	
CO2 I CO3 I	system nterpre comput Develop	nication to establish decentralized control mechanism of t the software and hardware architecture for distributed ng	L2 - Understand
CO2 I CO3 C CO4 C CO5 k	ystem nterpre comput Develop Develop mprove	nication to establish decentralized control mechanism of t the software and hardware architecture for distributed ng solution for smart card	L2 - Understand L3 – Apply L3 – Apply
CO2 I CO3 C CO4 C CO5 k	aystem nterpre comput Develop Develop mprove comput	nication to establish decentralized control mechanism of t the software and hardware architecture for distributed ng solution for smart card Apps based on android SDK. ed Employability and entrepreneurship capacity due to ge up gradation on recent trends in embedded system ng environment.	L2 - Understand L3 – Apply L3 – Apply
CO2 I CO3 C CO4 C CO5 K REFEREN	oystem nterpre comput Develop Develop mprove comput NCE BC Amitava	nication to establish decentralized control mechanism of t the software and hardware architecture for distributed ng solution for smart card Apps based on android SDK. d Employability and entrepreneurship capacity due to lge up gradation on recent trends in embedded system ng environment. OKS: Gupta , Anil Kumar Chandra and Peter Luksch " Real-Time ystems Theory and Applications " CRC, Press_2016_Internat	L2 - Understand L3 – Apply L3 – Apply L2 - Understand and Distributed Rea
CO2 I CO3 C CO4 C CO4 C CO5 k CO5 k CO5 C REFEREN	opstem nterpre comput Develop Develop mprove comput NCE BC Amitava Time S S Mumber Volfgar	nication to establish decentralized control mechanism of t the software and hardware architecture for distributed ng solution for smart card Apps based on android SDK. ed Employability and entrepreneurship capacity due to ge up gradation on recent trends in embedded system ng environment. OKS: Gupta , Anil Kumar Chandra and Peter Luksch " Real-Time ystems Theory and Applications " CRC Press 2016 Internat -13: 978-1-4665-9849-2 (eBook - PDF). g Rankl and Wolfgang Effing "Smart Card Handbook" John Wi	L2 - Understand L3 – Apply L3 – Apply L2 - Understand and Distributed Reational Standard Boo
CO2 I CO3 C CO4 C CO4 C CO5 k CO5 k CO5 C REFEREN	system nterpre comput Develop Develop mprove comput NCE BC Amitava Time S	nication to establish decentralized control mechanism of t the software and hardware architecture for distributed ng solution for smart card Apps based on android SDK. ed Employability and entrepreneurship capacity due to ge up gradation on recent trends in embedded system ng environment. OKS: Gupta , Anil Kumar Chandra and Peter Luksch " Real-Time ystems Theory and Applications " CRC Press 2016 Internat -13: 978-1-4665-9849-2 (eBook - PDF). g Rankl and Wolfgang Effing "Smart Card Handbook" John Wi	L2 - Understand L3 – Apply L3 – Apply L2 - Understand and Distributed Rea tional Standard Boo

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3.	Reto Meier "Professional Android application development" Wiley Publishing	, Inc , 2009
4.	Joshua " Android hacker's Handbook" John Wiley & sons , 2014	
5.	Dietel&Dietel, "JAVA how to program", Prentice Hall 1999.	1. A 1
6.	SapeMullender, "Distributed Systems", Addison-Wesley, 1993	
WEB F	REFERENCES:	
1.	https://archive.nptel.ac.in/courses/106/105/106105191/	
2.	https://archive.nptel.ac.in/courses/106/106/106106156/	E.
ONLIN	NE COURSES:	
1.	https://onlinecourses.swayam2.ac.in/nou21_ge41/	2
2.	https://onlinecourses.nptel.ac.in/noc22_cs47/	
VIDEC	REFERENCES:	
1.	https://www.youtube.com/watch?v=-foyVzTOf8o&list=PLJ5C 6qdAvBEJ6-	•
±.,	TBzKoa10v21lwDzJfM	
2.	https://www.youtube.com/watch?v=OjdT2I-	
2.	EZJA&list=PLfn3cNtmZdPOe3R_wO_h540QNfMkCQ0ho	

				with POs PO		
со	PO1	PO2	PO3	PO4	PO5	PO6
CO1	2		1	->>	2	2
CO2	2	3	2		-	-
CO3	3	×1/	2	3	2	3
CO4	3	1	2	3	2	3
CO5	2	1	2			3
Avg.	2.4	1.5	1.8	3	2	2.25

🔹 1–Low, 2 –Medium, 3–High. 🥿

SALEN

Beyond Knowledge



CHAIRPERSON Board of Studies Faculty of Electrical & Electronics Engg Knowledge Institute of Technology KIOT Campus, Kakapalayam, Salem-637 504

	23ET414		EMBEDDED SY	STEMS SECURITY	CP L T P C 3 3 0 0 3
	gramme nch	&	M.E. EMBEDDED SY	STEM TECHNOLOGIES	Version: 1.0
	rse Object	tives			1
1	To introdu	ce th	fundamentals related to (Cryptography and Data Secur	ity.
2	To teach th	he m	thematical foundations for	Cryptography.	
3	To impart	know	edge about Embedded Cry	ptography and Data Protection	on Protocols.
4	To make th	hem	inderstand the practical as	pects of Embedded System S	ecurity.
5			students in Discussions/Tu yability skills.	utorials/Programming to fam	liarize the concepts fo
บทา	(T–I		BACKGROUND AND INT	RODUCTION	9
Vetv Eucl Test	work Secur lidean Algor ting for Prin	rity. 1 rithm nality	ntroduction to Number Th – Modular Arithmetic – Pr	– Attack Surfaces and Attack neory: Divisibility and the D ime Numbers – Fermet's and nder Theorem – Discrete Loga	vision Algorithm – The Euler's Theorems (L2)
	T-II	0.175		pher Model – Substitution Tec	the second se
I CU). DIU	K Ciphers and the Data End		
Stru Enci AES	ryption Star Key Expan	e Dat ndaro ision	: Finite Field Arithmetic - - An AES Example - AES I) – A DES Example – Strengt AES Structure – AES Transfo mplementation(L3).	rmation Functions(L2)
Stru Enci AES	ryption Star Key Expan	e Dat ndarc ision	a Encryption Standard (L2) : Finite Field Arithmetic – - An AES Example – AES In MBEDDED SYSTEMS SEC) – A DES Example – Strengt AES Structure – AES Transfo mplementation(L3). CURITY	rmation Functions(L2) -
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Stru Enco AES UNJ Emb Com Emb Syst the UNJ The Enco Ellip Ran Cert Data Auto Netv Seco Prot Haro	Inclure – The ryption Star Key Expan IT– III Dedded Sec siderations: Dedded OS tem Virtuali TCB(L3). IT – IV One-time ryption(L2) Dic Curve (dom Numb cifications(L a-at-Rest) Dic Curve (dom Numb cifications(L a	e Dat ndaro nsion E curity : The Secu izatio E Proto curity Proto curity F nunice t La osing ed See mes :	A Encryption Standard (L2) Finite Field Arithmetic – An AES Example – AES In MBEDDED SYSTEMS SEC Trends(L2) – Security Role of Operating Syste ity Requirements (L2) – Ac (L2) – I/O Virtualization (MBEDDED CRYPTOGRAP ROTOCOLS (L2) – Cryptographic M obic Key Cryptography(L2) ography – Cryptographic meration(L2) – Key Manag ata Protection Protocols for cols(L2). Emerging Appl (L3) – Secured Android(L3) RACTICAL EMBEDDED S tions Protocols and Built- fer – Embedded Security and Optimizing Cryptography	 A DES Example – Strengt AES Structure – AES Transfo mplementation(L3). CURITY Policies – Security Threats em(L2) – Microkernel versus ccess Control and Capabilities L2) – Remote Management (L2) CHY AND DATA PROTECTIO Modes(L2) – Block Ciphers – Key Agreement – Public K Hashes(L2) – Message Auth gement for Embedded System for Embedded Systems: Dat ications: Embedded Netwo). YSTEM SECURITY in Security – Security Protoco – Wireless – Application-Lohic Algorithms for Resource - 	9 (L2). System Softward Monolithic (L2) – Cord Son (L2) – Hypervisors and 2) – Assuring Integrity of (L2) – Authentication (L2) – Son (L2) – Son (L2) – Cryptographica-in-Motion Protocols – ms(L3) –
Stru Enco AES UNJ Emb Com Emb Syst the UNJ The Enco Ellip Ran Cert Data Auto Netv Seco Prot Haro	intervention Star Key Expan IT – III bedded Sec siderations: bedded OS tem Virtuali TCB(L3). IT – IV One-time ryption(L2) btic Curve O dom Numb ifications(L a-at-Rest D bifications(L a-at-Rest D omotive Sec IT – V work Communed Socker ocols– Choo dward Base IT se Outcom	e Dat ndaro nsion E curity : The Secu izatio E Proto curity Proto curity F nunic et La osing ed Sec messi	A Encryption Standard (L2) Finite Field Arithmetic – An AES Example – AES In MBEDDED SYSTEMS SEC Trends(L2) – Security Role of Operating Syste ity Requirements (L2) – Ac n(L2) – I/O Virtualization (I MBEDDED CRYPTOGRAP ROTOCOLS (L2) – Cryptographic Molic Key Cryptography(L2) Ography – Cryptographic Ineration(L2) – Key Managata Protection Protocols for cols(L2). Emerging Appl (L3) – Secured Android(L3 RACTICAL EMBEDDED S nitions Protocols and Built- yer – Embedded Security and Optimizing Cryptograp urity(L3).	 A DES Example – Strengt AES Structure – AES Transfo mplementation(L3). CURITY Policies – Security Threats em(L2) – Microkernel versus ccess Control and Capabilities L2) – Remote Management (L2) CHY AND DATA PROTECTIO Modes(L2) – Block Ciphers – Key Agreement – Public K Hashes(L2) – Message Auth gement for Embedded System for Embedded Systems: Dat ications: Embedded Netwo). YSTEM SECURITY in Security – Security Protoco – Wireless – Application-Lohic Algorithms for Resource - 	9 (L2). System Softward Monolithic (L2) – Cords (L2) – Hypervisors and 2) – Assuring Integrity of N 9 S(L2) – Hypervisors and 2) – Assuring Integrity of N 9 S(L2) – Authenticated ey Authentication (L2) – entication Codes(L2) – ms(L3) – Cryptographila-in-Motion Protocols – ms(L3) – Cryptographila-in-Motion Protocols – rk Transactions • (L2) – 9 0 9 olls and Algorithm– The ayer and Client/Serve Constrained Systems – Total : 45 Periods BLOOM'S

19

Salem-637.524.Tech. Regulations-2023

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соз	Demonstrate thorough knowledge about the aspects of Embedded System Security.	L2 - Understand
CO4	Delivers insight onto role of Security Aspects during Data Transfer and Communication.	L2 - Understand
C05	Applying the Security Algorithms for Real-time Applications.	L3 - Apply
REFE	RENCE BOOKS:	
1.	"Cryptography and Network Security Principles and Practice", 7th Edi William Stallings, Pearson Education Limited, 2017.	
2.	Embedded Systems Security - Practical Methods for Safe and Secure S Development", David Kleidermacher and Mike Kleidermacher, Newnes (a 2012	
3.	"Practical Embedded Security - Building Secure Resource-Constraine Stapko, Newnes (an imprint of Elsevier), 2008.	d Systems", Timothy
WEB	REFERENCES:	0
1.	https://www.geeksforgeeks.org/cryptography-and-network-security-pr	inciples/
2.	https://blackberry.qnx.com/en/ultimate-guides/embedded-system-secu	urity
ONL	INE COURSES:	
1.	https://onlinecourses.nptel.ac.in/noc22_cs90/	
2.	https://nptel.ac.in/courses/106106199	
VIDE	O REFERENCES:	
1.	https://www.youtube.com/watch?v=1plMO7ChXMU&list=PLJ5C_6qdAv 2gYtev	BFAuGoLC2wFGruY E
2.	https://www.youtube.com/watch?v=-dNsW2AOGYY&list=PLyqSpQzTE6 q0Xgn0icEHvUS7WQxvenv	<u>M-</u>

Mapping of COs with POs										
~~			と と 熱に 本	PO		3				
со	P01	PO2	PO3	PO4	PO5	P06				
CO1	1	1		1	1					
CO2	3	2	2							
CO3	1	3	SPLET	1						
CO4	3	1	2	3	1					
CO5	3	2	3	2	3					
Avg.	2.2	//1.8	/2.33 //	1.33	2.33					
		- 6 212 1 2 f - 1	ow, 2 –Medium		(([,] =====					

CHAIRPERSON Board of Studies Faculty of Electrical & Electronics Engg Knowledge Institute of Technology KIOT Campus, Kakapalayam, Salem-637 504

M.E./M.Tech. Regulations-2023

ME23E	T415	ROBOTICS AND AUTOMATION	CP 3	3 0	0 3				
Progra &Brand		M.E. EMBEDDED SYSTEM TECHNOLOGIES		Version	: 1.0				
Course		ctives:							
1 To t	each t	he need of embedded system technology for robot building.	L						
		he Various Parts of Robots and Fields of Robotics.							
3 To study t		he Various Kinematics and Inverse Kinematics of Robots.	2	520					
4 To study t		he Trajectory Planning for Robot.	rajectory Planning for Robot.						
- 199		he Control of Robots for Some Specific Applications.	5. 5.						
UNIT-I		INTRODUCTION TO ROBOTICS & AUTOMATION		9					
Types of compor in Robo	of Robo nents o otics an	d software for Automation(L2)- Embedded Processors for Autots(L2) – Various Generations of Robots(L2) - Asimov's Laws (f a robot(L2) - Design Criteria for Selection of a Robot (L3)- Role d Automation (L2)- Recent trends(L3).	Of Ro	obotics(L embedde	2) – Ke				
		SENSORS AND DRIVE SYSTEMS		9					
Displac sensors	ement s(L3).	tical, Acoustic, Magnetic)- Proximity Sensors – Ranging Ser Sensing(L2) - Tactile Sensors(L2) – Vision Sensing (L2) - Smar MANIPULATORS AND GRIPPERS	nsors	s(L2) –	Speed				
Displace sensors UNIT – Introdu (L2)– M	ement s(L3). III ction to lanipul	Sensing(L2) - Tactile Sensors(L2) – Vision Sensing (L2) - Smar MANIPULATORS AND GRIPPERS o Manipulators (L2)- Joints and Degrees of Freedom (L2)- Constr ator Dynamics and Force Control (L2) – Electronic And Pneumat	ructic	s(L2) – nsors(L2 9 on of Mar anipulato	Speed) - MEM nipulator				
Displace sensors UNIT– Introdu (L2)– M Circuits	ement (L3). III ction to lanipul (L2) –	Sensing(L2) - Tactile Sensors(L2) – Vision Sensing (L2) - Smar MANIPULATORS AND GRIPPERS Manipulators (L2)- Joints and Degrees of Freedom (L2)- Constr	ructic	s(L2) – nsors(L2 9 on of Mar anipulato	Speed) - MEM nipulator				
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KIOT

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NIOT Campus/ Kakap Revailions-2023 Salem-637 504

C04	Develop Program to Use a Robot for a Typical Application	L2 - Understand
C05	Apply and improve Employability and entrepreneurship capacity due to knowledge upgradation on Embedded system based robot development	L3 - Apply
REFER	ENCE BOOKS:	
1.	Mikell P. Weiss G.M., Nagel R.N., Odraj N.G., "Industrial Robotics", Mc 1996.	Graw-Hill Singapore
2.	Ghosh, Control in Robotics and Automation: Sensor Based Integration Chennai, 1998	
3.	Deb. S.R.,"Robotics Technology And Flexible Automation", John Wiley,	USA 1992
4.	Klafter R.D., Chimielewski T.A., Negin M., "Robotic Engineering – An I Prentice Hall of India, New Delhi, 1994	
5.	Mc Kerrow P.J. "Introduction to Robotics", Addison Wesley, USA, 1991	•
6.	Issac Asimov "Robot", Ballantine Books, New York, 1986.	
7.	Barry Leatham – Jones, "Elements of Industrial Robotics" PITMAN Pub	lishing, 1987
8.	MikellP.Groover, Mitchell Weiss, Roger N.Nagel Nicholas G.Odrey, Technology, Programming And Applications ", McGraw Hill Book Comp	
9.	Fu K.S. Gonzaleaz R.C. And Lee C.S.G., "Robotics Control Sensing, Vis McGraw Hill International Editions, 1987	sion and Intelligence
WEB R	REFERENCES:	
1.	https://nptel.ac.in/courses/112101098	
1. 2.	https://nptel.ac.in/courses/112101098 https://archive.nptel.ac.in/courses/112/105/112105249/	
2.	A Contract grander contract and a Contra	
2.	https://archive.nptel.ac.in/courses/112/105/112105249/	7
2. ONLIN	https://archive.nptel.ac.in/courses/112/105/112105249/	3. II 15
2. ONLIN 1. 2.	https://archive.nptel.ac.in/courses/112/105/112105249/ IE COURSES: https://nptel.ac.in/courses/112101098	3
2. ONLIN 1. 2.	https://archive.nptel.ac.in/courses/112/105/112105249/ IE COURSES: https://nptel.ac.in/courses/112101098 https://onlinecourses.nptel.ac.in/noc21_me76/	ngdCkMipemSKP_dC

Mapping of COs with POs										
CO			I and the second s	20	- Lo-25 HUL	Tr. I				
co	PO1	// PO2	/ PO3	PO4/	PO5	POG				
CO1	1	2		3 /						
CO2		3								
CO3				-						
CO4				2	3	1				
CO5			2	1		3				
Avg.	1	2.5	2	2	3	2				

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4025

ME2	23ET416	RECONFIGURABLE PROCESSOR AND SoC DESIGN	CP L T P C 3 3 0 0 3
1	gramme ranch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	Version : 1.0
Cou	rse Object		
1		ize the need and role of Reconfigurable Processor for embedded syste	em applications
2		ce the Reconfigurable Processor technologies	
3		ne salient features and architecture of FPGA	
4		an insight and architecture significance of SoC.	
5	To impart	the knowledge of Reconfigurable embedded Processor for real time ap	plications.
UNI		INTRODUCTION	9
Prog	ramming T	reconfigurable processor(L2)- Reconfigurable Computing-Programm ools for Reconfigurable Processors, ASIC design flow(L2)- Hardware/ ure overview- recent trends in Reconfigurable Processor & SoC(L3).	ning elements and Software Co-design
UNI	T-II	FPGA TECHNOLOGIES	9
- CL	B Vs LAB V	ning technology (L2)- Alternative FPGA architectures: MUX Vs LUT bas s Slices(L2)- Fast carry chains(L2)- Embedded RAMs- Routing for FPG or Low(L3)-Power FPGAs- Physical Design(L3).	sed logic blocks(L2) As(L2)- Circuits and
UNI	T- III	FPGA ARCHITECTURE	9
proc harc	essor desi ware/softw	ure overview-(L2) Challenges of FPGA processor design(L2)-Opp gn(L2) - Designing SoftCore Processors(L2) – Designing Hardcore vare co-simulation(L2)- FPGA to multi core embedded computing(L3 r system(L3).	Processors(L2) -
UNI	T – IV	RECONFIGURABLE SOC PROCESSORS	9
		L2)-Architecture and applications of Virtex II pro, Zynq-7000, Excalit - Multicore SoCs(L3).	our, Cyclone V - A7,
UNI	T-V	RECONFIGURABLE PROCESSOR AND SOC APPLICATIONS	9
deve	elopment l	processor(L2) - based DC motor control- digital filter design(L2 High Speed Data Acquisition(L2) - Image Processing application for mobile robot- Crypto-processor(L3).	2) - mobile phone n(L3) - controller
			Total : 45 Periods
	rse Outco		BLOOM'S Taxonomy
CO1	Illustrat	ion of this course the students will be able to: e the need of reconfigurable computing and hardware-software co	L2-Understand
C02		trate the significance of FPGA technology	L2-Understand
соз	Apply th	e concept of FPGA technology and understand FPGA architectures	L2-Understand
C04		t the operation of SoC processor.	L2-Understand
CO5	Relate a	and improve Employability and entrepreneurship capacity due to ge up-gradation on reconfigurable computing and SoC design.	L3 - Apply
REF	ERENCE B	OOKS:	
1	2007.	ari (Ed.) "Processor Design System-On-Chip Computing for ASICs an	20 - 20 M
2	. Hübner, 2011.	it, "Digital system design with FPGAs and CPLDs" Elsevier, 2008 Joa "Reconfigurable Computing: From FPGAs to Hardware/Software C	Codesign" Springer,
3	' Practices	s and AnderewG.Schmidt, " Embedded System design with platform FF 5", Elsevier, 2010.	
4	2007	ilts, "Advanced FPGA Design: Architecture, Implementation, and Q	
5		mmanuel Gaillardon, Reconfigurable Logic: Architec GHAIROUS Son CRC Press, 2015 Faculty of Electrical & Electric	
		Knowledge Institute of Te	chnology
	KIOT		tars=2023

WEB	REFERENCES:
1.	https://www.electronicdesign.com/technologies/embedded/digital- ics/processors/dsp/article/21753427/reconfigurable-socs
2.	https://ieeexplore.ieee.org/document/6926215
ONL	INE COURSES:
1.	https://www.coursera.org/learn/copy-of-fpga-intro
2.	https://nptel.ac.in/courses/117108040
VID	EO REFERENCES:
1.	https://www.youtube.com/watch?v=ht7nEjNydDU&t=3s
2.	https://www.youtube.com/watch?v=PRQXzjTrCJY

		Mapping	of COs with	POS			
~~			PO		-14		
со	PO1	PO2	PO3	PO4	PO5	POG	
CO1		b. Ale					
CO2		2	3.				
CO3		C CAN	2	1	2		
CO4		1	3				
CO5				W.		3	
Avg.	0	1.5	2.66		2	3	



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	3ET417	MEMS AND NEMS TECHNOLOGY	3 3 0 0 3		
the second se	ramme anch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	Version: 1.0		
Cour	se Objec		MEMC/NEMC an		
1	application		MEMS/NEMS and		
2	To under	stand the microstructures and fabrication methods			
3	To provid	de an insight of micro and nano sensors, actuators.			
4	To emph	To emphasis the need for NEMS techology			
5	To updat	e the ongoing trends and real time applications of MEMS and NEMS	s technology.		
UNI	r–ı	INTRODUCTION TO MEMS and NEMS	9		
techr	view of M nologies(L NEMS (L3)		tems, devices an plications of MEM		
To an age state	T-II	MICRO-MACHINING AND MICROFABRICATION TECHNIQUES	9		
Photo mach	olithograp nining, sili	hy(L2)- Film deposition, Etching Processes(L2)- wafer bonding con surface micro machining(L2)- LIGA process(L3).	(L2)- Bulk micr		
	T– III	MICRO SENSORS AND MICRO ACTUATORS	9		
Tran: piezo	sduction r	nechanisms in different energy domain(L2)- Micromachined capacit and Electromechanical and thermal sensors/actuators and application	ive, Piezoelectric ons(L3)		
UNI	T – IV	NEMS TECHNOLOGY	9		
		recision engineering(L2)- Nano Fabrication techniques (L2)- NEMS tion and systems design(L3).	in measurement		
UNI	т-v	MEMS and NEMS APPLICATION	9		
Intro	duction to ors(L2)- Re	o Micro/Nano Fluids and applications- Bio MEMS- Optical NEMS-	- Micro and Nan		
		SALEN			
	se Outco	mes:	BLOOM'S		
Upo	n comple	mes: tion of this course the students will be able to:	BLOOM'S Taxonomy		
Upo	n comple Explain for indu	mes: tion of this course the students will be able to: the material properties and the significance of MEMS and NEMS ustrial automation.	BLOOM'S Taxonomy		
Upo CO1	n comple Explain	tion of this course the students will be able to: the material properties and the significance of MEMS and NEMS ustrial automation. strate knowledge delivery on micromachining and micro	BLOOM'S Taxonomy L2 - Understand		
Upo CO1 CO2	n comple Explain for indu Demon fabricat	tion of this course the students will be able to: the material properties and the significance of MEMS and NEMS ustrial automation. strate knowledge delivery on micromachining and micro	BLOOM'S Taxonomy L2 - Understand L2 - Understand		
Upor CO1 CO2 CO3	n comple Explain for indu Demon fabricat Apply t Apply t	tion of this course the students will be able to: the material properties and the significance of MEMS and NEMS ustrial automation. strate knowledge delivery on micromachining and micro			
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Upo CO1 CO2 CO3 CO4 CO5	n comple Explain for indu Demon fabricat Apply t Apply t the sen Improv	tion of this course the students will be able to: the material properties and the significance of MEMS and NEMS istrial automation. strate knowledge delivery on micromachining and micro tion. the fabrication mechanism for MEMS sensor and actuators the concepts of MEMS and NEMS to models ,simulate and process sors and actuators. ed Employability and entrepreneurship capacity due to knowledge lation on MEMS and NEMS technology.	BLOOM'S Taxonomy L2 - Understand L2 - Understand L2 - Understand L2 - Understand		
Upo CO1 CO2 CO3 CO4 CO5	Apply t Apply t Improv up grace Chang	tion of this course the students will be able to: the material properties and the significance of MEMS and NEMS istrial automation. strate knowledge delivery on micromachining and micro ion. the fabrication mechanism for MEMS sensor and actuators the concepts of MEMS and NEMS to models ,simulate and process sors and actuators. ed Employability and entrepreneurship capacity due to knowledge lation on MEMS and NEMS technology. BOOKS: Liu, "Foundations of MEMS", Pearson International Edition, 2006.	BLOOM'S Taxonomy L2 - Understand L2 - Understand L2 - Understand L2 - Understand L2 - Understand		
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Upor CO1 CO2 CO3 CO4 CO5 REFI 1. 2. 3.	Apply t Apply t Apply t Apply t Apply t the sen Improv up grac ERENCE E Chang Marc F M.H.Ba gyroscc Maluf, house, Moham	tion of this course the students will be able to: the material properties and the significance of MEMS and NEMS Istrial automation. strate knowledge delivery on micromachining and micro tion. he fabrication mechanism for MEMS sensor and actuators he concepts of MEMS and NEMS to models ,simulate and process sors and actuators. ed Employability and entrepreneurship capacity due to knowledge dation on MEMS and NEMS technology. BOOKS: Liu, "Foundations of MEMS", Pearson International Edition, 2006. madou" Fundamentals of micro fabrication" CRC Press 2002 2nd Eco o "Micromechanical transducers :Pressure sensors, acco opes",Elsevier, Newyork, 2000 Nadim "An introduction to Micro Electro-mechanical Systems Eng Boston 2000. ed Gad - el - Hak "MEMS Handbook" Edited CRC Press 2002	BLOOM'S Taxonomy L2 - Understand L2 - Understand L2 - Understand L2 - Understand L2 - Understand L2 - Understand L2 - Understand ition Marc Madou elerometers an ineering "AR Tec		
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7.	Lyshevski, S.E. " Nano- and Micro-Electromechanical Systems: Fundamentals of Nano-and Microengineering " (2nd ed.). CRC Press, 2005.
WEE	REFERENCES:
1.	https://link.springer.com/referenceworkentry/10.1007/978-0-387-30877-7_9
2.	https://mechheart.com/difference-between-mems-and-nems-devices/
ONL	INE COURSES:
1.	https://archive.nptel.ac.in/courses/108/108/108108113/
2.	https://nptel.ac.in/courses/117105082
VID	EO REFERENCES:
٦.	https://www.youtube.com/watch?v=j9y0gfN9WMg
2.	https://www.youtube.com/watch?v=Ak7Y-vIWbnA&t=1s

~			PO			
со	PO1	PO2	PO3	PO4	PO5	POG
CO1	3	2	3		2	
CO2	3	-3	2	Silicity	2	
CO3	3	3	3	3		
CO4	3	3	3 👘		3	
CO5	3	2	3	2	3	
Avg.	3.2	6	2.8	2	2.4	

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Begend Knowledge

CHAIRPERSON

Board of Studies Faculty of Electrical & Electronics Engg Knowledge Institute of Technology KIOT Campus, Kakapalayam, Salem+637 504

ME2	23ET418	ENTREPRENEURSHIP AND EMBEDDED PRODUCT DEVELOPMENT	CP L T P C 3 3 0 0 3		
Pro	gramme &	M.E. EMBEDDED SYSTEM TECHNOLOGIES	Version : 1.0		
	rse Objectiv	es:			
1	To develop a	n understanding on business promotion process.			
2	To expose stu	idents on the skills required for success in business.			
3	To impart em	ecture			
4	Creative thin	arket value			
5	Developing a				
UNI	т–1	INTRODUCTION TO ENTREPRENEURSHIP	9		
moti rewa entr	vation (L2)- ards and me epreneurship(ation and intelligence Fairs- challenges i		
	T-II	RESPONSIBILITIES IN ENTREPRENEURSHIP a small industry -selection of type of organization(L2) -Ind	9		
(L2) and poss Entr	- Central Gov Licensing re ibilities(L2)-	c. schemes and State Govt. Schemes -incentives to SSI -reg equirements for sales tax, CST, Excise Duty -Power incentives for exports (L2) - import of capital goods ar development programmes in India(L2) - Role and Im	gistration, Registratio (L2)-Exploring expon nd raw materials(L2)		
UNI	T- III	CONCEPTS OF PRODUCT DEVELOPMENT	9		
Cono desig	cept Generatio gn concepts-	Development Phases(L2)- Product Development Process on(L2)-Five Step Method(L2)- Creative thinking methods and Product Architecture-(L2) component standardization(L2) ent management(L2)- Portfolio Architecture- Benchmarking	d problem solving(L2) –Bill of materials(L2)		
UNI	T – IV	APPROACHES FOR NEW PRODUCT DEVELOPMENT	9		
Cond PERT Prote	cept Develop (L2)- Revers otype basics	 2)- Industrial Design(L2) -Brainstorming Methods(L2) - nent & Testing(L2)- Risk Management Process(L2)- Cri e Engineering Methodology(L2)- need for Involving CAE, (L2)- Rapid Prototyping(L2) - Prototyping Techniques conomic & Cost Analysis(L3) 	tical Path Analysis 8 CAD, CAM tools(L2)		
UNI	T-V	SCOPE IN EMBEDDED SYSTEM FIELD			
deve softv syste Wasl	elopment (L2) vare and harc em field(L2)- hing machine	opportunities in Embedded system technologies (L2)- Embe Entrepreneurial skills for embedded system hardware and ware co-design and challenges(L2); problems of entreprer case studies(L3): Mobile phone development(L2)- automa - Food Processing system and devices (L2)- High Pe dustrial Controllers(L3)	software architecture neurship in Embeddeo tion components(L2)		
			Total : 45 Period		
		of this course the students will be able to:	BLOOM'S Taxonomy		
201		internal/external factors affecting a business/organization business opportunities.			
02	Demonstrat	e extemporaneous speaking skills developed through in- sion of text materials, case study analyses, and current irship-related issues.	L2 - Understand		
anas Ogaži -	agarst, jeuen XCS TLA-mens	Board	PERSON of Studies		
	кіот	27 Board of Electrica 27 Knowledgeenst KIOT Campus	of Studies		

соз	Apply and Relate Key concepts underpinning entrepreneurship and its application in the recognition and exploitation of product/ service/ L2 - Understand process opportunities							
CO4	,economic analysis through							
C05	Improved Employability and entrepreneurship capacity due to knowledge up gradation on recent trends in embedded systems design.							
REFE	RENCE BOOKS:							
1.	Kuratko, Entrepreneurship: A Contemporary Approach, Thomson Learn							
2.	Thomas Zimmerer et.al., Essentials of Entrepreneurship and small busi Ed. Pearson Education, 2002							
3.	Greene, Entrepreneurship: Ideas in Action, Thomson Learning, Mumbai	, 2000						
4.	Jeffry Timmons, New Ventrure creation, McGraw Hill, 1999.	8						
5.	James K.peckol ," Embedded Systems: A contemporary Design Tool", V	Participant and a second se						
6.	Anita Goyal, Karl T Ulrich, Steven D Eppinger, "Product Design and Edition, 2009, Tata McGraw-Hill Education, ISBN-10-007-14679-9							
7.	George E.Dieter, Linda C.Schmidt, "Engineering Design", McGraw-Hill In Edition, 2009, ISBN 978-007-127189-9							
8.	Gupta and Smivasan, Entrepreneurial Development, New Delhi, Sultan	Chand, 1992						
WEB	REFERENCES:							
1.	https://archive.nptel.ac.in/courses/112/107/112107217/							
2.	https://www.techtarget.com/searchcio/definition/product-development development-NPD	t-or-new-product-						
ONLI	INE COURSES:							
1.	https://onlinecourses.nptel.ac.in/noc21_mg70/							
2.	https://onlinecourses.nptel.ac.in/noc21_me83/							
VIDE	O REFERENCES:							
1.	https://www.youtube.com/watch?v=Tzzfd6168jk&list=PLyqSpQzTE6M GkdbB1R	8EGZbmNUuUM7Vh2						
2.	https://www.youtube.com/watch?v=Hgj_kRrvbhQ&list=PL7oBzLzHZ1v	vXW3mtolxV5nIGn48						

2. NLKwrb

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Mapping of COs with POs										
	4	Som and	CK PO	whether						
со	PO1	PO2	PO3	PO4	P05	POE				
CO1	3	2								
CO2	3	3								
CO3	3	3			10 ¹⁰	•				
CO4	3	3		1						
CO5	3	2	3	2	3					
Avg.	3.2	6	3	1.5	3	-				

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	23ET419							
	gramme 8 nch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	Version : 1.0					
	irse Objecti	ves:						
1	To Introduce	e Fundamentals of Biomedical Engineering						
2	To understa	nd the concept of wearable health devices						
3	To study the hardware for image processing applications							
4	To have a b	asic knowledge of Embedded system in diagnostic applications	in co					
5	To study ab	out the various assist devices used in the hospitals.						
UNI	IT-I	INTRODUCTION TO BIOMEDICAL ENGINEERING	9					
char	racteristics a	ptential and its propagation(L1)- Resting and Action Potenti and Types of electrodes (L1)- Types of transducers and types of recorders components of a biomedical system(L3)						
UNJ	IT-II	WEARABLE HEALTH DEVICES	9					
Bios	ensors (L2)- diac pacemal	arable technology in health care (L2)-Components of wea Blood glucose sensors (L2) - Head worn- Hand worn- Body w kers (L2)- Hearing aids and its recent advancements(L3)-wea	orn-pulse oxymete					
UNI	III – III	III EMBEDDED SYSTEM FOR MEDICAL IMAGE						
Intro	oduction to e	mbedded image processing (L1). ASIC vs FPGA (L2) - memory	requirement-, powe					
cons (L2) com	sumption- pa - interfacin pression (L3	rallelism(L2) - Design issues in VLSI implementation of Image p g. Hardware implementation of image processing algorithms)	processing algorithm : Segmentation an					
cons (L2) com UNI	sumption- pa) - interfacin pression (L3 I T – IV	rallelism(L2) - Design issues in VLSI implementation of Image p g. Hardware implementation of image processing algorithms) EMBEDDED SYSTEM FOR DIAGNOSTIC APPLICATIONS	processing algorithm : Segmentation an 9					
cons (L2) com UNI	sumption- pa) - interfacin pression (L3 I T – IV	rallelism(L2) - Design issues in VLSI implementation of Image p g. Hardware implementation of image processing algorithms EMBEDDED SYSTEM FOR DIAGNOSTIC APPLICATIONS nitoring system (L2)- ECG-EEG-EMG acquisition system(L2)-N	processing algorithm : Segmentation an 9					
cons (L2) com UNI ICCl scan	sumption- pa - interfacin pression (L3 IT – IV U patient mo	rallelism(L2) - Design issues in VLSI implementation of Image p g. Hardware implementation of image processing algorithms EMBEDDED SYSTEM FOR DIAGNOSTIC APPLICATIONS nitoring system (L2)- ECG-EEG-EMG acquisition system(L2)-N	processing algorithm : Segmentation an 9					
cons (L2) com UNI ICCU scan UNI Resp	sumption- pa pression (L3 T – IV U patient mo nner(L2) Son T–V piratory mea	rallelism(L2) - Design issues in VLSI implementation of Image p g. Hardware implementation of image processing algorithms EMBEDDED SYSTEM FOR DIAGNOSTIC APPLICATIONS nitoring system (L2) - ECG-EEG-EMG acquisition system(L2) - No ography(L2) CASE STUDY surement using spirometer- IPPB unit for monitoring respirator	Processing algorithm Segmentation an 9 ARI scanner (L2)- C 9					
cons (L2) com UNI ICCU scan UNI Resp	sumption- pa pression (L3 T – IV U patient mo nner(L2) Son T–V piratory mea	rallelism(L2) - Design issues in VLSI implementation of Image p g. Hardware implementation of image processing algorithms EMBEDDED SYSTEM FOR DIAGNOSTIC APPLICATIONS nitoring system (L2) - ECG-EEG-EMG acquisition system(L2)-N ography(L2) CASE STUDY	Processing algorithm Segmentation an 9 ARI scanner (L2)- C 9					
cons (L2) com UNI ICCU scan UNI Resp vent	sumption- pa pression (L3 IT – IV U patient mo nner(L2) Son IT–V piratory mea tilators(L4) -	rallelism(L2) - Design issues in VLSI implementation of Image p g. Hardware implementation of image processing algorithms EMBEDDED SYSTEM FOR DIAGNOSTIC APPLICATIONS nitoring system (L2) - ECG-EEG-EMG acquisition system(L2)-Nography(L2) CASE STUDY surement using spirometer- IPPB unit for monitoring respirated Defibrillator(L4) - Glucometer(L4)-Heart- Lung machine(L4)	Processing algorithm Segmentation an 9 ARI scanner (L2)- C 9 Pry parameters(L4) Total : 45 Period BLOOM'S					
cons (L2) com UNI ICCU Scan UNI Resp vent	sumption- pa pression (L3 IT – IV U patient mo nner(L2) Son IT–V piratory mea tilators(L4) -	rallelism(L2) - Design issues in VLSI implementation of Image p g. Hardware implementation of image processing algorithms EMBEDDED SYSTEM FOR DIAGNOSTIC APPLICATIONS nitoring system (L2) - ECG-EEG-EMG acquisition system(L2)-N ography(L2) CASE STUDY surement using spirometer- IPPB unit for monitoring respirate Defibrillator(L4) - Glucometer(L4)-Heart- Lung machine(L4)	Processing algorithm Segmentation an 9 ARI scanner (L2)- C 9 Pry parameters(L4) Total : 45 Period					
cons (L2) com UNI ICCU scan UNI Resp vent Cou Upo CO1	sumption- pa pression (L3 T – IV U patient mo nner(L2) Son T–V piratory mea tilators(L4) - se Outcom Demonstr	rallelism(L2) - Design issues in VLSI implementation of Image p g. Hardware implementation of image processing algorithms EMBEDDED SYSTEM FOR DIAGNOSTIC APPLICATIONS nitoring system (L2) - ECG-EEG-EMG acquisition system(L2)-Nography(L2) CASE STUDY surement using spirometer- IPPB unit for monitoring respirated Defibrillator(L4) - Glucometer(L4)-Heart- Lung machine(L4) mes: on of this course the students will be able to:	Processing algorithm Segmentation an 9 ARI scanner (L2)- C 9 Dry parameters(L4) Total : 45 Period BLOOM'S Taxonomy					
cons (L2) com UNI ICCU scan UNI Resp vent	sumption- pa pression (L3 IT – IV U patient mo nner(L2) Son IT–V piratory mea tilators(L4) -I rse Outcom Demonstrate Illustrate	rallelism(L2) - Design issues in VLSI implementation of Image p g. Hardware implementation of image processing algorithms EMBEDDED SYSTEM FOR DIAGNOSTIC APPLICATIONS nitoring system (L2) - ECG-EEG-EMG acquisition system(L2)-Nography(L2) CASE STUDY surement using spirometer- IPPB unit for monitoring respirate Defibrillator(L4) - Glucometer(L4)-Heart- Lung machine(L4) res: on of this course the students will be able to: ate the fundamental art of biomedical engineering.	9 ARI scanner (L2)- C 9 9 9 9 9 0 9 0 7 7 7 7 7 7 7 7 7 7 7 7 7					
cons (L2) com UNI ICCU scan UNI Resp vent Cou Upo CO1	sumption- pa pression (L3 IT – IV U patient mo nner(L2) Son IT–V piratory mea tilators(L4) - Demonstr Illustrate Implemen	rallelism(L2) - Design issues in VLSI implementation of Image p g. Hardware implementation of image processing algorithms EMBEDDED SYSTEM FOR DIAGNOSTIC APPLICATIONS nitoring system (L2) - ECG-EEG-EMG acquisition system(L2)-Nography(L2) CASE STUDY surement using spirometer- IPPB unit for monitoring respirate Defibrillator(L4)- Glucometer(L4)-Heart- Lung machine(L4) res: on of this course the students will be able to: ate the fundamental art of biomedical engineering. about wearable health devices and its importance	9 ARI scanner (L2)- C 9 Ory parameters(L4) Total : 45 Period BLOOM'S Taxonomy L2 - Understand L2 - Understand					
Cou UNI ICCU ICCU ICCU ICCU ICCU ICCU ICCU	sumption- pa pression (L3 IT – IV U patient mo nner(L2) Son IT–V piratory mea tilators(L4) -I rse Outcom Demonstr Illustrate Implemen Compare	rallelism(L2) - Design issues in VLSI implementation of Image p g. Hardware implementation of image processing algorithms EMBEDDED SYSTEM FOR DIAGNOSTIC APPLICATIONS nitoring system (L2)- ECG-EEG-EMG acquisition system(L2)-Nography(L2) CASE STUDY surement using spirometer- IPPB unit for monitoring respirated Defibrillator(L4)- Glucometer(L4)-Heart- Lung machine(L4) res: on of this course the students will be able to: ate the fundamental art of biomedical engineering. about wearable health devices and its importance t image processing applications using software and hardware	9 ARI scanner (L2)- C 9 Ory parameters(L4) Total : 45 Period BLOOM'S Taxonomy L2 - Understand L2 - Understand L2 - Understand					
cons (L2) com UNI ICCU Scan UNI Resp vent COU UPO CO1 CO2 CO2 CO3 CO4 CO4	sumption- pa pression (L3 IT – IV U patient mo nner(L2) Son IT–V piratory mea tilators(L4) -I rse Outcom Demonstr Illustrate Implemen Compare Build and	rallelism(L2) - Design issues in VLSI implementation of Image p g. Hardware implementation of image processing algorithms EMBEDDED SYSTEM FOR DIAGNOSTIC APPLICATIONS nitoring system (L2) - ECG-EEG-EMG acquisition system(L2)-Nography(L2) CASE STUDY surement using spirometer- IPPB unit for monitoring respirated Defibrillator(L4) - Glucometer(L4)-Heart- Lung machine(L4) res: on of this course the students will be able to: ate the fundamental art of biomedical engineering. about wearable health devices and its importance t image processing applications using software and hardware various embedded diagnostic applications. analyze of some biomedical equipment.	9 ARI scanner (L2)- C 9 ARI scanner (L2)- C 9 Ory parameters(L4) Total : 45 Period BLOOM'S Taxonomy L2 - Understand L2 - Understand L2 - Understand L2 - Understand					
cons (L2) com UNI ICCU Scan UNI Resp vent COU UPO CO1 CO2 CO2 CO3 CO4 CO5 REF	sumption- pa pression (L3 IT – IV U patient mo nner(L2) Son IT–V piratory mea tilators(L4) - Demonstr Illustrate Implemen Compare Build and ERENCE BO Leslie Cror	rallelism(L2) - Design issues in VLSI implementation of Image p g. Hardware implementation of image processing algorithms EMBEDDED SYSTEM FOR DIAGNOSTIC APPLICATIONS nitoring system (L2)- ECG-EEG-EMG acquisition system(L2)-Nography(L2) CASE STUDY surement using spirometer- IPPB unit for monitoring respirate Defibrillator(L4)- Glucometer(L4)-Heart- Lung machine(L4) res: on of this course the students will be able to: ate the fundamental art of biomedical engineering. about wearable health devices and its importance t image processing applications using software and hardware various embedded diagnostic applications. analyze of some biomedical equipment. OKS: mwell, "Biomedical Instrumentation and Measurement", Prenti	9 ARI scanner (L2)- C 9 Ory parameters(L4) Total : 45 Period BLOOM'S Taxonomy L2 - Understand L2 - Understand L2 - Understand L2 - Understand L2 - Understand L2 - Understand					
cons (L2) com UNI ICCU Scan UNI Resp vent Cou Upo CO1 CO2 CO2 CO3 CO4 CO4	sumption- pa pression (L3 IT – IV U patient mo nner(L2) Son IT–V piratory mea tilators(L4) - Demonstr Demonstr Illustrate Implemen Compare Build and ERENCE BO Leslie Cror Delhi, 200	rallelism(L2) - Design issues in VLSI implementation of Image p g. Hardware implementation of image processing algorithms EMBEDDED SYSTEM FOR DIAGNOSTIC APPLICATIONS nitoring system (L2)- ECG-EEG-EMG acquisition system(L2)-Nography(L2) CASE STUDY surement using spirometer- IPPB unit for monitoring respirate Defibrillator(L4)- Glucometer(L4)-Heart- Lung machine(L4) res: on of this course the students will be able to: ate the fundamental art of biomedical engineering. about wearable health devices and its importance t image processing applications using software and hardware various embedded diagnostic applications. analyze of some biomedical equipment. OKS: mwell, "Biomedical Instrumentation and Measurement", Prenti 7.	9 ARI scanner (L2)- C 9 ARI scanner (L2)- C 9 Ory parameters(L4) Total : 45 Period BLOOM'S Taxonomy L2 - Understand L2 - Understand Carter of India, New Edition, Wiley Indian CRSON					

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3.	Khandpur R.S, Handbook of Biomedical Instrumentation, Tata McGraw Hill, New Delhi, 3rd Edition, 2014.
4.	L.A Geddes and L.E.Baker, Principles of Applied Biomedical Instrumentation, 3rd Edition, John Wiley and Sons, Reprint 2008
5.	Richard S.Cobbold, Transducers for Biomedical Measurements; Principle and applicationsJohn Wiley and sons, 1992.
WEB	REFERENCES:
1.	https://www.dedicatedcomputing.com/markets/healthcare/
2.	https://www.intechopen.com/chapters/75395
ONLI	NE COURSES:
1.	https://onlinecourses.nptel.ac.in/noc22_bt34/
2.	https://onlinecourses.nptel.ac.in/noc21_bt50/
VIDE	O REFERENCES:
1.	https://www.youtube.com/watch?v=TpPXxJ7fPDs&list=PLyqSpQzTE6M_ZBtBMkhFNMg6RA8 vsBdBk
2.	https://www.youtube.com/watch?v=f08efmygAIM&list=PLyqSpQzTE6M9wr5IpP7WZxP9trrH ht3N5

Mapping of COs with POs									
60			PO						
со	P01	PO2	PO3	P04	P05	POG			
CO1	1	2	3						
CO2	W.	3	2	3					
CO3			2		3				
CO4	3	1	1		2				
CO5	1	3	3	13	E.	1			
Avg.	1.66	2.25	2.2	3	2.5				

SALEI

Bernard Knowledge



Board of Studies Faculty of Electrical & Electronics Engg Knowledge Institute of Technology KIOT Campus, Kakapalayam, Salem-637 504

ME23ET420	PYTHON PROGRAMMING FOR MACHINE LEARNING		L T 3 0	P	C 3
Programme			ersion		1 -
& Branch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	ve	ersion	: 1.	J
Course Object					
¹ variable, co	Il understand and be able to use the basic programming principles inditionals, loops, recursion and function calls.	101			
2.1.1	ill learn how to use basic data structures such as List, Dictiona text files and images	iry a	nd be	able	e to
The second	e students familiar with machine learning concepts & techniques.	- ¹			
⁴ machine lea	ill understand the process and will acquire skills necessary to ef rning problem and implement it using Python. Discussions/ Practice/Exercise onto revising & familiarizing the cond of the subject for improved research/employability skills	_	<i>91</i>	- N	
UNIT-I	INTRODUCTION TO MACHINE LEARNING AND PYTHON		9		
Learning (L2)– Model, Evaluati Difference betw Installation & R Reading Input	Machine Learning: Significance, Advantage and Applications (L1) – Ca Basic Steps in Machine Learning(L2): Raw Data Collection, Pre-pro- on of Model, Performance Improvement Introduction to Python and it ween C, C++ and Python Languages; Compiler and Interpreto unning (L2) – Basics of Python Programming Syntax: Variable Type from User (L2) – Arrays/List, Dictionary and Set (L2) – Conditiona d loop control statements(L3)	ocessi ts sig ers(L es, Ba	ing, Tr nifican 2) - asic Op	ainir ce (l Pyth erat	ng a _2)- ion3 :ors,
UNIT-II	PYTHON FUNCTIONS AND PACKAGES		9		
Loading Numpy	mensional Arrays, Joining Numpy Arrays, Array intersection and Diff Arrays(L3) – Introduction to SciPy Package & its functions(L2) - Int mming with Python(L1) IMPLEMENTATION OF MACHINE LEARNING USING PYTHON			o Ob	
			1 1		
Housing Datase with analytical Application of L	Standard Datasets: Coco, ImageNet, MNIST (Handwritten Digits t (L2)– Introducing the concepts of Regression – Linear, Polynomial & understanding (L2)- Introduction to SciPy Package & its funct near Regression and Polynomial Regression using SciPy(L3) – Interp concepts & examples using SciPy(L3)	Logis ions(stic Re (L2) –	gres: Pyt	sion hon:
UNIT – IV	CLASSIFICATION AND CLUSTERING CONCEPTS OF ML	1	9		
(L2) – Support V scikitlearn(l1) – fitting, Multiclas data from csv(L Algorithm & H Matplotlib(L1):	ML Concepts of Clustering and Classification (L1)– Types of Class Vector Machines (SVM) - Decision Tree - Random Forest(L2) – Introd Using scikit-learn, Loading a sample dataset, Learning & predicti is fitting (L2)- Implementation of SVM using Blood Cancer Dataset, I .3) Types of Clustering Algorithms & Techniques(L2) – K-means Alg ierarchical Clustering Algorithm(L2) – Introduction to Python Plotting 2- dimensional, 3-dimensional graphs; formatting axis value same graph(L3) – Implementation of K-means Algorithm and Mean S	duction, i Decis Jorith Visua es; pla	on to N nterpo sion Tro m, Me alizatio otting	AL us latio ee us an S n us mult	sing on & sing Shift sing tiple
UNIT-V	INTRODUCTION TO NEURAL NETWORKS AND EMBEDDED MACHINE LEARNING	2	9		
Perceptron & M Propagation, Ba Keras ML Pyth Introduction to Dataset ML for Overcoming (L2	Neural Networks & Significance(L1) – Neural Network Architecture(ulti-Layer Perceptron (MLP) (L2) – Commonly Used Activation Funct ok Propagation, and Epochs (L2)– Gradient Descent – Introduction on packages(L1) – Implementation of MLP Neural Network on Convolution Neural Networks(L1) – Implementation of Digit Classific Embedded Systems: Comparison with conventional ML(L3) ()– TinyML and Tensorflow Lite for Microcontrollers Don Board of Studies Encelly of Electrical & Electric Knowledge Institute of Te	tions to T Iris cation ages ML onics I ochno	(L2)- ensorf Datase n using & Met Edge [Engg	Forw low et (L g MN hods	vard and .3)- IIST ifor
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Arduino Nano BLE Sense, Google Edge TPU and Intel Movidius(L2)

	Τ	otal : 45 Periods
	se Outcomes: completion of this course the students will be able to:	BLOOM'S Taxonomy
CO1	Develop skill in system administration and network programming by learning Python.	L3 - Apply
CO2	Demonstrating understanding in concepts of Machine Learning and its implementation using Python	L2- Understand
CO3	Relate to use Python's highly powerful processing capabilities for primitives, modelling etc	L2- Understand
CO4	Improved Employability and entrepreneurship capacity due to knowledge up gradation on recent trends in embedded systems design	L3 - Apply
C05	Apply the concepts acquired over the advanced research/employability skills	L3 - Apply
REFE	RENCE BOOKS:	
1.	Mark Lutz, "LearningPython, Powerful OOPs, O'reilly, 2011.	
2.	Zelle, John "M. Python Programming: An Introduction to Computer Science.", Associates, 2003	Franklin Beedle8
3.	Andreas C. Müller, Sarah Guido, "Introduction to Machine Learning with Python	n", O'Reilly,2016
4.	Sebastian Raschka , VahidMirjalili, "Python Machine Learning - Third Edition", 2019	Packt, December
WEB	REFERENCES:	
1.	https://www.edureka.co/blog/install-numpy/	
2.	https://aws.amazon.com/what-is/neural-network/	
ONLI	NE COURSES: u	
1.	https://www.udemy.com/course/machinelearning	
2.	https://onlinecourses.nptel.ac.in/noc19_cs52/	e.
VIDE	O REFERENCES:	
1.	https://www.youtube.com/watch?v=xbYgKoG4x2g&list=PL53BE265CE4A6C05	
2.	https://www.youtube.com/watch?v=eoPsX7MKfe8&list=PLIdgECt554OVFKXRp ycO	oo_kuI0XpUQKk0

Mapping of COs with POs								
CO 10 1/PO 11								
со	PO1 .	De (PO2/el	PO3///	PO4/	PO5	POG		
CO1	+13	1.10	2	3	3			
CO2	3	1	3		3			
CO3	2	1	2	1	3			
CO4	3	2	3	3	3			
CO5	-	81		. V	3			
Avg.	2.66	1.33	2.5	3	3			

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M.E./M.Tech. Regulations-2023

ME23	3ET421	RENEWABLE ENERGY AND GRID INTEGRATION	CP 3	3 0	P (
	ramme anch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	v	ersio	n : 1.0
	se Objec	tives:			
1 7	To provide	knowledge about the stand alone and grid connected renewable	ener	gy sys	stems.
2 7	To equip w	ith required skills to derive the criteria for the design of power con	verter	rs for	renewab
- 6	energy ap	plications a and comprehend the various operating modes of wind electrical	dene	rators	and sol
3 6	eneray sy	stems		- 15 	
		different power converters namely AC to DC, DC to DC and AC	to AC	C conv	erters f
	 renewable energy systems To develop maximum power point tracking algorithms. 				
UNIT		INTRODUCTION	- 2 - 2	ç)
conve count analy	ersion(L2) tries(L2). vsis(L2) -E	to renewable energy systems(L1), environmental aspects , impacts of renewable energy penetration to grid(L2). Grid Cod Basic power electronic converters for renewable energy integration Boost and buck-boost converters, three phase AC voltage contro /M Inverters, Grid Interactive Inverters-matrix converters(L3).	es in on to	India grid-C	and oth Qualitativ
UNIT	Г-II	PHOTO VOLTAIC ENERGY CONVERSION SYSTEMS		ç)
chara alone	cteristics PV syste	1), Photo Voltaic (PV) effect, Solar Cell, Types(L2), Equivalent cire (I/V and P/V) for variation of insolation(L2), temperature and sl m(L2), Grid connected PV system(L2), Design of PV system-load n of converter/inverter, battery sizing(L3).	hading	g effe	ct, Stand
UNIT	- III	- III WIND ENERGY CONVERSION SYSTEMS			
Electi (L2),	rical mach Grid Coni	ies, Power curve and Operating area, Types of wind generate ines(L2)-Induction Generator and Permanent Magnet Synchrono nected-Single and Double output system, Self-excited operation of peed PMSG(L3).	ous Ge	enerat	or(PMSC
UNIT	r – IV	STANDARDS AND FRAMEWORK		9)
Case	studies o	f PV-Maximum Power Point Tracking (MPPT) and Wind Energy sys	stem(l	L3)	
UNIT	r- v	HYBRID STORAGE SYSTEMS AND GRID MANAGEMENT		9	
		e systems(L2), Need for Hybrid Systems(L2), Features of Hybrid ybrid systems (Wind-Diesel, PV-Diesel and Wind-PV)(L3).	Syste	ems(L	2), Ran <u>c</u>
		-	Tota	al : 4!	5 Period
	se Outco			OM'S	
	and the second se	tion of this course the students will be able to: ne power generation of different renewable energy sources to grid		onom	
CO1	impact and grid codes		L2- Understand		stand
CO2	Explain	the design principles of solar energy management systems	L3- A	Apply	
	D3 Understand the power conversion system of wind generators		L2- Understand		stand
CO3	Underst				
~	N IN PAGE	the different Maximum Power Point tracking Techniques	L2- L	Inder	stand
CO4	Analyze Build gr	the different Maximum Power Point tracking Techniques id connected and stand alone renewable energy management		Jnders Jnders	
CO4 CO5	Analyze Build gr system	id connected and stand alone renewable energy management			
in Giai	Analyze Build gr system	id connected and stand alone renewable energy management OOKS: CHAIRPERSON Board of Studies	L2- U	Jnders	
CO4 CO5 REFE	Analyze Build gr system	id connected and stand alone renewable energy management CHAIRPERSON Board of Studies	L2- U	Jnders	

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3.	Haitham Abu-Rub, Mariusz Malinowski and Kamal Al-Haddad, "Power Electronics for Renewable Energy Systems, Transportation and Industrial Applications", IEEE Press and John Wiley & Sons Ltd Press, 2014.
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5.	Gray, L. Johnson, "Wind energy system", prentice hall linc, 1995.
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2.	https://www.nrel.gov/docs/fy15osti/63033.pdf
ONL	INE COURSES:
1.	https://www.coursera.org/learn/renewable-power-electricity-systems
2.	https://nptel.ac.in/courses/103103206
VIDE	O REFERENCES:
1.	https://www.youtube.com/watch?v=mh51mAUexK4&list=PLwdnzIV3ogoXUifhvYB65ILJCZ74o_ fAk
2.	https://www.youtube.com/watch?v=cGHIV0EavaQ

		Mappin	g of COs with	PUS						
со	PO									
0	PO1	PO2	PO3/	PO4	P05	POe				
CO1	1	2	1	62	1	-				
CO2	1	1	2		1					
CO3	2		S 1 6	1	1	2				
CO4	1 🔍	2	1	2	1	2				
CO5	3 🧸	1 3	2	Active 2 August	2					
Avg.	1.6	2	1.4	1.5	1.25	2				

Beyond Knowledge

CHAIRPERSON

Board of Studies Faculty of Electrical & Electronics Engg Knowledge Institute of Technology KIOT Campus, Kakapalayam, Salem-637 504

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M.E./M.Tech. Regulations-2023

ME2	3ET422	ELECTRIC VEHICLES AND POWER MANAGEMENT	CP L T P C 3 3 0 0 3
Prog Bran	gramme & nch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	Version : 1.0
Cou	rse Objective	es:	1
1	To discuss the	e fundamentals building blocks of a digital instrument	
2	Introduce wir	ed, WSN for configuring metering network	Ξ
3	Discuss requi	rements for grid automation using meters.	
4	To discuss ne	tworking configuration to develop PAN	THE FOR
5	To discuss the	e functions of digital instrument Power quality monitoring	
UNI	T-I	ELECTRIC VEHICLES AND VEHICLE MECHANICS	9
		EV)(L2), Hybrid Electric Vehicles (HEV) (L2), Engine ratings- Con Engine vehicles(L2)- Fundamentals of vehicle mechanic(L2)	
	T-II	ARCHITECTURE OF EV'S AND POWER TRAIN COMPONENTS	9
		V's and HEV's (L2)- Plug-n Hybrid Electric Vehicles (PHE izing, Gears, Clutches, Transmission and Brakes(L2).	V) (L2)- Power train
	T– III	POWER ELECTRONICS AND MOTOR DRIVES	9
drive	es(L2) – Indu	nponents (L2)- Power electronic switches(L2)- four quadr uction motor and permanent magnet synchronous motor- witched reluctance motor (SRM) drives(L3)- EV motor sizing(L	based vector contro
12	T – IV	BATTERY ENERGY STORAGE SYSTEM	9
)- Different types- Battery Parameters-Battery life & safety ign of battery for large vehicles(L3).	impacts (L2)-Battery
UNI		ALTERNATIVE ENERGY STORAGE SYSTEMS	9
(PEM	duction to fue i) fuel cell for cations(L3)	el cell(L1) – Types, Operation and characteristics(L2)- proton E-mobility(L2)– hydrogen storage systems(L2) –Super capacil	exchange membrane tors for transportatior
		10 1 11 11	Total : 45 Periods
	rse Outcome n completion	s:	BLOOM'S Taxonomy
CO1	Understand	the concept of electric vehicle and energy storage systems.	L2 – Understand
C02	Describe th Electric Veh	e working and components of Electric Vehicle and Hybrid icle	L2 – Understand
соз	Know the p	rinciples of power converters and electrical drives	L2 – Understand
CO4	Illustrate th capacitors	ne operation of storage systems such as battery and super	L3 – Apply
CO5	and the second second second second second	e various energy storage systems based on fuel cells and corage	L2 – Understand
REFE	ERENCE BOO		
1.		in, "Electric and Hybrid Vehicles: Design Fundamentals, Secon Incis Group, Second Edition (2011).	d Edition" CRC Press,
2.	Ali Emadi, M	lehrdad Ehsani, John M.Miller, "Vehicular Electric Power Syster cel dekker, Inc 2010.	ns", Special 63 Indiar
3.	Mehrdad Eh	sani, YiminGao, Sebastian E. Gay, Ali Emadi, 'Modern Electric hicles: Fundamentals, Theory and Design', CRC Press, 2004.	
e de se	401 M.S. mass		Board of Studies
		Knowled	f Electrical & Electronics E dge Institute of Technol
	KIOT	35 M.E./M.TephORe	Cuttions? Rakapalayan Salem - 637 504

4.	C.C. Chan and K.T. Chau, 'Modern Electric Vehicle Technology', OXFORD University Press, 2001
5.	Wie Liu, "Hybrid Electric Vehicle System Modeling and Control", Second Edition, John Wiley & Sons, 2017.
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2.	https://archive.nptel.ac.in/courses/108/106/108106170/
ONL	INE COURSES:
1.	https://onlinecourses.nptel.ac.in/noc22_ee53/
2.	https://onlinecourses.nptel.ac.in/noc21_ee112/
VIDE	O REFERENCES:
1.	https://www.youtube.com/watch?v=UgtjRob5qMg&list=PLyqSpQzTE6M9spod- UH7Q69wQ3uRm5thr
2.	https://www.youtube.com/watch?v=V004WUdpHeA&list=PLIYm0- AHZdZRLYSylFinxkspWmcgNvbtl

Mapping of COs with POs								
со РО								
0	P01	PO2	PO3	PO4	P05	POG		
CO1	3	3 < 1	3	2	3			
CO2	3	3	3	2	3			
CO3	3	3	3	2	3			
CO4	3	3	3	2	3			
CO5	3	3	3	2	3			
Avg.	3	3	3	2	3			

SALEI

Begend Knowledge

CHAIRPERSON Board of Studies Faculty of Electrical & Electronics Engg Knowledge Institute of Technology KIOT Campus, Kakapalayam, Salem-637 504

36

ME	3ET423	SMART GRID	CP L T P C 3 3 0 0 3
Pro Bra	gramme &	M.E. EMBEDDED SYSTEM TECHNOLOGIES	Version : 1.0
	rse Objectiv	es:	
1		oout Smart Grid technologies, different smart meters and	advanced metering
2	To know abou	ut the function of smart grid	
3	To familiarize	the power quality management issues in Smart Grid	
4	To familiarize	the high performance computing for Smart Grid applications	
5	To get familia	rized with the communication networks for Smart Grid application	ons
UNI	T-I	INTRODUCTION TO SMART GRID	9
func Grid Sma	tions, opport (L2), Compar art Grid, Smar	ric Grid(I2), Concept, Definitions and Need for Smart Grid(I2), unities, challenges and benefits(I2), Difference between cor ison of Micro grid and Smart grid(I2), Present development & Int t Grid Initiative for Power Distribution Utility in India(L2) – Case	nventional & Smar ernational policies in
UNJ	T-II	SMART GRID TECHNOLOGIES	9
Auto mon Dete Dist	omation(L2), F itoring(L2), I ection(L2), Is ribution Trans	rs, Smart Integration of energy resources(L2), Smart substat reeder Automation(L2), Transmission systems: EMS, FACTS and F Protection and control, Distribution systems: DMS(L2), Volt solation and service restoration(L2), Outage management(sformers(L2), Phase Shifting Transformers(L2), Plug in Hybr	HVDC(L2), Wide area t/Var control, Faul L2), High-Efficiency
(PHI	EV(L2)) (L3) -	Grid to Vehicle and Vehicle to Grid charging concepts(L2)	
UNI	T– III	SMART METERS AND ADVANCED METERING	9
UNI Intro AMI Unit	T– III oduction to S protocols, sta (PMU) & their	SMART METERS AND ADVANCED METERING	rs and benefits(L2) Phasor Measuremen gement and deman
UNI Intro AMI Unit resp	T– III oduction to S protocols, sta (PMU) & their	SMARTMETERSANDADVANCEDMETERINGINFRASTRUCTUREmartmart Meters(L1), Advanced Metering infrastructure (AMI) driveandards and initiatives(L2), AMI needs in the smart grid(L2), Fapplication for monitoring & protection(L2). Demand side management	rs and benefits(L2) Phasor Measuremen gement and deman
UNI AMI Unit resp UNI Pow Sou	T- III oduction to Si protocols, sta (PMU) & their onse program T - IV er Quality & I rces(L2), Powe	SMART METERS AND ADVANCED METERING INFRASTRUCTURE mart Meters(L1), Advanced Metering infrastructure (AMI) drive andards and initiatives(L2), AMI needs in the smart grid(L2), F application for monitoring & protection(L2). Demand side manages(L2), Demand pricing and Time of Use, Real Time Pricing(L3), Pereception (L2), Demand pricing (L2), Power Quality issues of Grid connected and the smart Grid(L2), Power Quality issues of Grid connected and the smart Grid(L2), Web based Power Quality Conditioners for Smart Grid(L2), Web based Power Quality	ers and benefits(L2) Phasor Measuremen gement and demand eak Time Pricing(L3) 9 d Renewable Energy
UNI Intro AMI Unit resp UNI Pow Sou Pow	T- III protocols, sta (PMU) & their onse program T - IV er Quality &	SMART METERS AND ADVANCED METERING INFRASTRUCTURE mart Meters(L1), Advanced Metering infrastructure (AMI) drives andards and initiatives(L2), AMI needs in the smart grid(L2), F application for monitoring & protection(L2). Demand side manages s(L2), Demand pricing and Time of Use, Real Time Pricing(L3), Period POWER QUALITY MANAGEMENT IN SMART GRID EMC in Smart Grid(L2), Power Quality issues of Grid connected er Quality Conditioners for Smart Grid(L2), Web based Power Quality (L3). HIGH PERFORMANCE	ers and benefits(L2) Phasor Measuremen gement and demand eak Time Pricing(L3) 9 d Renewable Energy
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UNI Intra AMI Unit resp UNI Pow Sour Pow Sour Pow Sour Pow Sour Pow Sour Pow Sour Pow Sour Pow Sour Pow Sour Pow Sour Pow Sour Pow Sour Pow Sour Pow Sour Pow Sour Pow Sour Pow	T- III oduction to Si protocols, sta (PMU) & their onse program T - IV er Quality & I rces(L2), Powe er Quality Auc T-V itecture and vork (WAN), E Service and o	SMART METERS AND ADVANCED METERING INFRASTRUCTURE mart Meters(L1), Advanced Metering infrastructure (AMI) drives andards and initiatives(L2), AMI needs in the smart grid(L2), F application for monitoring & protection(L2). Demand side manages s(L2), Demand pricing and Time of Use, Real Time Pricing(L3), Period POWER QUALITY MANAGEMENT IN SMART GRID EMC in Smart Grid(L2), Power Quality issues of Grid connected er Quality Conditioners for Smart Grid(L2), Web based Power Quality (L3). HIGH PERFORMANCE COMPUTING FOR SMART GRID Standards(L2) - Local Area Network (LAN), House Area Network Broadband over Power line (BPL), PLC, Zigbee, GSM, IP based Proce CLOUD Computing(L3), Cyber Security for Smart Grid(L3).	rs and benefits(L2) Phasor Measuremen gement and demand eak Time Pricing(L3) 9 d Renewable Energy ality monitoring(L3) 9 k (HAN), Wide Area btocols(L2), Basics o Total : 45 Periods
UNI Intra AMI Unit Unit Unit UNI Pow Sou Pow Sou Netw Web Cou	T- III oduction to Si protocols, sta (PMU) & their onse program T - IV er Quality & I rces(L2), Powe er Quality Auc T-V itecture and vork (WAN), E Service and o rse Outcome	SMART METERS AND ADVANCED METERING INFRASTRUCTURE mart Meters(L1), Advanced Metering infrastructure (AMI) drives andards and initiatives(L2), AMI needs in the smart grid(L2), F application for monitoring & protection(L2). Demand side manages s(L2), Demand pricing and Time of Use, Real Time Pricing(L3), Period POWER QUALITY MANAGEMENT IN SMART GRID EMC in Smart Grid(L2), Power Quality issues of Grid connected er Quality Conditioners for Smart Grid(L2), Web based Power Qualities HIGH PERFORMANCE COMPUTING FOR SMART GRID Standards(L2) - Local Area Network (LAN), House Area Network Broadband over Power line (BPL), PLC, Zigbee, GSM, IP based Proce CLOUD Computing(L3), Cyber Security for Smart Grid(L3).	rs and benefits(L2) Phasor Measuremen gement and demand eak Time Pricing(L3) 9 d Renewable Energy ality monitoring(L3) 9 k (HAN), Wide Area btocols(L2), Basics o Total : 45 Periods BLOOM'S
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UNI Intra AMI Unit Tresp UNI Pow Soul Pow Soul Pow UNI Arch Netv Web Cou UPO CO1	T – III oduction to Si protocols, sta (PMU) & their onse program T – IV er Quality & I rces(L2), Powe er Quality Auc T–V iltecture and vork (WAN), E Service and o rse Outcome n completion Relate with Explain the	SMART METERS AND ADVANCED METERING INFRASTRUCTURE mart Meters(L1), Advanced Metering infrastructure (AMI) drives and ards and initiatives(L2), AMI needs in the smart grid(L2), F application for monitoring & protection(L2). Demand side manages(L2), Demand pricing and Time of Use, Real Time Pricing(L3), Perescuence of Use, Demand pricing and Time of Use, Real Time Pricing(L3), Perescuence of Use, Demand pricing and Time of Use, Real Time Pricing(L3), Perescuence of Use, Demand Standards(L2), Demand pricing and Time of Use, Real Time Pricing(L3), Perescuence of Use, Demand Standards(L2), Power Quality issues of Grid connected of Quality Conditioners for Smart Grid(L2), Web based Power Quality (L3). HIGH PERFORMANCE COMPUTING FOR SMART GRID APPLICATIONS Standards(L2) -Local Area Network (LAN), House Area Network CLOUD Computing(L3), Cyber Security for Smart Grid(L3). Standards(L2) -Local Area Network (LAN), House Area Network CLOUD Computing(L3), Cyber Security for Smart Grid(L3). es: n of this course the students will be able to: the smart resources, smart meters and other smart devices.	rs and benefits(L2) Phasor Measuremen gement and deman- eak Time Pricing(L3) 9 d Renewable Energ ality monitoring(L3) 9 k (HAN), Wide Are- otocols(L2), Basics of Total : 45 Period BLOOM'S Taxonomy L1 - Remember
UNI Intra AMI Unit resp UNI Pow Sou Pow UNI Pow UNI Arch Netv Web Cou UD0 CO1 CO2 CO3	T - III oduction to Si protocols, sta (PMU) & their onse program T - IV er Quality & I rces(L2), Powe er Quality Aud T-V itecture and vork (WAN), E Service and of rse Outcome n completion Relate with Explain the Experiment	SMART METERS AND ADVANCED METERING INFRASTRUCTURE mart Meters(L1), Advanced Metering infrastructure (AMI) drive andards and initiatives(L2), AMI needs in the smart grid(L2), F application for monitoring & protection(L2). Demand side manars(L2), Demand pricing and Time of Use, Real Time Pricing(L3), Peters(L2), Demand pricing and Time of Use, Real Time Pricing(L3), Peters(L2), Demand pricing and Time of Use, Real Time Pricing(L3), Peters(L2), Demand pricing and Time of Use, Real Time Pricing(L3), Peters(L2), Demand pricing and Time of Use, Real Time Pricing(L3), Peters(L2), Demand pricing and Time of Use, Real Time Pricing(L3), Peters(L2), Demand pricing and Time of Use, Real Time Pricing(L3), Peters(L2), Demand pricing and Time of Use, Real Time Pricing(L3), Peters(L3). EMC in Smart Grid(L2), Power Quality issues of Grid connected are Quality Conditioners for Smart Grid(L2), Web based Power Quality (L3). HIGH PERFORMANCE COMPUTING FOR SMART GRID APPLICATIONS Standards(L2) -Local Area Network (LAN), House Area Networe Broadband over Power line (BPL), PLC, Zigbee, GSM, IP based Procecuber CLOUD Computing(L3), Cyber Security for Smart Grid(L3). es: n of this course the students will be able to: the smart resources, smart meters and other smart devices. function of Smart Grid	rs and benefits(L2) Phasor Measuremen gement and deman- eak Time Pricing(L3) 9 d Renewable Energ ality monitoring(L3) 9 k (HAN), Wide Are- btocols(L2), Basics of Total : 45 Period BLOOM'S Taxonomy L1 - Remember L2 - Understand
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UNI Intra AMI Unit resp UNI Pow Soul Pow Soul Pow UNI Arch Netv Web Cou UNI CO1 CO2 CO3 CO4 CO4	T - III oduction to Si protocols, sta (PMU) & their onse program T - IV er Quality & I rces(L2), Powe er Quality Auc T-V itecture and vork (WAN), E Service and of rse Outcome n completion Relate with Explain the Experiment Analyze the	SMART METERS AND ADVANCED METERING INFRASTRUCTURE mart Meters(L1), Advanced Metering infrastructure (AMI) drive andards and initiatives(L2), AMI needs in the smart grid(L2), Fapplication for monitoring & protection(L2). Demand side manas(L2), Demand pricing and Time of Use, Real Time Pricing(L3), Pe POWER QUALITY MANAGEMENT IN SMART GRID EMC in Smart Grid(L2), Power Quality issues of Grid connected are quality Conditioners for Smart Grid(L2), Web based Power Qualit (L3). HIGH PERFORMANCE COMPUTING FOR SMART GRID APPLICATIONS Standards(L2) -Local Area Network (LAN), House Area Networe Groadband over Power line (BPL), PLC, Zigbee, GSM, IP based Proc CLOUD Computing(L3), Cyber Security for Smart Grid(L3). es: n of this course the students will be able to: the smart resources, smart meters and other smart devices. function of Smart Grid the issues of Power Quality in Smart Grid. e performance of Smart Grid d suitable communication networks for Shart Or State of States and	rs and benefits(L2) Phasor Measuremen gement and deman- eak Time Pricing(L3) 9 d Renewable Energ ality monitoring(L3) 9 k (HAN), Wide Are- btocols(L2), Basics of Total : 45 Period BLOOM'S Taxonomy L1 - Remember L2 - Understand L2 - Understand L2 - Understand

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2.	JanakaEkanayake, Nick Jenkins, KithsiriLiyanage, Jianzhong Wu, Akihiko Yokoyama, 'Smart Grid: Technology and Applications', Wiley, 2012
3.	Mini S. Thomas, John D McDonald, 'Power System SCADA and Smart Grids', CRC Press, 2015
4.	Kenneth C.Budka, Jayant G. Deshpande, Marina Thottan, 'Communication Networks for Smart Grids', Springer, 2014
5.	SMART GRID Fundamentals of Design and Analysis, James Momoh, IEEE press, A John Wiley & Sons, Inc., Publication.
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2.	https://amity.edu/icactm/Proceeding/Paper%20Index%20Content/24%20T4%20P9%20ID%209 .pdf
ONL	INE COURSES:
1.	https://onlinecourses.nptel.ac.in/noc21_ee68
2.	https://onlinecourses.nptel.ac.in/noc23_ee124/
VIDE	EO REFERENCES:
1.	https://www.youtube.com/watch?v=KgVFJnmJvKk&list=PLSJzHGpGe6IP5biCvZrtQdHf80tnSXRBr
2.	https://archive.nptel.ac.in/noc/courses/noc20/SEM2/noc20-ee65/

	Mapping	of COs with I	POs		
		PO			
PO1	PO2	PO3	PO4	PO5	P06
3	2	1	2	2	
3		2/	2		
2		1			10
1		1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1	3	3	
E an	2	2	2	2	
2.25	2 2	1.66	2.25	2.3	
	3 3 2 1	PO1 PO2 3 2 3 2 1 2 2 2	PO1 PO2 PO3 3 2 2 3 2 1 1 2 1 2 2 2	PO1 PO2 PO3 PO4 3 2 2 2 3 2 2 2 2 1 3 3 1 2 2 2 2 2 2 2	PO1 PO2 PO3 PO4 PO5 3 2 2 2 2 3 2 2 2 2 3 2 2 2 2 3 2 2 2 2 1 3 3 3 3 2 2 2 2 2 2



Begend Knowledge

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M.E./M.Tech. Regulations-2023