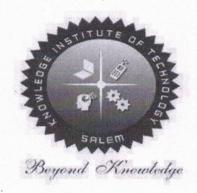
KNOWLEDGE INSTITUTE OF TECHNOLOGY

(An Autonomous Institution)

Approved by AICTE, Affiliated to Anna University, Chennai.

Accredited by NBA (CSE, ECE, EEE & MECH), Accredited by NAAC with 'A' Grade KIOT Campus, Kakapalayam (PO), Salem – 637 504, Tamil Nadu, India.



M.E. / M.Tech. Regulations 2023

M.E. - Computer Science and Engineering

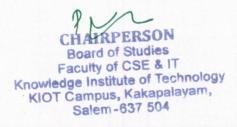
Curriculum and Syllabi
(For the Students Admitted from the Academic Year 2023-24 Onwards)

Version: 1.0

Date: 09.09.2023

CHAIRPERSON
Board of Studies
Faculty of CSE & IT
Knowledge Institute of Technology
KIOT Campus, Kakapalayam,
Salem-637, 504

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KNOWLEDGE INSTITUTE OF TECHNOLOGY (AUTONOMOUS), SALEM -637504

Approved by AICTE, Affiliated to Anna University, Accredited by NAAC and NBA (B.E.: Mech., ECE, EEE & CSE)

Website: www.kiot.ac.in

Version 1.0

M.E. / M.Tech. REGULATIONS 2023 (R 2023) CHOICE BASED CREDIT SYSTEM AND OUTCOME BASED EDUCATION

M.E. COMPUTER SCIENCE AND ENGINEERING

VISION OF THE INSTITUTE

To be a world class institution to impart value and need based professional education to the
aspiring youth and carving them into disciplined world class professional who have the quest for
excellence, achievement orientation and social responsibilities

MISSI	ON OF THE INSTITUTE
A	To promote academic growth by offering state-of-art undergraduate, postgraduate and doctora programs and to generate new knowledge by engaging in cutting – edge research
В	To nurture talent, innovation, entrepreneurship, all-round personality and value system among the students and to foster competitiveness among students
С	To undertake collaborative projects which offer opportunities for long-term interaction with academia and industry
D	To pursue global standards of excellence in all our endeavors namely teaching, research, consultancy, continuing education and support functions

VISION OF THE DEPARTMENT

To create globally competent software professionals with social values to cater the ever-changing industry requirements.

MISSIO	N OF THE DEPARTMENT
M1	To provide appropriate infrastructure to impart need-based technical education through effective teaching and research.
M2	To involve the students in collaborative projects on emerging technologies to fulfill the industrial requirements.
МЗ	To render value based education to students to take better engineering decision with social consciousness and to meet out the global standards.
М4	To inculcate leadership skills in students and encourage them to become a Globally competent professional.

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Faculty of CSE M.E./M.Tech. Regulation 2023

Knowledge Institute of Technology

KIOT Campus, Kakapalayam,

Salem-637 504

PROGRA	M EDUCATIONAL OBJECTIVES (PEOs)
PEO 1	Develop proficiency as a computer science engineer with an ability to solve a wide range of computational problems and have sustainable development in industry or any other work environment.
PEO 2	Possess the ability to think analytically and logically to understand technical problems with computational systems for a lifelong learning which leads to pursuing research.
PEO 3	Strongly focus on design thinking and critical analysis to create innovative products and become entrepreneurs.

PROGRA	AM OUTCOMES (POs)
Engineer	ring Graduates will be able to:
PO1	An ability to independently carry out research / investigation and development work to solve practical problems.
PO2	An ability to write and present a substantial technical report/document.
РОЗ	Students should be able to demonstrate a degree of mastery over the area of Computer Science and Engineering.
PO4	Efficiently design, build and develop system application software for distributed and centralized computing environments in varying domains and platforms.
PO5	Understand the working of current Industry trends, the new hardware architectures, the software components and design solutions for real world problems by Communicating and effectively working with professionals in various engineering fields and pursue research orientation for a lifelong professional development in computer and automation arenas.
P06	Model a computer based automation system and design algorithms that explore the understanding of the tradeoffs involved in digital transformation.

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		I.E. COMPUTER SCIENCE AND E	NGIN	EER	NG			1,34	V	ersion	: 1.0
20.0	Courses o	f Study and Scheme of Assessm	ent (Regi	ılati	ons	202	23)	Dat	te : 09	.09.23
SI.	Course	Course Title	F	eriods / Week			ek		Maxi	mum	Marks
No.	Code	Course Title	CAT	CP	L	Т	P	С	IA	ESE	Total
		SEMEST	ERI								
-	-	Induction Programme	-		-	-	-	-	-		-
	THEORY										
1.	ME23MA103	Applied Probability and Statistics for Computer Science Engineers	FC	4	3	1	0	4	40	60	100
2.	ME23RM201	Research Methodology and IPR	RM	3	2	1	0	3	40	60	100
3.	ME23CP301	Advanced Data Structures and Algorithms	PC	3	3	0	0	3	40	60	100
4.	ME23CP302	Database Practices	PC	3	3	0	0	3	40	60	100
5.	ME23CP303	Network Technologies	PC	3	3	0	0	3	40	60	100
6.	ME23CP304	Principles of Programming Languages	PC	3	3	0	0	3	40	60	100
7.	ME23AC7XX	Audit Course – I*	AC	2	2	0	0	NC	100	-	100
	PRACTICALS										
8.	ME23CP305	Advanced Data Structures and Algorithms Laboratory	PC	4	0	0	4	2	60	40	100
9.	ME23CP306	Database Practices Laboratory	PC	4	0	0	4	2	60	40	100
	EMPLOYABI	LITY ENHANCEMENT									
10.	ME23PT801	Technical Seminar / Case Study Presentation	EEC	2	0	0	2	0	100	-	100
ГОТ	AL	•		31	19	2	10	23	560	440	1000
		SEMEST	ER II								
	THEORY										
1.	ME23CP307	Advanced Software Engineering	PC	3	3	0	0	3	40	60	100
2.	ME23CP308	Multicore Architecture , and Programming	PC	3	3	0	0	3	40	60	100
3.	ME23MC701	Universal Human Values and Ethics	МС	3	2	1	0	3	40	60	100
4.	ME23CP4XX	Professional Elective - I	PE	3	3	0	0	3	40	60	100
5.	ME23CP4XX	Professional Elective - II	PE	3	3	0	0	3	40	60	100
6.	ME23AC7XX	Audit Course – II*	AC	2	2	0	0	0	100	<u>-</u>	100
7.	ME23XX5XX	Open Elective - I	OE	3	3	0	0	3	40	60	100
	PRACTICAL	S									
8.	ME23CP309	Software Engineering Laboratory	PC	2	0	0	2	1	60	40	100
	EMPLOYABI	LITY ENHANCEMENT	3421861A	D. Ta		111		pulls.			
9.	ME23PT802	Research Paper Review and Presentation	EEC	2	0	0	2	1	100	-	100
				1							

*Audit Course is Optional



		M.E. COMPUTER SCIENCE AN	ND ENGIN	EER:	ING				V	ersio	n:1.0
	Courses	of Study and Scheme of Asse	essment (Reg	ulati	ons	202	23)	Da	te : 0	9.09.23
SI.	Course	Course Title		Peri	ods	/ W	eek		Max	cimun	n Marks
No.	Code	Course ritte	CAT	CP	L	T	P	С	IA	ESE	Total
		SE	MESTER I	II							
	THEORY										
1.	ME23CP310	Security Practices	PC	3	3	0	0	3	40	60	100
2.	ME23CP4XX	Professional Elective - III	PE	3	3	0	0	3	40	60	100
3.	ME23XX5XX	Open Elective - II	OE	3	3	0	0	3	40	60	100
	THEORY CU	M PRACTICAL				5.1				43/7×2 (1.3	
4.	ME23CP4XX	Professional Elective - IV	PE	5	3	0	2	4	50	50	100
5.	ME23CP311	Internet of Things	PC	5	3	0	2	4	50	50	100
	PRACTICAL										
6.	ME23CP601	Project Work - Phase I	PW	12	0	0	12	6	60	40	100
		TOTAL		31	15	0	16	23	280	320	600
		SEMI	ESTER IV								
	PRACTICAL	2000									
1.	ME23CP602	Project Work -Phase II	, bM	24	0	0	24	12	60	40	100
		TOTAL	EV.	24	0	0	24	12	60	40	100

						-								
		PROFESSIONA	L ELE	CTIV	/ES									
	SEMESTER II (Professional Electives - I & II)													
s.	Course			Perio	ods	/ W	eek		Ma	ximum	Marks			
No.	Code	Course Title	CAT	СР	L	т	Р	С	IA	ESE	Total			
1.	ME23CP401	Cloud Computing Technologies	PE	3	3	0	0	3	40	60	100			
2.	ME23CP402	Foundations of Data Science	PE	3	3	0	0	3	40	60	100			
3.	ME23CP403	Agile Methodologies	PE	3	3	0	0	3	40	60	100			
4.	ME23CP404	Digital Image Processing	PE	3	3	0	0	3	40	60	100			
5.	ME23CP405	Machine Learning	PE	3	3	0	0	3	40	60	100			
6.	ME23CP406	Software Quality Assurance	, PE	3	3	0	0	3	40	60	100			
7.	ME23CP407	Autonomous Systems	PE	3	3	0	0	3	40	60	100			
8.	ME23CP408	Big Data Mining and Analytics	PE	3	3	0	0	3	40	60	100			
	400.6	SEMES (Professional Ele			I & :	(V)								
S.	Course			Peri	ods	/ W	/eek		Maximum		Marks			
No.	Code	Course Title	CAT	СР	L	Т	P	С	IA	ESE	Total			
.1.	ME23CP409	Web Services and API Design	PE	3	3	0	0	3	40	60	100			

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				The second second	A State of the Sta				And the state of the state of		
2.	ME23CP410	Data Visualization Techniques	PE	3	3	0	0	3	40	60	100
3.	ME23CP411	Compiler Optimization Techniques	PE	3	3	0	0	3	40	60	100
4.	ME23CP412	Robotics	PE	3	3	0	0	3	40	60	100
5.	ME23CP413	Devops and Micro services	PE	5	3	0	2	4	50	50	100
6.	ME23CP414	Deep Learning	PE	5	3	0	2	4	50	50	100
7.	ME23CP415	Block chain Technologies	PE	5	3	0	2	4	50	50	100
8.	ME23CP416	Full Stack Web Application Development	PE	5	3	0	2	4	50	50	100

		OPEN ELE	CTIVE	S								
S.		Course Tible		Perio	ods	/ W	eek		Maximum Marks			
No.	Course Code	Course Title	CAT	СР	L	Т	Р	С	IA	ESE	Total	
Exc		outer Science and Engineering	ng				Cell	Trial I		MARKET !		
1.	ME23CP501/ ME23CP310	Security Practices	OE	3	3	0	0	3	40	60	100	
2.	ME23CP502/ ME23CP401	Cloud Computing Technologies	OE	3	3	0	0	3	40	60	100	
3.	ME23CP503/ ME23CP415	Block chain Technologies	OE	3	3	0	0	3	40	60	100	
4.	ME23CP504/ ME23CP414	Deep Learning	OE	3	3	0	0	3	40	60	100	
5.	ME23CP505	Design Thinking	OE	3	3	0	0	3	40	60	100	
6.	ME23CP506	Principles of Multimedia	, OE	3	3	0	0	3	40	60	100	
Exce	pt M.E. Indus	trial Safety Engineering										
7.	ME23IS501/ ME23IS302	Environmental Safety	OE	3	3	0	0	3	40	60	100	
8.	ME23IS502/ ME23IS309	Electrical safety	OE	3	3	0	0	3	40	60	100	
9.	ME23IS503/ ME23IS413	Safety in Engineering Industry	OE	3	3	0	0	3	40	60	100	
10.	ME23IS504	Design of Experiments	OE	3	3	0	0	3	40	60	100	
11.	ME23IS505	Circular Economy	OE	3	3	0	0	3	40	60	100	
Exce	pt M.E. Embe	dded System Technologies										
12.	ME23ET501/ ME23ET310	IoT for Smart Systems	OE	3	3	0	0	3	40	60	100	
13.	ME23ET502/ ME23ET408	Machine Learning and Deep Learning	OE	3	3	0	0	3	40	60	100	
14.	ME23ET503	Renewable Energy Technology	OE	3	3	0	0	3	40	60	100	
15.	ME23ET504/ ME23ET423	Smart Grid	OE	3	3	0	0	3	40	60	100	
Exce	pt M.E. VLSI	Design						138				
16.	ME23VL501	Big Data Analytics	OE	3	3	0	0	3	40	60	100	
17.	ME23VL502	Internet of Things and Cloud	OE	3	3	0	0	3	40	60	100	
18.	ME23VL503	Medical Robotics	OE	3	3	0	0	3	40	60	100	
19.	ME23VL504	Embedded Automation	OE	3	3	0	0	3	40	60	100	

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	FOUNDATION COURSES (FC)													
SI.	Course	Course title		Perio	ods	/ W		Maximum Marks						
No.	Code		CAT	СР	L	Т	P	С	IA	ESE	Total			
1.	ME23MA103	Applied Probability and Statistics for Computer Science Engineers	FC	4	3	1	0	4	40	60	100			

	MANDATORY COURSE AUDIT COURSES (Optional Courses)													
			ı	Perio	ods	/ W	eek		Maxi	mum I	4arks			
SI. No.	Course Code	Course Title	CAT	СР	L	T	P	С	IA	ESE	Total			
1.	ME23AC701	English for Research Paper Writing	AC	2	2	0	0	0	100	3.5(-3)	100			
2.	ME23AC702	Disaster Management	AC	2	2	0	0	0	100	35 (5)	100			
3.	ME23AC703	Constitution of India	AC	2	2	0	0	0	100	-	100			
4.	ME23AC704	ew;wkpo; ,yf;fpak;/ Classical Tamil Literature	AC	2	2	0	0	0	100	-	100			
100		MANDATOR	Y CO	URSI	ES									
1.	ME23MC701	Universal Human Values and Ethics	МС	3	2	1	0	3	40	60	100			

SEMESTER-WISE CREDITS DISTRIBUTION

SUMMARY '								
	Course		Credits pe	r Semeste			Credit	
SI. No.	Category	I	II	III	IV	Credits	%	
1.	FC	4	-	-		4	5	
2.	RM	3	-	- 11		3	4	
3.	PC PC	16	7	8		31	40	
4	PE		6	6		12	15	
5.	OE .	-	3	3		6	8	
6.	PW		-	6	12	18	23	
7.	MC/AC	-	3	rine <u>-</u> me		3	4	
8.	EEC	-	1			1	1	
	Total	23	20	23	12	78	100	

АТ	Category of Course	FC	Foundation Courses	МС	Mandatory Courses
СР	Contact Period	PC	Professional Core Courses	AC	Audit Courses
L	Lecture Period	PE	Professional Elective Courses	IA	Internal Assessment
Т	Tutorial Period	OE	Open Elective Courses	ESE	End Semester Examination
Р	Laboratory Period	PW	Project Work Courses		
С	Credits	EEC	Employability Enhancement Courses	CHA	RPERSON

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Faculty of CSE & M. Tech. Regulation 2023
Knowledge Institute of Technology
KIOT Campus, Kakapalayam,
Salem -637 504

	ME23CP311	INTERNET OF THINGS		Vers	sion:	1.0		
rog	ramme &	M.E. – Computer Science and Engineering	CP 5	L 3	T 0	P 2	C	
our	rse Objectives: U	pon completion of the course, students will be able:						
1.	To learn the arc	hitectural overview of IoT.				A STATE OF S		
2.	To understand t	he IoT reference architecture and real world design constrai	nts.					
3.	To understand t	he various IoT levels.						
4.	To explore the basics of cloud architecture.							
5.	To gain experience in Raspberry PI and experiment simple IoT application on it.							
UN	IT-I	INTRODUCTION			9)		
	IT-II	IOT ARCHITECTURE, GENERATIONS AND PROTOCOL	*	Fa.		9		
Cha	aracteristics (L2)	IoT (L2) - IoT reference architecture (L2) - First Generation -Advanced Generation (L2) - Description & Characteristics						
	nsors (L3) - Desc	ription & Characteristics (L2). IoT PROTOCOLS AND TECHNOLOGY				9		
Wir		cocols (L3) - BACnet Protocol (L3) -Zigbee Architecture (L2)- cocols (L3) - BACnet Protocol (L3) -Zigbee Architecture (L2)- cucture (L2)-Energy Storage Module (L2)-Power Managem g Module(L2).						
UN	IIT – IV	- IV CLOUD ARCHITECTURE BASICS				9		
		S, PaaS, SaaS(L2)- Development environments for service ud platform in industry(L2).	deve	lopm	ent;	Ama	zor	
UN	NIT-V	IOT PROJECTS ON RASPBERRY PI		9				
Cla	yster libraries (L2 ernal representati	SPBERRY PI (L3) - Creating the sensor project (L3)- Prepa) - Hardware Interacting with the hardware (L3) - Interfaction of sensor values (L2) - Persisting data (L2)- External rigidal sensor data (L3).	ing th	ne ha	rdwa	re (l	_3)	
			тот	AL:	45	PER	10	

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LIST	OF EXPERIMENTS/EXERCISES:
1.	Develop an application for LED Blink and Pattern using Arduino or Raspberry Pi
2.	Develop an application for LED Pattern with Push Button Control using Arduino or Raspberry Pi
3.	Develop an application for LM35 Temperature Sensor to display temperature values using arduino or Raspberry Pi
4.	Develop an application for Forest fire detection end node using Raspberry Pi device and sensor
5.	Develop an application for home intrusion detection web application
6.	Develop an application for Smart parking application using python and Django for web application
-	

TOTAL: 30 PERIODS

OPEN ENDED PROBLEMS / QUESTIONS

Course Specific Open Ended Problems will be solved during teaching. Such problems can be given as Assignments and evaluated as IA only and not for the End Semester Examinations.

	A DETERMINATION OF THE PROPERTY OF THE PROPERT	TOTAL: 75 PERIODS
	e Outcomes: completion of this course the students will be able to:	BLOOM'S Taxonomy
CO1	Understand the various concept of the IoT and their technologies.	L2 - Understand
CO2	Develop the IoT application using different hardware platforms.	L3 - Apply
CO3	Implement the various IoT Protocols.	L3 – Apply
CO4	Understand the basic principles of cloud computing.	L2 - Understand
CO5	Develop and deploy the IoT application into cloud environment.	L3 – Apply
REFE	RENCE BOOKS:	FERMI COLDE STACKS
1.	Arshdeep Bahga, Vijay Madisetti, Internet of Things: A hands-on appr 2015	roach, Universities Press,
2.	Dieter Uckelmann, Mark Harrison, Florian Michahelles (Eds), Architectin Springer, 2011	g the Internet of Things,
3.	Peter Waher, 'Learning Internet of Things', Packt Publishing, 2015	
4.	Ovidiu Vermesan Peter Friess, 'Internet of Things – From Research a Deployment', River Publishers, 2014	
5.	N. Ida, Sensors, Actuators and Their Interfaces: A Multidisciplinary I Scitech Publishers, 202014	Introduction, 2nd Edition
6.	Reese, G. (2009). Cloud Application Architectures: Building Applications Cloud. Sebastopol, CA: O'Reilly Media, Inc. (2009)	and Infrastructure in the
VIDE	O REFERENCES:	
1.	https://www.youtube.com/watch?v=WUYAjxnwjU4&list=PLJ5C 6qdAvB0sOPu3k	G7SHg5mLOQq6bzF-
2.	https://www.youtube.com/watch?v=h0gWfVCSGQQ	
3.	https://www.youtube.com/watch?v=GkD0NjUubWM	
WEB	REFERENCES:	
1.	https://www.ibm.com/topics/internet-of-things	
2.	https://freeeway.com/16-types-of-sensors-used-in-iot/	
3.	https://www.guvi.in/blog/best-iot-project-ideas/	
ONL	NE COURSES:	
1.	https://online.stanford.edu/courses/xee100-introduction-internet-things	S

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- 2. https://onlinecourses.nptel.ac.in/noc22_cs53/preview
- 3. https://www.coursera.org/specializations/iot

Mapping of COs with Pos								
-				Pos				
COs	PO1	PO2	PO3	PO4	PO5	P06		
CO1	1	1	2	1	1	3		
CO2	3	2	1	2	3	2		
CO3 ·	1	1	2	1	3	3		
CO4	2	3	2	1	2	2		
CO5	1	2	1	2	1	1		
Average	1.60	1.80	1.60	1.40	2.00	2.20		



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	ME23CP409	WEB SERVICES AND API DESIGN	Version: 1.0					
	gramme &	M.E. – Computer Science and Engineering CP 3	L T P C 3 0 0 3					
	se Objectives:							
1.	To learn the bas	sics of web service.	500					
2.	. To become familiar with the web services building blocks.							
3.	To learn to work	k with RESTful web services.						
4.	To implement th	ne RESTful web services.						
5.	To understand r	resource oriented architecture.						
UN	IT-I	INTRODUCTION TO WEB SERVICE	9					
Ser	vices: Web Services	vice - Architecture(L1) - Service-Oriented Architecture (SOA)(L1), ces Technology Stack(L1), Logical Architectural View(L2), Deploynes Architectural View(L2).						
UN	IT-II	WEB SERVICE BUILDING BLOCKS	9					
		SDL: WSDL Syntax(L2) - SOAP Binding (L2)- WSDL Imple :: The UDDI API(L1) - Implementations(L2) - The Future of UDDI						
	IT- III	RESTFUL WEB SERVICES	9					
		- HTTP: Documents in Envelopes (L2)- Method Information - Sco						
		ing Architectures - Technologies on the Programmable W						
		Vriting Web Service Clients: The Sample Application(L2) - Mak Processing the Response: XML Parsers(L2) - JSON Parsers(L2): H						
		ade Easy with WADL(L2).	anding Senanzed					
UN	IT – IV	IMPLEMENTATION OF RESTFUL WEB SERVICES	9					
Int	roducing the Sim	ple Storage Service (L1)- Object-Oriented Design of S3(L2) - I	Resources - HTTP					
Res	sponse Codes Res	ource(L2)- URIs - Addressability(L2) - Statelessness - Represent	ations (L3)- Links					
and	d Connectedness	- The Uniform Interface(L2) - Spring Web Services(L2) - Spring	MVC Components					
(L3	s)- Spring Web Flo	ow - A Service Implementation using Spring Data REST(L3).						
UN	IT-V	RESOURCE ORIENTED ARCHITECTURE	9					
		- Addressability (L2)- Statelessness - Representations						
		The Uniform Interface(L2)- Designing Read-Only Resource-O						
		2)- Turning Requirements Into Read-Only Resources (L2)- Figu						
		ata Set into Resources- Name the Resources (L2)- Design Repres	entation(L2)- Link					
the	Resources to Eac	ch Other- The HTTP Response (L2).						

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10

TOTAL: 45 PERIODS

OPEN ENDED PROBLEMS / QUESTIONS

Course Specific Open Ended Problems will be solved during teaching. Such problems can be given as Assignments and evaluated as IA only and not for the End Semester Examinations.

	outcomes: completion of this course the students will be able to:	BLOOM'S Taxonomy				
CO1	Explain how to write XML documents.	L2 - Understand				
CO2	Apply the web service building blocks such as SOAP, WSDL and UDDI.	L3 - Apply				
CO3	Describe the RESTful web services.	L2 - Understand				
CO4	Implement the RESTful web service with Spring Boot MVC.	L3 - Apply				
CO5	Discuss Resource-oriented Architecture.	L2 - Understand				
REFE	RENCE BOOKS:					
1.	Leonard Richardson and Sam Ruby, RESTful Web Services, O'Reilly Media,	2007				
2.	McGovern, et al., "Java Web Services Architecture", Morgan Kaufmann Pub	lishers,2005.				
3.	Lindsay Bassett, Introduction to JavaScript Object Notation, O'Reilly Media,	2015				
4.	Craig Walls, "Spring in Action, Fifth Edition", Manning Publications, 2018					
5.	Raja CSP Raman, Ludovic Dewailly, "Building A RESTful Web Service Publishing, 2018.					
6	Bogunuva Mohanram Balachandar, "Restful Java Web Services, Third Edit					
6.	to designing and building RESTful APIs using Java", Ingram short title, 3rd					
7.	Mario-Leander Reimer, "Building RESTful Web Services with Java EE 8: RESTful web services with the Java EE 8 API", Packt publishing, 2018	Create modern				
VIDE	O REFERENCES:					
1.	https://www.youtube.com/watch?v=0CSyIBHQy9g					
2.	https://www.youtube.com/watch?v=BZi44GOD8kY					
3.	https://www.youtube.com/channel/UCSJbGtTIrDami-tDGPUV9-w					
WEB	REFERENCES:	apholic metalogicals is				
1.	https://restfulapi.net/					
2.	https://learn.microsoft.com/en-us/azure/architecture/best-practices/api-de	esign				
3.	https://apiblueprint.org/					
	INE COURSES:					

https://www.coursera.org/learn/api-design-google-cloud-apigee 1.

https://www.udemy.com/course/rest-api-design-the-complete-guide/ 2.

Mapping of COs with POs								
				POs		A to a house of the		
COs	PO1	PO2	РО3	PO4	PO5	P06		
CO1	1	3	3	_				
CO2	1	ERDIEL-IZAL	3	3	1	2		
CO3	SCHEETELWN :	3	3,			S		
CO4	1	Rous-1 Mild	2	3	1	2		
CO5	1	-	1	-	1 2 2 2 2 2 2 2 2	6 13 ST - 18		
Average	1	3	2.4	3	1	2		

11

Board of Studies M.E. / M.Tech. Regulations 2023 Faculty of CSE & IT

Knowledge Institute of Technology KIOT Campus, Kakapalayam, Salem-637 504

	ME23CP410	DATA VISUALIZATION TECHNIQUES	Version: 1.0	
Prog Brar	ramme & nch	M.E. – Computer Science and Engineering CP	L T P (
Cour	se Objectives:			
1.	To develop skills	s to both design and critique visualizations.		
2.	To introduce vis	sual perception and core skills for visual analysis.		
3.	To understand t	echnological advancements of data visualization.	Masad (£G5.	
4.	To understand v	various data visualization techniques.	resignas j. acg.o.	
5.	To understand t	the methodologies used to visualize large data sets.		
UNI	IT-I	INTRODUCTION AND DATA FOUNDATION	9	
Pse	udo code Convent	between Visualization and Other Fields(L1) -The Visualization cions(L3) - The Scatter plot(L3). Data Foundation (L2)- Types of Decords (L2)- Data Pre-processing(L2) - Data Sets(L3).		
	UNIT-II FOUNDATIONS FOR VISUALIZATION			
		L2) - Semiology of Graphical Symbols (L2)- The Eight Visual \	9 (ariables (1.2)	
		e – Taxonomies(L2) - Experimental Semiotics based on Perce) – A Model of Perceptual Processing(L2).	ption Gibson's	
	IT- III	VISUALIZATION TECHNIQUES	9	
Data Data Visu	a - Combining Te a -Visualization o ualization Multivar	imensional Data - Two-Dimensional Data - Three Dimensional Dechniques(L2). Geospatial Data : Visualizing Spatial Data - Visualif Line Data (L3)- Visualization of Area Data - Other Issues in Grate Data : Point-Based Techniques - Line Based Techniques(L3) ombinations of Techniques - Trees Displaying Hierarchical St	ization of Point Geospatial Data - Region-Based	
Gra	phics and Networ	ks- Displaying Arbitrary Graphs/Networks(L2).		
UN	IT – IV	INTERACTION CONCEPTS AND TECHNIQUES	9	
Spa Tex	ce Model - Singl t Visualizations	Visualization: Introduction - Levels of Text Representations(L1) e Document Visualizations(L2) -Document Collection Visualization Interaction Concepts: Interaction Operators(L2) - Interaction	ons – Extended Operands and	
Spa	ce (L3)- Attribut	ed Framework. Interaction Techniques: Screen Space(L3) - Object e Space- Data Structure Space (L2)- Visualization Structure (L - Interaction Control(L2).		
UNI	IT-V	RESEARCH DIRECTIONS IN VISUALIZATIONS	9	
Data		risualizations (L1)- Problems in designing effective Visualizations gnition, Perception, and Reasoning(L2). Issues of System Desations(L2).		
mar	uware and Applica	ations(LZ).		

TOTAL: 45 PERIODS

KIOT

OPEN ENDED PROBLEMS / QUESTIONS

Course Specific Open Ended Problems will be solved during teaching. Such problems can be given as Assignments and evaluated as IA only and not for the End Semester Examinations.

	e Outcomes: completion of this course the students will be able to:	BLOOM'S Taxonomy
CO1	Visualize the objects in different dimensions.	L3 - Apply
CO2	Design and process the data for Visualization.	L3 - Apply
CO3	Apply the visualization techniques in physical sciences, computer science, applied mathematics and medical sciences.	L3 – Apply
CO4	Apply the virtualization techniques for research projects.	L3 – Apply
CO5	Identify appropriate data visualization techniques given particular requirements imposed by the data.	L2 - Understand
REFE	RENCE BOOKS:	
1.	Matthew Ward, Georges Grinstein and Daniel Keim, "Interactive Foundations, Techniques, Applications", 2010.	Data Visualization
2.	Colin Ware, "Information Visualization Perception for Design", 4th edition Publishers, 2021.	
3.	Robert Spence "Information visualization – Design for interaction", Pear Edition, 2007	rson Education, 2nd
4.	Alexandru C. Telea, "Data Visualization: Principles and Practice," A. K. Pete	rs Ltd, 2008.
VIDE	O REFERENCES:	
1.	https://www.youtube.com/user/tableausoftware	
2.	https://www.youtube.com/user/currankelleher	
3.	https://www.youtube.com/user/GoogleDevelopers	
WEB	REFERENCES:	
1.	https://www.datavisualizationsociety.org/	148-44441
2.	https://www.data-to-viz.com/	
3.	https://www.datavisualizationsociety.org/	
ONLI	NE COURSES:	
1.	https://www.storytellingwithdata.com/	学表一 等新地
2.	https://visualisingdata.com/	
3.	https://github.com/hal9ai/awesome-dataviz	

		Мар	ping of COs w	ith POS MAN	ARRIGED	
				POs	W.	
COs	PO1	PO2	PO3	PO4	PO5	P06
CO1	3	1	2	2	1	2
CO2	2	1	2 ,	3	2	2
CO3	1	-	2	2	1	1
CO4	3	1	3	3	2	2
CO5	2	1	3	2	2	2
Average	2.20	1	2.40	2.40	1.40	1.60

CHARPERSON Board of Studies

M.E. / M.Tech. Regulations 2023

М	E23CP411	COMPILER OPTIMIZATION TECHNIQUES		Vers	sion	1.0	
rogr rand	ramme &	M F - Computer Science and Engineering	CP 3	L 3	T 0	P 0	
ours	e Objectives:						
1.	To understand	the optimization techniques used in compiler design.	30.3				
2.	2. To be aware of the various computer architectures that support parallelism.						
3. To become familiar with the theoretical background needed for code optimization.							
4.	To understand	the techniques used for identifying parallelism in a sequential p	prog	gram			
5.	To learn the va	rious optimization algorithms.					
UNI	T-I	INTRODUCTION			9)	
Prog Over	ramming Lang	The Science of Building a Compiler(L2) – Applications of Conguage Basics(L2) - The Lexical Analyser Generator(L3) -Pars Blocks and Flow Graphs(L2) - Optimization of Basic Blocks(L2)	ser	Gen	erati	or(L3	3)
Prog Over	ramming Lang view of Basic I	guage Basics(L2) - The Lexical Analyser Generator(L3) -Pars Blocks and Flow Graphs(L2) - Optimization of Basic Blocks(L2)	ser	Gen	erati	or(L3	3)
Progr Over of Op	ramming Lang view of Basic I ptimization(L2)	puage Basics(L2) - The Lexical Analyser Generator(L3) -Pars Blocks and Flow Graphs(L2) - Optimization of Basic Blocks(L2) INSTRUCTION-LEVEL PARALLELISM	ser) - I	Gen Princ	erato iple	or(L3 Soui	3) rce
Programmer Processing	ramming Lang rview of Basic I ptimization(L2) T-II essor Architect	Blocks and Flow Graphs(L2) - Optimization of Basic Blocks(L2) INSTRUCTION-LEVEL PARALLELISM Sures(L1) - Code-Scheduling Constraints(L2) - Basic-Block Sch	ser) - I	Gen Princ	erato	Sour	3) ce
Programmer Proce	ramming Lang view of Basic I ptimization(L2) T-II essor Architect e Scheduling	puage Basics(L2) - The Lexical Analyser Generator(L3) -Pars Blocks and Flow Graphs(L2) - Optimization of Basic Blocks(L2) INSTRUCTION-LEVEL PARALLELISM cures(L1) - Code-Scheduling Constraints(L2) - Basic-Block Sch (L2)- Advanced code motion techniques(L3) - Interact oftware Pipelining(L1).	ser) - I	Gen Princ	erato	Sour	3) ce
Programmer Proces	ramming Lang rview of Basic I ptimization(L2) T-II essor Architect e Scheduling edulers(L1)- So	Blocks and Flow Graphs(L2) - Optimization of Basic Blocks(L2) INSTRUCTION-LEVEL PARALLELISM Fures(L1) - Code-Scheduling Constraints(L2) - Basic-Block Scheduling Constraints(L2) - Interact of Stware Pipelining(L1).	ser) - I nedu	Gen Princ	eratoriple (L2)	Sour	B)
Programmer Processing Codes	ramming Lang rview of Basic I ptimization(L2) T-II essor Architect e Scheduling edulers(L1)- So T-III	puage Basics(L2) - The Lexical Analyser Generator(L3) -Pars Blocks and Flow Graphs(L2) - Optimization of Basic Blocks(L2) INSTRUCTION-LEVEL PARALLELISM cures(L1) - Code-Scheduling Constraints(L2) - Basic-Block Sch (L2)- Advanced code motion techniques(L3) - Interact oftware Pipelining(L1).	nedution	Gen Prince uling wit	erato	Sour Sour)-Glo Dyna	3) rce
Programmer of Operation of Oper	ramming Lang rview of Basic I ptimization(L2) T-II essor Architect e Scheduling edulers(L1)- So T-III c Concepts (L2)	puage Basics(L2) - The Lexical Analyser Generator(L3) -Pars Blocks and Flow Graphs(L2) - Optimization of Basic Blocks(L2) INSTRUCTION-LEVEL PARALLELISM cures(L1) - Code-Scheduling Constraints(L2) - Basic-Block Sch (L2)- Advanced code motion techniques(L3) - Interact oftware Pipelining(L1). OPTIMISING FOR PARALLELISM AND LOCALITY-THEO	nedution	Gen Prince uling wit	erato	Sour Sour)-Glo Dyna	B)
Programmer of Operation of Oper	ramming Lang rview of Basic I ptimization(L2) T-II essor Architect e Scheduling edulers(L1)- So T-III c Concepts (L2)	puage Basics(L2) - The Lexical Analyser Generator(L3) -Parsible Blocks and Flow Graphs(L2) - Optimization of Basic Blocks(L2) INSTRUCTION-LEVEL PARALLELISM Fures(L1) - Code-Scheduling Constraints(L2) - Basic-Block Scheduling Constraints(L2) - Basic-Block Scheduling Constraints(L3) - Interaction of the Pipelining(L1). OPTIMISING FOR PARALLELISM AND LOCALITY-THEO	nedution	Gen Prince uling wit	erate (L2) (L2) (L2) (L2) (L2) (L2) (L2) (L2)	Sour Sour)-Glo Dyna	B)
Programmer of Operation of Oper	ramming Lang rview of Basic I ptimization(L2) T-II essor Architect e Scheduling edulers(L1)- So T-III c Concepts (L2 a Reuse(L2)- Ar T-IV	puage Basics(L2) - The Lexical Analyser Generator(L3) -Pars Blocks and Flow Graphs(L2) - Optimization of Basic Blocks(L2) INSTRUCTION-LEVEL PARALLELISM cures(L1) - Code-Scheduling Constraints(L2) - Basic-Block Scheduling Constraints(L2) - Basic-Block Scheduling Constraints(L2) - Interact of tware Pipelining(L1). OPTIMISING FOR PARALLELISM AND LOCALITY-THEO OPTIMISING FOR PARALLELISM AND LOCALITY - Affine Tray data dependence Analysis(L3). OPTIMISING FOR PARALLELISM AND LOCALITY -	nedution	Gen Prince Uling with	erate (L2) (L2) (Index)	Sour Sour) -Glo	bba mi
Programmer of Operation of Oper	ramming Lang rview of Basic I ptimization(L2) T-II essor Architect e Scheduling edulers(L1)- So T-III c Concepts (L2 n Reuse(L2)- Ar T-IV ing Synchronis	puage Basics(L2) - The Lexical Analyser Generator(L3) -Parsible Blocks and Flow Graphs(L2) - Optimization of Basic Blocks(L2) INSTRUCTION-LEVEL PARALLELISM Eures(L1) - Code-Scheduling Constraints(L2) - Basic-Block Sche(L2) - Advanced code motion techniques(L3) - Interact of tware Pipelining(L1). OPTIMISING FOR PARALLELISM AND LOCALITY-THEO D) - Matrix-Multiply: An Example - Iteration Spaces(L2) - Affine Gray data dependence Analysis(L3). OPTIMISING FOR PARALLELISM AND LOCALITY - APPLICATION	nedution	Gen Prince Uling with	erate (L2) (L2) (Index)	Sour Sour) -Glo	bba mi
Programmer of Operation of Oper	ramming Lang rview of Basic I ptimization(L2) T-II essor Architect e Scheduling edulers(L1)- So T-III c Concepts (L2 a Reuse(L2)- Ar T-IV ing Synchronis lining - Locality	Blocks and Flow Graphs(L2) - Optimization of Basic Blocks(L2) INSTRUCTION-LEVEL PARALLELISM Fures(L1) - Code-Scheduling Constraints(L2) - Basic-Block Scheduling Constraints(L2) - Basic-Block Scheduling Constraints(L3) - Interact of tware Pipelining(L1). OPTIMISING FOR PARALLELISM AND LOCALITY-THEO OPTIMISING FOR PARALLELISM AND LOCALITY-THEO OPTIMISING FOR PARALLELISM AND LOCALITY - Affine Fray data dependence Analysis(L3). OPTIMISING FOR PARALLELISM AND LOCALITY - APPLICATION Station(L2) - Free Parallelism (L2)- Synchronisation Between Forces	nedution	Gen Prince Uling with	erate (L2) (L2) (Index)	Souri Souri	bba mi
Programmer of Operation of Oper	ramming Lang rview of Basic I ptimization(L2) T-II essor Architect e Scheduling edulers(L1)- So T-III c Concepts (L2 n Reuse(L2)- Ar T-IV ing Synchronis lining - Locality T-V	Blocks and Flow Graphs(L2) - Optimization of Basic Blocks(L2) INSTRUCTION-LEVEL PARALLELISM Bures(L1) - Code-Scheduling Constraints(L2) - Basic-Block Scheduling Constraints(L2) - Basic-Block Scheduling Constraints(L3) - Interaction of Basic Blocks(L3) - Interaction of Basic B	nedution PRY	Gen Prince Uling with	eration (L2)	Souri Souri) - Glo Dyna) - Glo Sos(L2	B) Db m

Context- Sensitive Pointer-Analysis(L2) - Datalog Implementation by Binary Decision Diagrams(L3).



TOTAL: 45 PERIODS

OPEN ENDED PROBLEMS / QUESTIONS

Course Specific Open Ended Problems will be solved during teaching. Such problems can be given as Assignments and evaluated as IA only and not for the End Semester Examinations.

	e Outcomes: completion of this course the students will be able to:	BLOOM'S Taxonomy
CO1	Design and implement techniques used for optimization by a compiler.	L3 - Apply
CO2	Modify the existing architecture that supports parallelism.	L3 - Apply
CO3	Modify the existing data structures of an open source optimising compiler.	L3 - Apply
CO4	Design and implement new data structures and algorithms for code optimization.	L3 - Apply
CO5	Critically analyse different data structures and algorithms used in the building of an optimising compiler.	L4 - Analyze
REFE	RENCE BOOKS:	
1.	Charles N, Ron K Cytron, Richard J LeBlanc Jr., "Crafting a Compiler", Pearso	n Education, 2010.
2.	Torbengidius Mogensen, "Basics of Compiler Design", Springer, 2011.	
3.	Alfred V Aho, Monica S Lam, Ravi Sethi, Jeffrey D Ullman, "Compilers - Prand Tools", Second Edition, Pearson Education 2007.	rinciples, Techniques
4.	Randy Allen, Ken Kennedy, Optimizing Compilers for Modern Architectures, I	First Edition ,2001.
5.	Steven S. Muchnick, "Advanced Compiler Design and Implementation", Publishers - Elsevier Science, India, 2007	
6.	John Hopcroft, Rajeev Motwani, Jeffrey Ullman, "Introduction to Automata and Computation", Third Edition, Pearson Education, 2007.	Theory Languages
VIDE	O REFERENCES:	
1.	https://godbolt.org/	
2.	https://learn.microsoft.com/en-us/cpp/build/reference/optimization-compiler	
	WEB REFERENCES:	
1.	https://compileroptimizations.com/	
	A CONTROL OF THE PROPERTY OF T	

https://compileroptimizations.com/
 https://community.st.com/t5/stm32-mcus-products/compiler-optimization-problems/td-p/542634

ONLINE COURSES:

KIOT

- 1. https://nptelvideos.com/course.php?id=439
- 2. https://www.quora.com/Where-can-I-find-a-free-online-compiler-for-C-language

CHAIRPERSON

Board of Studies

Faculty of CSE & IT

Knowledge Institute of Technology
KIOT Campus, Kakapalayam,

Mapping of COs with POs								
			ANTENNE DETAILS	POs				
COs	PO1	PO2	РО3	P04	PO5	P06		
CO1	2	2	2	3	2	2		
CO2			3	3		3		
CO3	3		3	+ 3		3		
CO4	3	3	3	3				
CO5		3	3	3	3	THE PARTY OF THE P		
Average	2.6	2.6	2.8	3	2.5	2.6		
		1-Lc	w, 2 -Medium	, 3-High	2000 - 200 English W			



Board of Studies
Faculty of CSE & IT
Knowledge Institute of Technology
KIOT Campus, Kakapalayam,
Salem-637 504

ME23CP412		ME23CP412 ROBOTICS					
	gramme &	M.E. – Computer Science and Engineering	CP 3	L 3	T 0	P 0	С 3
oui	se Objectives:				***		
1.	To introduce the	e concepts of robotic systems.					
2.	To understand t	he concepts of instrumentation and control related to robot	tics.				
3.	To understand t	he kinematics and dynamics of robotics.					
4.	To learn the art	ificial intelligence techniques and task planning for robotics	s. ·				
5.	To explore robo	tics in industrial applications.					
UN	IT-I	INTRODUCTION TO ROBOTICS				9	
	guages(L2)- Robo sensor(L2).	tic sensors(L2)- proximity and range sensors(L2), ultrasor	nic sens	or(L2	2), to	uch	and
O LO			7	The same of			
Kin par	ameters(L2), For	ROBOT KINEMATICS AND DYNAMICS Translation and Rotation Representation(L2), Coordinate ward and inverse kinematics(L2), Jacobian(L2), Dynamic 2), Equations of motion using Euler-Lagrange formula	Model	ling:	ation	vard	an
Kin par inv	ematic Modelling: ameters(L2), For erse 'dynamics(L2 nulation(L2).	Translation and Rotation Representation(L2), Coordinate ward and inverse kinematics(L2), Jacobian(L2), Dynamic 2), Equations of motion using Euler-Lagrange formula	Model	ling:	Forw Newto	(L2), vard on E	an
Kin par inve fore	ematic Modelling: ameters(L2), For erse dynamics(L2 nulation(L2).	Translation and Rotation Representation(L2), Coordinate ward and inverse kinematics(L2), Jacobian(L2), Dynamic 2), Equations of motion using Euler-Lagrange formula ROBOTICS CONTROL	ation(L2	ling: 2), N	Forw Forw Newto	(L2), vard on E	an
Kin par inve form UN Co	ematic Modelling: ameters(L2), Foregree dynamics(L2) nulation(L2). IT-III ntrol of robot matems(L2), single-	Translation and Rotation Representation(L2), Coordinate ward and inverse kinematics(L2), Jacobian(L2), Dynamic 2), Equations of motion using Euler-Lagrange formula	ation(L2	ling: 2), N	Forw Newto	(L2), vard on E	an
Kin par nve form UN Con sys	ematic Modelling: ameters(L2), Foregree dynamics(L2) nulation(L2). IT-III ntrol of robot matems(L2), single-	ranslation and Rotation Representation(L2), Coordinates ward and inverse kinematics(L2), Jacobian(L2), Dynamic (L2), Equations of motion using Euler-Lagrange formula (L2), Equations (L2) - state equations(L2) - constant solutions (L2) - computed (L2) - c	ation(L2	ling: 2), N	Forw Newtonear f	(L2), vard on E	an
Kin par inve form UN Co sys str	ematic Modelling: ameters(L2), Foregree dynamics(L2) nulation(L2). IT-III ntrol of robot matems(L2), single- ucture control and	ROBOTICS CONTROL anipulator(L2) - state equations(L2) - computed impedance control(L2).	ation(L2 ons (L2 d torque	ling: 2), N)-line con	Forw Newton ear f	(L2), vard on E 9 feedb varia	an
Kin par inve form Col sys str UN Art	ematic Modelling: ameters(L2), Foregree dynamics(L2) anulation(L2). IT-III atrol of robot matems(L2), single- acture control and IT-IV ficial Intelligence	ROBOTICS CONTROL anipulator(L2) - state equations(L2) - computed dimpedance control(L2). ROBOTICS CONTROL anipulator(L2) - pD gravity control(L2) - computed dimpedance control(L2). ROBOT INTELLIGENCE AND TASK PLANNING	ons (L2	ling: 2), N)-line con	ear fatrol,	yard on E 9 Feedb varia 9 eans	an ule accabl
Kin par inverse invers	ematic Modelling: ameters(L2), Foregree dynamics(L2) anulation(L2). IT-III atrol of robot matems(L2), single- acture control and IT-IV ficial Intelligence I analysis(L2) -p	ROBOTICS CONTROL anaipulator(L2) - state equations(L2) - computed impedance control(L2). ROBOTICS CONTROL anaipulator(L2) - pD gravity control(L2) - computed impedance control(L2). ROBOT INTELLIGENCE AND TASK PLANNING (L1) - techniques (L2) - search problem reduction (L2) - p	ons (L2	ling: 2), N)-line con	ear fatrol,	yard on E 9 Feedb varia 9 eans	an ule ac abl
Kin par nvo	ematic Modelling: ameters(L2), Forerse dynamics(L2) nulation(L2). IT-III atrol of robot matems(L2), single- cucture control and IT-IV ficial Intelligence I analysis(L2) -p nning - AI in robo	Translation and Rotation Representation(L2), Coordinate ward and inverse kinematics(L2), Jacobian(L2), Dynamic (L2), Equations of motion using Euler-Lagrange formula (L2), Equations of motion using Euler-Lagrange formula (L2), Equations (L2) - state equations(L2) - constant solution (L2) - pp gravity control(L2) - computed (L2) - pp gravity control(L2) - computed (L2) - manipulator(L2). ROBOT INTELLIGENCE AND TASK PLANNING (L1) - techniques (L2) - search problem reduction (L2) - problem solving(L2) - robot learning - task planning (L2) (L2) atics and Knowledge Based Expert System in robotics(L2) INDUSTRIAL ROBOTICS	ons (L2 d torque	ling: 2), N)-line con e log prob	ear fatrol,	(L2), vard on E 9 feedb varia 9 eans s in	an cule acabl ar tas
Kin par inversion of the control of	ematic Modelling: ameters(L2), Foregree dynamics(L2) IT-III ntrol of robot matems(L2), single- fucture control and IT-IV ficial Intelligence I analysis(L2) -p Inning - AI in robot IT-V pot cell design ar	ROBOTICS CONTROL anipulator(L2) - state equations(L2) - computed impedance control(L2). ROBOTICS CONTROL anipulator(L2) - pD gravity control(L2) - computed impedance control(L2). ROBOTINTELLIGENCE AND TASK PLANNING (L1) - techniques (L2) - search problem reduction (L2) - problem solving(L2) - robot learning - task planning (L2) atics and Knowledge Based Expert System in robotics(L2) INDUSTRIAL ROBOTICS and control (L2) - cell layouts - multiple robots and machine	ons (L2 di torque)-line con	ear fatrol,	(L2), vard on E 9 eedb varia eans s in	ancal
Kinn parrinversion vin Consystem Struk Art end pla	ematic Modelling: ameters(L2), Foregree dynamics(L2) amulation(L2). IT-III atrol of robot matems(L2), single- acture control and IT-IV ficial Intelligence I analysis(L2) -p aning - AI in robot IIT-V oot cell design ar design(L2) - wo	ROBOTICS CONTROL anipulator(L2) - state equations(L2) - computed impedance control(L2). ROBOTICS CONTROL anipulator(L2) - state equations(L2) - computed impedance control(L2). ROBOTINTELLIGENCE AND TASK PLANNING (L1) - techniques (L2) - search problem reduction (L2) - problem solving(L2) - robot learning - task planning (L2) atics and Knowledge Based Expert System in robotics(L2) INDUSTRIAL ROBOTICS and control (L2) - cell layouts - multiple robots and machinark cell control - interlocks(L2) - error detection deduction	ons (L2 d torque	ing: 2), N)-line con e log prob	ear fatrol,	(L2), vard on E 9 Feedb varia 9 eans s in 9 2) - 1	an a
Kinn parrinversion vin Consystem of Consyste	ematic Modelling: ameters(L2), Foregree dynamics(L2) IT-III Introl of robot matems(L2), single- fucture control and IT-IV ficial Intelligence I analysis(L2) -p Inning - AI in robot IIT-V oot cell design and design(L2) - wo controller - robot	ROBOTICS CONTROL anipulator(L2) - state equations(L2) - computed impedance control(L2). ROBOTICS CONTROL anipulator(L2) - pD gravity control(L2) - computed impedance control(L2). ROBOTINTELLIGENCE AND TASK PLANNING (L1) - techniques (L2) - search problem reduction (L2) - problem solving(L2) - robot learning - task planning (L2) atics and Knowledge Based Expert System in robotics(L2) INDUSTRIAL ROBOTICS and control (L2) - cell layouts - multiple robots and machine	ons (L2 d torque	ing: 2), N)-line con e log prob	ear fatrol,	(L2), vard on E 9 Feedb varia 9 eans s in 9 2) - 1	an fule
Kin par inversion of the column of the colum	ematic Modelling: ameters(L2), Foregree dynamics(L2) amulation(L2). IT-III atrol of robot matems(L2), single- acture control and IT-IV ficial Intelligence I analysis(L2) -p aning - AI in robot IIT-V oot cell design ar design(L2) - wo	ROBOTICS CONTROL anipulator(L2) - state equations(L2) - computed impedance control(L2). ROBOTICS CONTROL anipulator(L2) - state equations(L2) - computed impedance control(L2). ROBOTINTELLIGENCE AND TASK PLANNING (L1) - techniques (L2) - search problem reduction (L2) - problem solving(L2) - robot learning - task planning (L2) atics and Knowledge Based Expert System in robotics(L2) INDUSTRIAL ROBOTICS and control (L2) - cell layouts - multiple robots and machinark cell control - interlocks(L2) - error detection deduction	ons (L2 ons (L2 ons (L2 d torque oredicate	or ling: 2), Note that it is a second or line to the log or line to t	ear fatrol, ic moderns ce(L2 ery(L2 ot ar	(L2), vard on E 9 eans s in 9 (L2) - 1	ande
Kinnoar nver form VIN Consystem VIN Art end pla Col col col	ematic Modelling: ameters(L2), Foregree dynamics(L2) IT-III Introl of robot matems(L2), single- fucture control and IT-IV ficial Intelligence I analysis(L2) -p Inning - AI in robot IIT-V oot cell design and design(L2) - wo controller - robot	ROBOTICS CONTROL anipulator(L2) - state equations(L2) - computed impedance control(L2). ROBOTICS CONTROL anipulator(L2) - state equations(L2) - computed impedance control(L2). ROBOTINTELLIGENCE AND TASK PLANNING (L1) - techniques (L2) - search problem reduction (L2) - problem solving(L2) - robot learning - task planning (L2) atics and Knowledge Based Expert System in robotics(L2) INDUSTRIAL ROBOTICS and control (L2) - cell layouts - multiple robots and machinark cell control - interlocks(L2) - error detection deduction	ons (L2 ons (L2 ons (L2 d torque oredicate	or ling: 2), Note that it is a second or line to the log or line to t	ear fatrol,	(L2), vard on E 9 eans s in 9 (L2) - 1	an and an arrangement arrangem

OPEN ENDED PROBLEMS/QUESTIONS

Course Specific Open Ended Problems will be solved during teaching. Such problems can be given as Assignments and evaluated as IA only and not for the End Semester Examinations.

ASSIGI	imerits and evaluated as IA only and not to the Line Line	TOTAL:45 PERIODS
ourse	e Outcomes: completion of this course the students will be able to:	BLOOM'S Taxonomy
CO1	Describe the fundamentals of robotics.	L2 - Understand
CO2	Understand the concept of kinematics and dynamics in robotics.	L2 - Understand
CO3	Discuss the robot control techniques.	L2 - Understand
CO4	Explain the basis of intelligence in robotics and task planning.	L2 - Understand
CO5	Discuss the industrial applications of robotics.	L2 - Understand
	PENCE BOOKS:	
1.	Mikell. P. Groover, Michell Weis, Roger. N. Nagel, Nicolous G.Odrey	
2.	Reza N.Jazar, 'Theory of Applied Robotics Kinematics, Dynamics and (Indian Reprint, 2010.	sorter or y Springer y
3.	K.S.Fu, R.C.Gonzalez and C.S.G.Lee, 'Robotics Control, Sensing, Vision McGraw Hill, 2 nd Reprint,2008	
4.	Richard D. Klafter, Thomas A. Chmielewski, Michael Negin, 'Robo Integrated Approach', PHI Learning, New Delhi, 2009.	
5.	John J. Craig, 'Introduction to Robotics (Mechanics and Control)', Edition, 2004.	Addison-Wesley, 2"
VIDE	O REFERENCES:	
1.	https://www.youtube.com/playlist?list=PLGs0VKk2DiYxkoe2XNxDvVHqL5	XG4dMWi
2.	https://www .TED Talks on Robotics/	
WEB	REFERENCES:	
1.	https://openai.com/	
2.	https://www.therobotreport.com/	
3.	https://www.ieee-ras.org/	
ONL	INE COURSES:	
1.	https://github.com/topics/robotics	
2.	https://www.coursera.org/courses?query=robotics	

Mapping of COs with POs								
POs								
COs	PO 1	PO2	РО3	P04	PO 5	PO 6		
CO1	1	3	3		2	<u>-</u>		
CO2	1	2	3	2	1	1		
CO3	1	2	-	3	3	2		
CO4	2	1.3 22 <u>-</u> 2016	3		2			
CO5	1	-	-	3	3	3		
Average	1.2	2.3	3	2.7	2.2	2		
		1-Lo	w, 2 -Medium	, 3-High				

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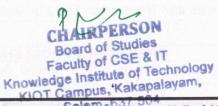
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KIOT Campus, Kakapalayam,
Salem-637 504

	ME23CP413	DEVOPS AND MICRO SERVICES	Version: 1.0
	ramme &	M.E. – Computer Science and Engineering CI 5	
ours	se Objectives:		
1.		sic concepts and terminology of DevOps.	
2.		dge on Devops platform.	
3.		building and deployment of code.	
4.		vith DevOps automation tools.	
5.	To learn basics	And the second s	
	T – I	INTRODUCTION	9
		g(L1) - traditional and Agile process models(L2) - DevC)ps -Definition(L1)
		os life cycle process(L2) - need for DevOps(L2) -Barriers (L1).	
			9
	T – II	DEVOPS PLATFORM AND SERVICES	
Cloud	d as a platform	- IaaS, PaaS, SaaS (L2)- Virtualization(L3) - Containers (L2	2)-Supporting Multiple
ata	Centres(L1) -	Operation Services(L2) - Hardware provisioning- software	Provisioning (L2)- I
ervi	ces - SLA - c	capacity planning(L3) - security - Service Transition(L2)	- Service Operation
	epts(L2).		
COLIC	cpts(tz).		
-	IT – III	BUILDING, TESTING AND DEPLOYMENT	9
UNI	IT – III		
UN I	IT – III oservices archite	ecture(L2) - coordination model (L2)- building and testing	ng (L3)- Deploymer
UN3 Micro	IT - III Diservices archite line(L2) - Develo	ecture(L2) - coordination model (L2)- building and testing properties and Pre-commit Testing (L2)-Build and Integration Te	ng (L3)- Deploymer esting(L3) - continuou
UNI Micro	IT - III Diservices archite line(L2) - Develo	ecture(L2) - coordination model (L2)- building and testing property and Pre-commit Testing (L2)-Build and Integration Testing (L2)- security - Resources to be Protected(L2) - Identity Management	ng (L3)- Deployment esting(L3) - continuou anagement (L2).
Micro pipel integ	IT - III Diservices archite line(L2) - Developration - monitor IT - IV	pecture(L2) - coordination model (L2)- building and testing per	ng (L3)- Deployment sting(L3) - continuou anagement (L2).
Micro pipel integ UN:	oservices archite line(L2) - Develo gration - monitor IT - IV astructure Autom	pecture(L2) - coordination model (L2)- building and testing per	ng (L3)- Deployment sting(L3) - continuou anagement (L2).
Micro pipel integ	oservices archite line(L2) - Develo gration - monitor IT - IV astructure Autom	pecture(L2) - coordination model (L2)- building and testing per	ng (L3)- Deployment esting(L3) - continuou anagement (L2). 9 mation (L2)-
Micro pipel integ UN: Infra Perfo	oservices archite line(L2) - Develo gration - monitor IT - IV astructure Autom ormance Manage	pecture(L2) - coordination model (L2)- building and testing per	ng (L3)- Deployment esting(L3) - continuous anagement (L2). 9 mation (L2)-
Micro pipel integ UN: Infra Perfo UN:	oservices archite line(L2) - Develor gration - monitor IT - IV astructure Autom ormance Manage IT - V ps(L2) - Definit	pecture(L2) - coordination model (L2)- building and testing per	ng (L3)- Deployment esting(L3) - continuous anagement (L2). 9 mation (L2)-
Micro pipel nteg UN: Infra Perfo UN:	oservices archite line(L2) - Develor gration - monitor IT - IV astructure Autom ormance Manage IT - V ps(L2) - Definit	pecture(L2) - coordination model (L2)- building and testing per	ng (L3)- Deployment esting(L3) - continuous anagement (L2). 9 mation (L2)- 9 ng to production(L2)
Micro pipel integ UN: Infra Perfo UN:	oservices archite line(L2) - Develor gration - monitor IT - IV astructure Autom ormance Manage IT - V ps(L2) - Definit	pecture(L2) - coordination model (L2)- building and testing per	ng (L3)- Deployment esting(L3) - continuous anagement (L2). 9 mation (L2)-
Micro pipel integ UN: Infra Perfo UN: MLO	oservices archite line(L2) - Develor gration - monitor IT - IV astructure Autom ormance Manage IT - V ps(L2) - Definit el Governance(L	pecture(L2) - coordination model (L2)- building and testing personnel person	ng (L3)- Deployment esting(L3) - continuous anagement (L2). 9 mation (L2)- 9 ng to production(L2)
Micropipel integration of the control of the contro	oservices archite line(L2) - Develor gration - monitor IT - IV astructure Autom ormance Manage IT - V ps(L2) - Definit el Governance(L	pecture(L2) - coordination model (L2)- building and testing per	ng (L3)- Deployment esting(L3) - continuous anagement (L2). 9 mation (L2)- 9 ng to production(L2)
Micro pipel nteg un: Infra Perfo UN: MLO Mod	oservices archite line(L2) - Develor gration - monitor IT - IV estructure Autom ormance Manage IT - V ps(L2) - Definit el Governance(L TOF EXPERIME Creating a repository,	pecture(L2) - coordination model (L2)- building and testing personnel person	ges into a Git
Micropipel integration of the control of the contro	oservices archite line(L2) - Develor gration - monitor IT - IV estructure Autom ormance Manage IT - V ps(L2) - Definit el Governance(L T OF EXPERIME Creating a repository, Installing D	precture(L2) - coordination model (L2)- building and testing properties and Pre-commit Testing (L2)-Build and Integration Testing (L2)- security - Resources to be Protected(L2) - Identity M. DEVOPS AUTOMATION TOOLS ation(L2)- Configuration Management(L2) - Deployment Autoroment(L2) - Log Management (L2)-Monitoring(L2). MLOPS ion(L1) - Challenges (L1) - Developing Models(L2) - Deploying Proceeding (L3). NTS/EXERCISES: new Git repository, cloning existing repository, Checking change Pushing changes to a Git remote, Creating a Git branch. Docker container on windows/Linux, issuing docker commands.	ges into a Git
Micropipel integration of the control of the contro	oservices archite line(L2) - Develor gration - monitor IT - IV astructure Autom ormance Manage IT - V ps(L2) - Definit el Governance(L TOF EXPERIME Creating a repository, Installing De Building De	pecture(L2) - coordination model (L2)- building and testing perment and Pre-commit Testing (L2)-Build and Integration Testing (L2)- security - Resources to be Protected(L2) - Identity M. DEVOPS AUTOMATION TOOLS ation(L2)- Configuration Management(L2) - Deployment Autoroment(L2) - Log Management (L2)-Monitoring(L2). MLOPS ion(L1) - Challenges (L1) - Developing Models(L2) - Deploying Position (L3). NTS/EXERCISES: new Git repository, cloning existing repository, Checking change Pushing changes to a Git remote, Creating a Git branch.	ges into a Git
Micro pipel integ UN: Infra Perfo UN: MLO Mod	oservices archite line(L2) - Develor gration - monitor IT - IV astructure Autom ormance Manage IT - V ps(L2) - Definit el Governance(L) TOF EXPERIME Creating a repository, Installing Development Setting up	pecture(L2) - coordination model (L2)- building and testing per	ges into a Git
Micro pipel integ integ UN: Infra Perfo UN: Signification MLO Mod	oservices archite line(L2) - Develor gration - monitor IT - IV astructure Autom ormance Manage IT - V ps(L2) - Definit el Governance(L) TOF EXPERIME Creating a repository, Installing Development Setting up	pecture(L2) - coordination model (L2)- building and testing personal properties of the protected (L2) - commit Testing (L2)-Build and Integration Testing (L2)- security - Resources to be Protected(L2) - Identity M. DEVOPS AUTOMATION TOOLS ation(L2)- Configuration Management(L2) - Deployment Autoroment(L2) - Log Management (L2)-Monitoring(L2). MLOPS ion(L1) - Challenges (L1) - Developing Models(L2) - Deploying (L2) - Real world examples (L3). NTS/EXERCISES: new Git repository, cloning existing repository, Checking change Pushing changes to a Git remote, Creating a Git branch. Docker container on windows/Linux, issuing docker commands. Docker Images for Python Application. Docker and Maven in Jenkins and First Pipeline Run.	ges into a Git
UNIMicro pipel integ UNI Infra Perfo UNI MLO Mod	oservices archite line(L2) - Develor gration - monitor IT - IV astructure Autom ormance Manage IT - V ps(L2) - Definit el Governance(L) TOF EXPERIME Creating a repository, Installing Development Setting up Setting up Running United	pecture(L2) - coordination model (L2)- building and testing personal pre-commit Testing (L2)-Build and Integration Testing (L2)- security - Resources to be Protected(L2) - Identity Models (L2)- Security - Resources to be Protected(L2) - Identity Models (L2)- Configuration Management (L2) - Deployment Autorometric (L2) - Log Management (L2)-Monitoring(L2). MLOPS Identity Models (L2) - Deployment Autorometric (L2) - Log Management (L2)-Monitoring(L2). MLOPS Identity Models (L2) - Deployment Autorometric (L2) - Deployment Autorometric (L2) - Log Management (L2)-Monitoring (L2). MLOPS Identity Models (L2) - Deployment Autorometric (L2) - Dep	ng (L3)- Deployment esting(L3) - continuous anagement (L2). 9 mation (L2)- 9 ng to production(L2) FOTAL: 45 PERIOD ges into a Git
Micro pipel integ un: Infra Perfo UN: 3 2 4	oservices archite line(L2) - Develor gration - monitor IT - IV astructure Autom ormance Manage IT - V ps(L2) - Definit el Governance(L) TOF EXPERIME Creating a repository, Installing Development Setting up Setting up Running United	pecture(L2) - coordination model (L2)- building and testing per	ng (L3)- Deployment esting(L3) - continuous anagement (L2). 9 mation (L2)- 9 ng to production(L2) FOTAL: 45 PERIOD ges into a Git

M.E. / M.Tech. Regulations 2023

		TOTAL: 75 PERIODS
ours	e Outcomes: completion of this course the students will be able to:	BLOOM'S Taxonomy
CO1	Implement modern software Engineering process.	L3 – Apply
CO2	Work with DevOps platform.	L3 – Apply
CO3	Build, test and deploy code.	L3 – Apply
CO4	Explore DevOps tools.	L2 - Understand
CO5	Correlate MLOps concepts with real time examples.	L3 – Apply
REFE	RENCE BOOKS:	
1.	Len Bass, Ingo Weber and Liming Zhu, — "DevOps: A Software Arch Education, 2016	litect's Perspective", Pearson
2.	Joakim Verona - "Practical DevOps" - Packet Publishing, 2016	
3.	Viktor Farcic - "The DevOps 2.1 Toolkit: Docker Swarm" - Packet Publi	shing, 2017
4.	Mark Treveil and the Dataiku Team - "Introducing MLOps" - O'Reilly M	edia- 2020
17 18 18 18	O REFERENCES:	
1.	https://youtu.be/7kX3fs0pWwc?si=YfRG3Cu4KCTtZPPd	
2.	https://youtu.be/rX4mQHpWuUY?si=6n00iwT50da7MJIE	
3.	https://youtu.be/XL4KGeQsN3c?si=QncAf6DcwQ 4-Q5	
WEB	REFERENCES:	
1.	https://www.stackify.com	
2.	http://docs.oracle.com	
3.	https://microservice.io	
ONL	INE COURSES:	
0111	https://www.udemy.com/topic/microservices	
1.		
N. S.	https://staragile.com/in/devops https://aws.amazon.com/training/learn-about/devops/?trk=d5f5086	

Mapping of COs with POs									
				POs					
COs	PO1	PO2	PO3	PO4	PO5	P06			
CO1	3	2	1	2	3				
CO2	3	2	-	-	3	-			
CO3	. 3	2	2	3	2	3			
CO4	3	2	1	2	3	-			
CO5	3	2	2	1	2	3			
Average	3	2	1.5	2	2.6	3			



	ME23CP414	DEEP LEARNING		V	ersio	n: 1	.0
	ogramme & M.E. – Computer Science and Engineering 5					P 2	C 4
oui	se Objectives:	Tige to the second seco					
1.	To develop and	Frain Deep Neural Networks.	bolt				
2. To develop a CNN, R-CNN, Fast R-CNN, Faster-R-CNN, Mask-RCNN for detection and recognition.							
3.	To build and trai	n RNNs, work with NLP and Word Embedding.					
4.	To understand to	ne internal structure of LSTM and GRU and the differences b	etwee	n th	em.		
5.	To learn the Aut	o Encoders for Image Processing.					
UN	IT-I	DEEP LEARNING CONCEPTS			9)	
		rixes, Higher Dimensional Tensors(L2) - Manipulating Tensage Data. Video Data(L2).	sors.	Vect	or D	ata(l	.2)
UN	IT-II	NEURAL NETWORKS	Ten d	1	9)	
Los	s Functions(L3) -	k(L1) - Building Blocks of Neural Network(L1) - Optimizer Data Pre-processing for neural networks(L3) - Feature Engiroer parameters(L2).					
UN	IT- III	CONVOLUTIONAL NEURAL NETWORK				9	
neu	ural network(L1) okpropagation Thr ough the Pooling rious Activation Fu	ear Time Invariant(L1)-Image Processing Filtering(L1)-Be-Input Layers, Convolution Layers, Pooling Layers ough the Convolutional Layer(L1)- Filters and Feature Markets (L2)- Dropout Layers and Regularization(L2)- Beautions(L1)-Various Optimizers(L2)-LeNet, AlexNet, VGG10	, De ps(L2 atch l 6, Res	ense)-Ba Norn sNet Goo	La ckpro naliza (L3)-	yersopag ation Tra	(L2) atio (L1) nsfe
Vai	del, Microsoft Resi	e Data. Transfer Learning using Inception Oxford VGG Model-R-CNN, Fast R-CNN, Faster R-CNN, Mask-RCNN, N		L3).			
Vai Lea Mo	del, Microsoft Resi			L3).		9	

recurrent unit GRU (L4).

DEEP REINFORCEMENT & UNSUPERVISED LEARNING UNIT-V

About Deep Reinforcement Learning(L1)- Q - Learning(L2) Deep Q - Network (DQN)(L2) - Policy Gradient Methods(L2) - Actor - Critic Algorithm(L2) - About Auto encoding(L2) - Convolutional Auto Encoding(L2) - Variational Auto Encoding(L2) - Generative Adversarial Networks(L2) - Autoencoders for Feature Extraction(L3). Auto Encoders for Classification(L2) - Denoising Autoencoders(L3) - Sparse Autoencoders(L3).

TOTAL: 45 PERIODS

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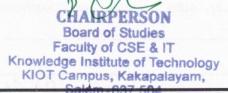
LIST	LIST OF EXPERIMENTS/EXERCISES:				
1.	Feature Selection from Video and Image Data				
2.	Image and video recognition				
3.	Image Colorization				
4.	Aspect Oriented Topic Detection & Sentiment Analysis				
5.	Object Detection using Autoencoder				

TOTAL: 30 PERIODS

OPEN ENDED PROBLEMS / QUESTIONS

Course Specific Open Ended Problems will be solved during teaching. Such problems can be given as Assignments and evaluated as IA only and not for the End Semester Examinations.

TOTAL: 75 PERIODS					
	Outcomes: completion of this course the students will be able to:	BLOOM'S Taxonomy			
CO1	Understand Feature Extraction from Image and Video Data.	L2 - Understand			
CO2	Implement Image Segmentation and Instance Segmentation in Images.	L3 - Apply			
CO3	Implement image recognition and image classification using a pretrained network (Transfer Learning).	L3 – Apply			
CO4	Analyse Traffic Information using Twitter Data.	L4 - Analyze			
CO5	Apply Autoencoder for Classification & Feature Extraction.	L3 - Apply			
REFE	RENCE BOOKS:	2.82 - 9.105			
1.	Pro Deep Learning with TensorFlow, Santanu Pattanayak, Apress, 2017				
2.	Deep Learning A Practitioner's Approach Josh Patterson and Adam Gi Inc.2017	bson O'Reilly Media,			
3.	Learn Keras for Deep Neural Networks, Jojo Moolayil, Apress,2018				
4.	Deep Learning Projects Using TensorFlow 2, Vinita Silaparasetty, Apress, 20)20			
5.	Deep Learning with Python, FRANÇOIS CHOLLET, MANNING SHELTER ISLAN	ND,2017			
VIDE	O REFERENCES:				
1.	https://onlinecourses.nptel.ac.in/noc20 cs62/preview	propri sa si 930 kus			
2.	https://onlinecourses.nptel.ac.in/noc20 cs50/preview				
WEB	REFERENCES:				
1.	https://www.kaggle.com/learn/intro-to-deep-learning				
2.	https://www.datacamp.com/tutorial/tutorial-deep-learning-tutorial	ALT INDICATE AND ADDRESS			
ONLI	NE COURSES:				
1.	https://www.udemy.com/course/deeplearning				
2.	https://in.mathworks.com/solutions/deep-learning				



Mapping of COs with Pos							
POs							
PO1	PO2	РОЗ	P04	PO5	P06		
2	2		3	3	3		
2	2	2	3	3	2		
2	2	2	3	2	3		
2	2	1	3	3	3		
2	2		3	2	2		
2	2	1.6	3	2.6	2.6		
	2 2 2	PO1 PO2 2 2 2 2 2 2 2 2 2 2	PO1 PO2 PO3 2 2 2 2 2 2 2 2 2 2 2 2 2 1 2 2 2	PO1 PO2 PO3 PO4 2 2 3 2 2 2 3 2 2 2 3 2 2 2 3 2 2 1 3 2 2 3 3	PO1 PO2 PO3 PO4 PO5 2 2 3 3 2 2 2 3 3 2 2 2 3 3 2 2 2 3 2 2 2 1 3 3 2 2 1 3 3 2 2 3 2		



CHAIRPERSON

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Knowledge Institute of Technology

KIOT Campus, Kakapalayam,

Salem-637 504

	ME23CP415	DLOCK CHAZIV I LOUING CO.	Version: 1.0							
	gramme &	M.E. – Computer Science and Engineering 5	L T P C 3 0 2 4							
our	se Objectives:									
1.	To understand cr	yptographic fundamentals and blockchain technology.	200							
2.		oto currency mechanics and impacts of block chain technology on i	it.							
3.	To gain comprehensive understanding of ethereum.									
4.	To explore the understanding of both private and public Blockchain and smart contract.									
5.		aspects of block chain technology like applications in various dom								
	IT-I	INTRODUCTION OF CRYPTOGRAPHY AND BLOCKCHAIN	9							
	public Blockchain(Digital Signatures(L2), Hashing(L2), and public key cryptosyst L2).	G5(12), F							
1	IT-II roduction to Bito	BITCOIN AND CRYPTOCURRENCY coin(L1), The Bitcoin Network(L2), The Bitcoin Mining Proc	ess(L2), Mining							
Intr Dev (EV	roduction to Bitovelopments, Bitcoi	coin(L1), The Bitcoin Network(L2), The Bitcoin Mining Proc in Wallets(L2), Decentralization and Hard Forks(L2), Ethereum ee, Double-Spend Problem(L3), Blockchain and Digital Currency(L	cess(L2), Mining Virtual Machine							
Intr Dev (EV Blo	roduction to Bitovelopments, Bitcoi	coin(L1), The Bitcoin Network(L2), The Bitcoin Mining Prod in Wallets(L2), Decentralization and Hard Forks(L2), Ethereum	cess(L2), Mining Virtual Machine							
Intr Dev (EV Bloo UN	roduction to Bitco velopments, Bitcoi /M)(L3), Merkle Tro- cks(L2), Impact of III III roduction to Ether	coin(L1), The Bitcoin Network(L2), The Bitcoin Mining Proc in Wallets(L2), Decentralization and Hard Forks(L2), Ethereum ee, Double-Spend Problem(L3), Blockchain and Digital Currency(L Blockchain Technology on Cryptocurrency(L4).	virtual Machine 2), Transactiona							
Intr Dev (EV Bloc UN Intr	roduction to Bitco velopments, Bitcoi /M)(L3), Merkle Tro- cks(L2), Impact of III III roduction to Ether	coin(L1), The Bitcoin Network(L2), The Bitcoin Mining Processin Wallets(L2), Decentralization and Hard Forks(L2), Ethereum ee, Double-Spend Problem(L3), Blockchain and Digital Currency(Lagrange) Blockchain Technology on Cryptocurrency(L4). INTRODUCTION TO ETHEREUM Teum(L2), Consensus Mechanisms(L2), Metamask Setup(L2), Ethereiving Ethers(L2), Smart Contracts(L2). INTRODUCTION TO HYPERLEDGER AND SOLIDITY	virtual Machine 2), Transactiona							
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1. Create a Simple Blockchain in any suitable programming language. 2. Use Geth to Implement Private Ethereum Block Chain. 3. Build Hyperledger Fabric Client Application. 4. Build Hyperledger Fabric with Smart Contract. 5. Create Case study of Block Chain being used in illegal activities in real world. 6. Using Python Libraries to develop Block Chain Application. TOTAL: 30 PERIODS

OPEN ENDED PROBLEMS / QUESTIONS

Course Specific Open Ended Problems will be solved during teaching. Such problems can be given as Assignments and evaluated as IA only and not for the End Semester Examinations.

		TOTAL: 75 PERIODS
	outcomes: completion of this course the students will be able to:	BLOOM'S Taxonomy
CO1	Understand and explore the working of Blockchain technology.	L2 - Understand
CO2	Analyze the working of Smart Contracts.	L4 - Analyze
CO3	Understand and analyze the working of Hyperledger.	L2 - Understand
CO4	Apply the learning of solidity to build de-centralized apps on Ethereum.	L3 - Apply
CO5	Analyze and develop applications on Blockchain.	L4 - Analyze
REFE	RENCE BOOKS:	
1.	Imran Bashir, "Mastering Blockchain: Distributed Ledger Technology, Smart Contracts Explained", Second Edition, Packt Publishing, 2018. Narayanan, J. Bonneau, E. Felten, A. Miller, S. Goldfeder, "Bitcoin	and Cryptocurrency
3.	Technologies: A Comprehensive Introduction" Princeton University Press, 2 Antonopoulos, Mastering Bitcoin, O'Reilly Publishing, 2014.	.010
4.	Antonopoulos and G. Wood, "Mastering Ethereum: Building Smart Co O'Reilly Publishing, 2018.	ontracts and Dapps",
5.	D. Drescher, Blockchain Basics. Apress, 2017.	
VIDE	OREFERENCES: Bosings OK mountarion	
1.	https://vidico.com/news/blockchain-animation/	
2.	https://www.youtube.com/watch?v=qOVAbKKSH10	
3.	https://www.youtube.com/watch?v=a4xgVqZdd6M	

WEB	REFERENCES:
1.	https://www.geeksforgeeks.org/solidity/
2.	https://www.tutorialspoint.com/ethereum/index.htm
3.	https://docs.aws.amazon.com/managed-blockchain/latest/hyperledger-fabric-dev/managed-blockchain-get-started-tutorial.html
ONL	INE COURSES:
1.	https://nptel.ac.in/courses/106/104/106104220/#
2.	https://www.udemy.com/course/build-your-blockchain-az/
3.	https://eduxlabs.com/courses/blockchain-technologytraining/?tab=tab-curriculum

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		Mapping of COs with POs							
POs									
PO1	PO2	, PO3	PO4	PO5	P06				
2	1	3	2	2	3				
2	1	2	3	2	2				
2	1	3	1	2	1				
2	1	2	3	2	2				
-									
2	1	2.5	2.25	2	2				
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ME23CP416	FULL STACK WEB APPLICATION DEVELOPMENT	Con The Control	Vers	ion:	1.0	
Programme &		CP	L	Т	P	C
Branch	M.E Computer Science and Engineering	5	3	0	2	4

- To develop Type Script Application. 1.
- To develop Single Page Application (SPA). 2.
- To understand the communication with a server over the HTTP protocol. 3.
- To learn all the tools need to start building applications with Node.js. 4.
- 5. To implement the Full Stack Development using MEAN Stack.

UNIT-I

FUNDAMENTALS & TYPESCRIPT LANGUAGE

10

Server-Side Web Applications(L2)- Client-Side Web Applications- Single Page Application(L1)- About Type Script- Creating TypeScript Projects(L3)- TypeScript Data Types- Variables-Expression and Operators- Functions(L1)- OOP in Typescript(L1)- Interfaces(L1) Generics Modules(L2) Enums-Decorators(L2). Enums- Iterators- Generators(L2).

UNIT-II **ANGULAR**

10

About Angular, Angular CLI(L2) Creating an Angular Project(L2)- Components(L3)- Components Interaction- Dynamic Components- Angular Elements- Angular Forms(L2)- Template Driven Forms. Property, Style, Class and Event Binding(L2)- Two way Bindings- Reactive Forms(L2)-Form Group- Form Controls(L2) About Angular Router- Router Configuration-Router State(L3)- Navigation Pages- Router Link- Query Parameters- URL matching(L2)- Matching Strategies- Services(L3)- Dependency Injection(L2)- HttpClient- Read Data from the Server- CRUD Operations- Http Header Operations-Intercepting requests and responses.

UNIT-III NODE.js

10

About Node.js- Configuring Node.js environment(L2- Node Package Manager NPM(L2)- Modules-Asynchronous Programming(L2)- Call Stack and Event Loop(L2)- Callback functions- Callback errors-Abstracting callbacks(L2)- Chaining callbacks-File System- Synchronous vs. asynchronous I/O(L2)- Path and directory operations- File Handle(L2)- File Synchronous API- File Asynchronous API(L2)- File Callback API. Timers(L2)- Scheduling Timers- Timers Promises API(L2)- Node.js Events- Event Emitter(L2)- Event Target and Event API(L2)- Buffers- Buffers and Typed Arrays(L3)- Buffers and iteration- Using buffers for binary data - Flowing vs non-flowing streams(L3)- JSON(L2).

UNIT - IV EXPRESS.Js

Express.js- How Express.js Works(L1). Configuring Express.js App Settings(L2) -Starting the App. Express.js Application Structure(L3)- Configuration, Settings- Middleware- body-parsecookie-parser- express-session(L2)- response-time- Template Engine(L2)- Jade. EJ- Parameters(L2)-

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Routing(L3)- router-route(path)- Router Class- Request Object- Response Object(L3)- Error Handling-RESTful(L2).

UNIT-V MONGODB 8

Introduction to MongoDB(L2)- Documents- Collections- Subcollections(L2)- Database- Data Type- Dates-Arrays(L2)- Embedded Documents(L2)- CRUD Operations- Batch Insert- Insert Validation(L2)- Querying the Documents(L2)- Cursors- Indexing- Unique Indexes(L2)- Sparse Indexes- Special Index and Collection Types(L2)- Full-Text Indexes- Geospatial Indexing(L2)- Aggregation framework(L2).

TOTAL: 45 PERIODS

LIST OF EXPERIMENTS/EXERCISES:

- 1. Accessing the Weather API from Angular
- 2. Accessing the Stock Market API from Angular
- 3. Call the Web Services of Express.js From Angular
- 4. Read the data in Node.js from MongoDB
- 5. CRUD operation in MongoDB using Angular

TOTAL: 30 PERIODS

OPEN ENDED PROBLEMS / QUESTIONS

Course Specific Open Ended Problems will be solved during teaching. Such problems can be given as Assignments and evaluated as IA only and not for the End Semester Examinations.

		TOTAL: 75 PERIODS
	e Outcomes: completion of this course the students will be able to:	BLOOM'S Taxonomy
CO1	Develop basic programming skills using Java script. •	L3 – Apply
CO2	Implement a front-end web application using Angular.	L3 - Apply
CO3	Create modules to organize the server.	L3 – Apply
CO4	Build RESTful APIs with Node, Express and MongoDB with confidence.	L3 - Apply
CO5	Interpret to Store complex, relational data in MongoDB using Mongoose.	L2 - Understand

REFERENCE BOOKS:

- 1. Adam Freeman, Essential TypeScript, Apress, 2019
- 2. Mark Clow, Angular Projects, Apress, 2018
- 3. Alex R. Young, Marc Harter, Node. js in Practice, Manning Publication, 2014
- 4. Pro Express.js, Azat Mardan, Apress, 2015
- 5. MongoDB in Action, Kyle Banker, Peter Bakkum, Shaun Verch, Douglas Garrett, Tim Hawkins, Manning Publication, Second edition, 2016

VIDEO REFERENCES:

- 1. https://www.youtube.com/watch?v=R6RX2Zx96fE
- 2. https://youtu.be/Gzk4cc8LTQs?si=472Z7JzqfXUwX-Or

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Saipa

3.	https://youtu.be/8KaJRw-rfn8?si=sRg9HINKIBgaeNvj
WEB	REFERENCES:
1.	https://www.mongodb.com
2.	https://www.simplilearn.com/what-is-full-stack-development-article
3.	https://ifact.iitk.ac.in/product/full-stack-web-developer-angular-react-and-mongo-db-advance
ONL	NE COURSES:
1.	https://www.classcentral.com/course/full-stack-mobile-app-development-35062
2.	https://www.udemy.com/course/full-stack-development-using-angular-10-web-api-sql
3.	https://ifacet.iitk.ac.in/product/full-stack-web-developer-mongodb-express-react-and-node-js-advance

Mapping of COs with POs						
	POs					
COs	PO1	PO2	PO3	PO4	PO5	P06
CO1	-		2	3	3	3
CO2	_		2	3 (Sayan	3	3
CO3	2	STATE OF THE STATE	1	Control of the Contro	3	3
CO4	2		2		3	3
CO5	3	3	ashalian -		3	3
Average	2.33	3	1.75	3	3	3
		1-Lo	w, 2 -Medium,	3-High		

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