KNOWLEDGE INSTITUTE OF TECHNOLOGY

(An Autonomous Institution)

Approved by AICTE, Affiliated to Anna University, Chennai. Accredited by NBA (CSE, ECE, EEE & MECH), Accredited by NAAC with 'A' Grade KIOT Campus, Kakapalayam – 637 504. Salem Dt., Tamil Nadu, India.



M.E. / M.Tech. Regulations 2023

M.E. – Embedded System Technologies

CURRICULUM and SYLLABI

(For the Students Admitted from the Academic Year 2023-24 Onwards)

Version: 1.0



KNOWLEDGE INSTITUTE OF TECHNOLOGY(AUTONOMOUS), SALEM -637504

Approved by AICTE, Affiliated to Anna University, Accredited by NAAC and NBA (B.E.:Mech., ECE, EEE & CSE)

Website: www.kiot.ac.in

TABLE OF CONTENTS

S.NO	CONTENTS	PAGE NO.
1	VISION, MISSION, PEOs	1
2	POs, PSOs	2
3	CURRICULUM STRUCTURE FROM I to VIII SEMESTER	3 - 5
4	SEMESTER WISE CREDIT DISTRIBUTION AND NOMENCLATURE	6
5	SEMESTER - I	7
6	SEMESTER - II	23
7	AUDIT COURSES I & II SALEM	35
8	PROFESSIONAL ELECTIVE COURSES I & II	44
9	OPEN ELECTIVE COURSES I & II	62

KNOWLEDGE INSTITUTE OF TECHNOLOGY (AUTONOMOUS), SALEM



Approved by AICTE, Affiliated to Anna University, Accredited by NAAC and NBA (B.E.: Mech., ECE, EEE & CSE)

M.E. / M.Tech. REGULATIONS 2023 (R 2023) CHOICE BASED CREDIT SYSTEM AND OUTCOME BASED EDUCATION

M.E. – Embedded System Technologies

VISION OF THE INSTITUTE

To be a world-class institution to impart value and need based professional education to the aspiring youth and carving them into disciplined world class professional who have the quest for excellence, achievement orientation and social responsibilities.

MISSION	OF THE INSTITUTE
Α	To promote academic growth by offering state-of-art undergraduate, postgraduate and doctoral programs and to generate new knowledge by engaging in cutting – edge research
В	To nurture talent, Innovation, entrepreneurship, all-round personality and value system among the students and to foster competitiveness among students
С	To undertake collaborative projects which offer opportunities for long-term interaction with academia and industry
D	To pursue global standards of excellence in all our endeavors namely teaching, research, consultancy, continuing education and support functions

VISION OF THE DEPARTMENT

To produce technically competent Electrical and Electronics Engineers having exemplary skills with ethical and social values.

Denond (Knomledae

MISSION OF THE DEPARTMENT									
M1	To provide state-of-the art facilities in Electrical and Electronics Engineering for improving the learning environment and research activities								
M2	To continuously enrich the knowledge and skill of students towards the employment and creation of innovative products for society								
М3	To develop ethical, social-valued and entrepreneurship skilled Electrical and Electronics Engineers								

PROGRAM EDUCATIONAL OBJECTIVES (PEOs)									
PEO 1	To provide students good foundation in mathematical, scientific, engineering fundamentals and hardware-software programming intelligence.								
PEO 2	To develop among students, the ability to develop embedded systems based smart solutions for purpose of system automation.								
PEO 3	To promote student awareness, for life-long learning and introduce them to professional ethics and code of practice.								

PROGRAM OUTCOMES (POs)

PO 1	An ability to independently carry out research / investigation and development work to solve practical problems.
PO 2	An ability to write and present a substantial technical report / document.
PO 3	Student should be able to demonstrate a degree of mastery over the area as per the specialization of the program. The mastery should be at a level higher than the requirements in the appropriate bachelor program.
PO 4	Be able to design and develop Embedded system automation based on dedicated ICs that have computation, networking and control capacity.
PO 5	Skill to work on professional software languages, standard modeling and analysis tools & commercial packages with communication protocols and computation platforms for analysis and design of system automation.
PO 6	To involve in research on an industrial problem or develop an innovative smart system with automation as a consumer product through project management and finance with due concerned for socio economic values

Beyond Knowledge

	KNOW	LEDGE INSTITUTE OF TECHNO	LOGY	(AUTO	DNOM	ous),	SALE	M - 6	37504			
		M.E. EMBEDDED SYSTEM TE	CHNO	OGIE	S				Versi	on: 1.	0	
	Courses of Study and Scheme of Assessment (Regulations 2023) Date: 9.9.2023										023	
SI.	Course	Course Title		Pe	riods	/ Wee	ek	-	Maxi	mum	Marks	
No.	Code	course fille	САТ	СР	L	т	Ρ	С	IA	ESE	Total	
SEMESTER I												
-	-	Induction Program	-	-	-	-	-	-	-	-	-	
THE	ORY											
1	ME23MA104	Applied Mathematics for Embedded Systems Technologists	FC	4	3	1	0	4	40	60	100	
2	ME23RM201	Research Methodology and IPR	RM	3	3	0	0	3	40	60	100	
3	ME23ET301	Design of Embedded Systems	PC	3	3	0	0	3	40	60	100	
4	ME23ET302	Software for Embedded Systems	PC	3	3	0	0	3	40	60	100	
5	ME23ET303	Microcontroller Based System Design	PC	3	3	0	0	3	40	60	100	
6	ME23ET304	VLSI Design and Reconfigurable Architecture	PC	3	3	0	0	3	40	60	100	
7	ME23AC7XX	Audit Course – I *	AC	2	2 1	0	0	0	100	-	100	
PRA	CTICAL			1								
8	ME23ET305	Embedded Systems- I Laboratory	PC	4	0	0	4	2	60	40	100	
EMP	LOYABILITY E	NHANCEMENT	15.	2		K						
9	ME23PT801	Technical Seminar / Case study Presentation	EEC	2	0	0	2	0	100	-	100	
		Total		27	20	1	6	21	500	400	900	

	SEMESTER II											
THE	THEORY											
1	ME23ET306	Real Time Operating System	PC	3	3	0	0	3	40	60	100	
2	ME23ET307	Embedded System Networking	PC	3	3	0	0	3	40	60	100	
3	ME23ET308	ME23ET308 Embedded Control for Electric Drives			3	0	0	3	40	60	100	
4	ME23ET4XX	Professional Elective I	PE	3	3	0	0	3	40	60	100	
5	ME23ET4XX	Professional Elective II	PE	3	3	0	0	3	40	60	100	
6	ME23XX5XX	Open Elective-I	OE	3	3	0	0	3	40	60	100	
7	ME23MC701	Universal Human Values and Ethics	МС	3	2	1	0	3	40	60	100	
8	ME23AC7XX	Audit Course – II *	AC	2	2	0	0	0	100	-	100	
PRA	CTICAL											
9	ME23ET309	Embedded Systems - II Laboratory	PC	4	0	0	4	2	60	40	100	
ЕМР		ENHANCEMENT										
10	ME23PT802	Research Paper Review and presentation	EEC	2	0	0	2	1	100	-	100	
		Total		29	23	0	6	24	540	460	1000	

* Audit Course is optional

	KNOV	VLEDGE INSTITUTE OF TECHNOL	OGY (/	AUTO	NOM	ious), SA	LEM -	63750	4	
		M.E. EMBEDDED SYS	тем т	ECH	NOLC	GIES	5				
		Courses of Study and Scheme of	Asses	sme	nt (R	egul	ation	s 2023	3)		
SI.	Course			Ре	riods	/ W	eek		Maxi	mum	Marks
No.	Code	Course litie	САТ	СР	L	т	Р	С	IA	ESE	Total
		SEMES	TER II	I		-					
THE	ORY										
1	ME23ET4XX	Professional Elective-III	PE	3	3	0	0	3	40	60	100
2	ME23ET4XX	Professional Elective-IV	PE	3	3	0	0	3	40	60	100
3	ME23ET310	IoT for Smart Systems	PC	3	3	0	0	3	40	60	100
4	ME23XX5XX	Open Elective-II	OE	3	3	0	0	3	40	60	100
PRA	CTICAL								-		
5	ME23ET601	Project Work Phase-I	PW	12	0	0	12	6	60	40	100
		Total	TE	24	12	0	12	18	220	280	500
		SEMES	TER I	V		7					
PRA	CTICAL	- 4		0	16	\$ /					
1	ME23ET602	Project Work Phase-II	PW	24	0	0	24	12	60	40	100
Total				24	0	0	24	12	60	40	100
			5.4			0	То	tal Nu	mber o	of Crec	lits: 75
			1	3		0					

	AUDIT COURSES - I & II											
1	ME23AC701	English for Research Paper Writing	AC	2	2	0	0	0	100	-	100	
2	ME23AC702	Disaster Management	AC	2	2	0	0	0	100	-	100	
3	ME23AC703	Constitution of India	AC	2	(2/	0	0	0	100	-	100	
4	ME23AC704	நற்றமிழ் இலக்கியம்	AC	2	2	0	0	0	100	-	100	

KNOWLEDGE INSTITUTE OF TECHNOLOGY (AUTONOMOUS), SALEM - 637504

M.E. EMBEDDED SYSTEM TECHNOLOGIES

Courses of Study and Scheme of Assessment (Regulations 2023)

SI.	Course			Pe	riods	Maximum Marks						
No.	Code	course ritle		СР	L	Т	Ρ	С	IA	ESE	Total	
	Professional Elective – I & II											
1	ME23ET401	Wireless And Mobile Communication	PE	3	3	0	0	3	40	60	100	
2	ME23ET402	Virtual Instrumentation		3	3	0	0	3	40	60	100	
3	ME23ET403	Embedded Processor Development	PE	3	3	0	0	3	40	60	100	
4	ME23ET404	Automotive Embedded System	PE	3	3	0	0	3	40	60	100	
5	ME23ET405	Intelligent Control and Automation	PE	3	3	0	0	3	40	60	100	
6	ME23ET406	Unmanned Aerial Vehicle	PE	З	З	0	0	3	40	60	100	
7	ME23ET407	DSP Based System Design	PE	3	3	0	0	3	40	60	100	
8	ME23ET408	Machine Learning and Deep Learning	PE	3	3	0	0	3	40	60	100	

	Open Electives – I & II											
S.	Course Cod		hil.	Peri	ods	/ W	eek		Maxi	imum	Marks	
No.	Course Cou	e Course Intie	CAT	СР	2	т	Ρ	С	CIA	ESE	Total	
Exce	pt M.E. Com	puter Science and Engineering	14			2						
1	ME23CP501	Security Practices	OE	3	3	0	0	3	60	40	100	
2	ME23CP502	Cloud Computing Technologies	OE	3	3	0	0	3	60	40	100	
3	ME23CP503	Blockchain Technologies	OE	3	3	0	0	3	60	40	100	
4	ME23CP504	Deep Learning	OE	3	3	0	0	3	60	40	100	
5	ME23CP505	Design Thinking	OE	3	3	0	0	3	60	40	100	
6	ME23CP506	Principles of Multimedia	OE	3	3	0	0	3	60	40	100	
Exce	pt M.E. Indu	strial Safety Engineering	10		/	/						
7	ME23IS501	Environmental Safety	OE	3	3	0	0	3	60	40	100	
8	ME23IS502	Electrical safety	OE	3	3	0	0	3	60	40	100	
9	ME23IS503	Safety in Engineering Industry	OE	3	3	0	0	3	60	40	100	
10	ME23IS504	Design of Experiments	OE	3	3	0	0	3	60	40	100	
11	ME23IS505	Circular Economy	OE	3	3	0	0	3	60	40	100	
Exce	pt M.E. Embe	dded System Technologies										
12	ME23ET501	IoT for Smart Systems	OE	3	3	0	0	3	60	40	100	
13	ME23ES502	Machine Learning and Deep Learning	OE	3	3	0	0	3	60	40	100	
14	ME23ES503	Renewable Energy Technology	OE	3	3	0	0	3	60	40	100	
15	ME23ES504	Smart Grid	OE	3	3	0	0	3	60	40	100	
Excep	ot M.E. VLSI D	esign										
16	ME23VL501	Big Data Analytics	OE	3	3	0	0	3	60	40	100	
17	ME23VL502	Internet of Things and Cloud	OE	3	3	0	0	3	60	40	100	
18	ME23VL503	Medical Robotics	OE	3	3	0	0	3	60	40	100	
19	ME23VL504	Embedded Automation	OE	3	3	0	0	3	60	40	100	

SEMESTER-WISE CREDITS DISTRIBUTION

SUMMARY											
SI.	Course	Cr	edits pe	r Semest	ter	Crodito	Cradit %				
No.	Category	I	II	III	IV	creats	Credit %				
1	FC	4	-	-	-	4	5				
2	RM	3	-	-	-	3	4				
3	PC	14	11	3	-	28	37				
4	PE	-	6	6	-	12	16				
5	OE	-	3	3	-	6	8				
6	PW	-	-	6	12	18	24				
7	MC/AC	~	3	-	-	3	4				
8	EEC	~	1	-	-	1	1				
	Total	21	24	18	12	75	100				

TITUTE

CA T	Category of	FC	Foundation Courses	MC/AC	Mandatory Courses/ Audit
СР	Contact Periods	RM	Research methodology and IPR courses	EEC	Employability Enhancement Courses
L	Lecture Hours	PC 🔨	Professional Core Courses	IA	Internal Assessment
Т	Tutorial Hours	PE <	Professional Elective Courses	ESE	Semester End Examination
Р	Practical Hours	OE 🗸	Open Elective Courses	PW	Project Work Courses
С	Credits		a con win		





ME	ME23MA104 APPLIED MATHEMATICS FOR EMBEDDED SYSTEMS Version: 1.0								
Prog Brar	Jramme & Nch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	СР 4	L 3	T 1	P 0	C 4		
Cou	rse Objectivo	es:							
1	To understa	nd the techniques of Fourier transform to solve partial differentia	l equ	ation	s.				
2	To learn the	graph theory concepts for modelling the system.							
3	To learn the	e optimization techniques.							
4	To learn the	e basic concepts of probability and Random Variables.							
5	To introduc	e the basic concept of queuing theory.							
UNI	T-I	FOURIER TRANSFORM TECHNIQUES FOR PARTIAL DIFFERENTIAL EQUATIONS		ç)+3				
Fou Dirac partia equat	rier transforr delta fur al differ tions(L3).	m : Definitions(L1) – Properties(L2) – Transform of elementar action(L2) – Convolution theorem(L3) – Parseval's identity(L3 ential equations: Heat equation Wave equation(L3) - Lapla	y fui 3) – ice a	nctior Solut and	ıs(L2 tions Poiso) - to n's			
UNI	UNIT-II GRAPH THEORY								
Intr Some – I algor	oduction to p basic algori somorphism(ithms(L3) – (paths(L1), trees, vector spaces(L2) - Matrix coloring and direc thms(L2) – Shortest path algorithms(L2) – Depth - First searc (L3) – Other Graph Theoretic algorithms(L2) – Performance of Graph theoretic computer languages(L2).	ted g h on f gra	graph a gra ph th	ıs(L3 эph(l าeore	5) - L2) etic			
UNI	T– III	OPTIMIZATION TECHNIQUES		g)+3				
Line meth probl	ar programm od(L3) - Two ems(L3) – As	ning(L2) - Basic concepts(L2) - Graphical and simplex metho o phase simplex method(L3) - Revised simplex method(L3) signment problems(L3) .	ods(l - Tı	.3) – ansp	Big ortat	M ion			
UNI	T – IV	PROBABILITY AND RANDOM VARIABLES		ç) +3				
Prol – funct – Two	bability(L1) – Random v ions(L2) au dimensional	Axioms of probability(L2) – Conditional probability(L2) – Bay ariables (L1) - Probability function(L2) – Moments – Mor nd their properties)L2) – Binomial,Poisson, Exponential, Normal random variables(L2) - Poisson process(L3).	/e's f nent I dist	theor ger ributi	em(l ierati ions(l	L3) ing L3)			
UNI	T-V	QUEUEING THEORY		9	9+3				
Sing queu	gle and multi es(L3) – Fin	ple servers(L2) - Markovian queuing models(L3) - Finite and itesource model(L3) — Queuing applications(L3).	infir	nite c	apac	ity			
		OPEN ENDED PROBLEMS / QUESTIONS							
Cour can l seme Exan	se specific Op de given as As ster hinations.	en Ended Problems will be solved during the class room teaching ssignments and evaluated as Internal Assessment only and not fo	. Suc r the	h pro End	blem	าร			
		PERIODS	То	otal :	60				
Cou Upo	rse Outcome n completior	s: • of this course the students will be able to:		BL Tax	MOC onor	′S ny			
C01	Apply Four	ier transform techniques to solve PDE technology	L3 – Apply						
C02	CO2Model the networks in embedded systems using graph theory.L3 – Apply								

CO3	Apply the optimization technique to solve the transportation and assignment related problems.	L3 – Apply					
CO4	Make use of the concepts of probability and random variables in solving L3 – Apply L3 – Apply						
CO5	Apply the knowledge queuing theory in embedded system technologies.	L3 – Apply					
REFE	RENCE BOOKS:						
1.	1. Taha H .A., " Operations Research: An Introduction ", 9 th Edition, Pearson Education Asia, New Delhi, 2016.						
2.	Walpole R.E., Myer R.H., Myer S.L., and Ye, K., " Probability and Statistics for Engineers and Scientists ", 7 th Edition, Pearson Education, Delhi, 2002.						
3.	Sankara Rao, K., " Introduction to Partial Differential Equations ", Prentice Hall ofIndia Pvt. Ltd., New Delhi, 1997.						
4.	Narasingh Deo, " Graph Theory with Applications to Engineering and Computer Science ", Prentice Hall India, 1997.						
5.	S. S. Rao, " Engineering Optimization, Theory and Practice ", 4 th Edition, Joh Wiley and Sons, 2009.	าท					
VIDE	O REFERENCES:						
1.	https://www.youtube.com/watch?v=6RcRSli0YEI&list=PLEAYkSg4uSQ3Nww0 Prof Rajiv Misra IIT-Karagpur	QtfSgnKPF5x4iI_XTb					
2.	https://www.youtube.com/watch?v=vqJuFD0GdJA (Dr P N Agarwal IIT R)						
WEB	REFERENCES:						
1.	http://stankova.net/book.pdf						
2.	https://www.edanz.com/blog/anova-explained						
ONLI	NE COURSES:						
1.	https://nptel.ac.in/courses/110105087						
2.	https://onlinecourses.nptel.ac.in/noc23_ge25/preview						
•							

Mapping of COs with POs							
6			PC	Ds of			
COS	PO1	PO2	PO3	PO4	PO5	P06	
CO1	2						
CO2	2	-					
CO3	2	2.1	- EIV				
CO4	2						
CO5	2		120				
Average	2		n K				

ME23RM201

RESEARCH METHODOLOGY AND IPR

M.E. EMBEDDED SYSTEM TECHNOLOGIES

Version: 1.0

(COMMON TO ALL BRANCHES)

Programme &Branch

 CP
 L
 T
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 3
 2
 1
 0
 3

6+3

6+3

Course Objectives:

1	Analyze the significance of research and formulate well-defined research questions.
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2 Apply appropriate research methods and critically evaluate research articles.

3 Create well-structured research papers and utilize research tools proficiently.

4 Produce effective technical reports and deliver impactful presentations.

⁵ Understand forms of intellectual property and analyze their implications on technological research and international cooperation.

UNIT-I CONCEPT OF RESEARCH

Meaning and Significance of Research(L2)-Skills, Habits and Attitudes for Research (L1)-Time Management (L3) -Status of Research in India (L2)-Why, How, and What a Research is? (L2)-Types and Process of Research (L2)-Outcome of Research (L2)-Sources of Research Problem (L2)-Characteristics of a Good Research Problem (L2)-Errors in Selecting a Research Problem (L2)-Importance of Keywords (L1)-Literature Collection - Analysis (L2)-Citation Study - Gap Analysis (L2)-Problem Formulation Techniques (L2).

UNIT-II	RESEARCH METHODS AND JOURNALS	6+3						
Interdisciplinary Research (L2)-Need for Experimental Investigations (L2)-Data Collection Methods (L3)-								
Appropriate Choic	Appropriate Choice of Algorithms / Methodologies / Methods (L2)-Measurement and Result Analysis							
(L3)-Investigation	of Solutions for Research Problem (L2)-Interpretation (L2)-Research L	imitations (L2)-						
Journals in Scienc	e/Engineering (L2)-Indexing and Impact factor of Journals (L3)-Citation	ns(L2)- h Index						
(L2)- i10 Index (L2)-Journal Policies (L4)How to Read a Published Paper (L2)-Ethical Is	sues Related to						
Publishing(L3)- Pl	agiarism and Self-Plagiarism (L2).							

UNIT- III PAPER WRITING AND RESEARCH TOOLS

Types of Research Papers (L2)- Original Article/Review Paper/Short Communication/Case Study(L2)-When and Where to Publish? (L2) - Journal Selection Methods (L2)-Layout of a Research Paper (L2)-Guidelines for Submitting the Research Paper (L2)-Review Process - Addressing Reviewer Comments (L3)-Use of tools / Techniques for Research (L3)-Hands-on Training related to Reference Management Software - EndNote (L3)- Introduction to Origin, SPSS,etc (L2)-Software for Detection of Plagiarism (L2)

UNIT – IV EFFECTIVE TECHNICAL THESIS WRITING/PRESENTATION 6+3

How to Write a Report(L1)- - Language and Style (L1)-Format of Project Report (L1) - Use of Quotations (L2)-Method of Transcription Special Elements (L3)-Title Page - Abstract - Table of Contents - Headings and Sub-Headings (L2)-Footnotes - Tables and Figures - Appendix - Bibliography etc. (L3)-Different Reference Formats (L2)-Presentation using PPTs (L2).

UNIT-VNATURE OF INTELLECTUAL PROPERTY6+3Patents(L1) - Designs(L2) - Trade and Copyright (L2)- Process of Patenting and Development (L2)-
Technological research(L2)- innovation(L2)- - patenting(L2)-Development International Scenario (L2)-
International Cooperation on Intellectual Property (L2)-Procedure for Grants of Patents (L2).

OPEN ENDED PROBLEMS / QUESTIONS

Total : 30+15=45 PERIODS

Course specific open ended problems will be solved during the classroom teaching. Such problems can be given as assignments and evaluated as internal assessment only and not for the end semester examination.

COURSE OUTCOMES: BLOOM'S							
Upon	completion of this course the students will be able to:	Taxonomy					
C01	Illustrate the importance and objectives of research in contributing to knowledge and solving real-world problems.	L2 - Understand					
CO2	Experiment with data collection techniques, choosing fitting approaches to ensure sound research framework and methodology.	L3 - Apply					
CO3	Utilize research & analytic tools for enhancing the research publication	L2 - Understand					
CO4	Apply knowledge to produce presentations and technical reports that effectively communicate research findings.	L3 - Apply					
CO5	Explain types of intellectual property and comprehend patenting as essential for safeguarding innovation and creativity.	L2 - Understand					
REFER	ENCE BOOKS:						
1.	Cooper Donald R, Schindler Pamela S and Sharma JK, "Business Research M McGraw Hill Education, 11e (2012).	lethods", Tata					
2.	DePoy, Elizabeth, and Laura N. Gitlin, "Introduction to Research-E-Book: Ur Applying Multiple Strategies", Elsevier Health Sciences, 2015.	nderstanding and					
3.	Walliman, Nicholas, "Research Methods: The basics", Routledge, 2017						
4.	Bettig Ronald V., "Copyrighting culture: The political economy of intellectual Routledge, 2018.	property",					
5.	The Institute of Company Secretaries of India, Statutory body under an Act "Professional Programme Intellectual Property Rights, Law and practice", Se	of parliament, ptember 2013.					
VIDEC	REFERENCES:						
1.	https://www.youtube.com/watch?v=1vf8ZvADxfY&list=PLLhSIFfDZcUWRlgi	XMkd1rNeLSz1You4O					
2.	https://www.youtube.com/watch?v=eIUaS51U05M&list=PLIEVEMAFhG4_Jm xapyC	LtWGr6G0PRGB13					
WEB F	REFERENCES:						
1.	https://www.researchgate.net/						
2.	https://www.wipo.int/about-ip/en/						
ONLIN	IE COURSES:						
1.	https://onlinecourses.nptel.ac.in/noc23_ge36/preview						
2.	https://onlinecourses.nptel.ac.in/noc22_hs59/preview						

Mapping of COs with POs								
<u> </u>			P	Os				
COS	PO1	PO2	PO3	PO4	PO5	PO6		
CO1	3	2	1			1		
CO2	3	3		2				
CO3	3			3	1			
CO4	3	3						
CO5	2	2		2		1		
Average	2.8	2.5	1	2.33	1	1		

ME	23ET301	Version : 1.0							
Pro & B	gramme ranch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	СР 3	L 3	T 0	P 0	C 3		
Cou	ırse Objeo	ctives:							
1	To provid	e knowledge on the basics, building blocks of Embedded Sy	/stem						
2	To discus	s Input/output Interfacing & Bus Communication with proce	essor	5.					
3	To teach	automation using scheduling algorithms and Real time oper	rating	sys	tem				
4	To discus	s on different Phases & Modeling of a new embedded produ	ıct.						
5	To involve acquired	e Discussions/ Practice/Exercise onto revising & familiarizin over the 5 Units of the subject for improved employability s	g the skills	con	cept	ts			
UN	IT-I	INTRODUCTION TO EMBEDDED SYSTEMS			9				
Intr - s mar Cou asse Deb	oduction to election of nagement nting devicembler, co ougging(L2	D Embedded Systems(L1) -built in features for embedded of Embedded processor (L2)- DMA(L2)- memory de methods(L2)-memory mapping(L2), cache replacement ces, Watchdog Timer, Real Time Clock(L2)- Software Deve ompiler, linker, simulator, debugger, In circuit emula)- Overview of functional safety standards for embedded sy	Farge evices poli lopme tor, vstem	t Ard (L2) cies ent t Targ s(L2	chite - T cools et 2).	Me ime s(L2) Har	re(L2) emory r and)-IDE, dware		
UN	IT-II	EMBEDDED NETWORKING BY PROCESSORS			9				
Emb inte RS4 base	oedded Ne rrupt serv 85(L2)S-L ed on Wifi	tworking: Introduction, I/O Device Ports & Buses(L2)- r ice mechanism(L2) – Serial Bus communication protoc JSB(L2)–Inter Integrated Circuits (I ² C) (L2)- CAN Bus(L , Bluetooth, Zigbee(L2) – Introduction to Device Drivers(L2	nultip ols - _2) - 2).	le i RS2 Wire	nter 32 eless	rupt stan s pr	s and dard– otocol		
UN	IT– III	RTOS BASED EMBEDDED SYSTEM DESIGN			9				
Intr rout sche mer betv com	oduction t tines in RT eduling(L2), mory(L2), ween proce	to basic concepts of RTOS(L1)- Need, Task, process & TOS(L2), Multiprocessing and Multitasking(L2), Preemptive), Task communication- context switching, interrupt latence message passing(L2)-, Interprocess Communication(Lesses(L2)-semaphores, Mailbox, pipes, priority inversion, p Real time Operating systems: VxWorks, uC/OS-II, RT Linu	threa e and cy and 2) – priority x(L2)	ads(d no d de sy y inl	_2), n-p adli nch nerit	int reen ne s roni anc	errupt nptive hared zation e(L2),		
UN	IT – IV	MODELLING WITH HARDWARE/SOFTWARE DESIGN APPROACHES			9				
Mod UML App Sing para	lelling emb _ modeling roaches fo gle-process allelism in	bedded systems- embedded software development appro with UML, UML Diagrams(L3) Hardware/Software Parti or System Specification and modeling(L2)- CoSynthesis(L2 sor Architectures & Multi-Processor Architectures(L3) uniprocessors & Multiprocessors(L3).	ach(L tionin)- Fe -Desig	.2) ig(L2 atur gn	Ov 2), (es c app	vervi Co-E comp roac	ew of)esign paring :h on		
UN	ΙΤ-ν	EMBEDDED SYSTEM APPLICATION DEVELOPMENT			9				
Obje Emt stuc inpu	Objective, Need, different Phases & Modelling of the EDLC.choice of Target Architectures for Embedded Application Development-for Control Dominated-Data Dominated Systems-Case studies on Digital Camera, Adaptive Cruise control in a Car, Mobile Phone software for key inputs.								
			Tot	al :	45	PER	IODS		
		OPEN ENDED PROBLEMS / QUESTIONS					_		
Obje for Case inpu	Objective, Need, different Phases & Modelling of the EDLC(L2)- choice of Target Architectures for Embedded Application Development-for Control Dominated-Data Dominated Systems(L3)- Case studies on Digital Camera, Adaptive Cruise control in a Car, Mobile Phone software for key inputs(L3).								

C ours At the	se Outcomes: e end of this course, the students will	BLOOM'S Taxonomy					
CO1	Demonstrate the functionalities of processor internal blocks, with their requirement.	L2 - Understand					
CO2	Analyze that Bus standards are chosen based on interface L2 - Understand overheads without sacrificing processor performance						
CO3	Explain the role and features of RT operating system, that makes multitask execution possible by processors.	L2 - Understand					
CO4	Illustrate that using multiple CPU based on either hardcore or softcore helps data overhead management with processing- speed reduction for uC execution.L3 - Apply						
CO5	Recommend Embedded consumer product design based on L3 - Apply L3 - Apply						
REFE	RENCE BOOKS:						
1.	Rajkamal, 'Embedded System-Architecture, Programming, Design	′, TMH,2011.					
2.	Peckol, "Embedded system Design", JohnWiley&Sons,2010						
3.	Lyla B Das," Embedded Systems-An Integrated Approach", Pearso	n2013					
4.	EliciaWhite," Making Embedded Systems", O'Reilly Series, SPD,20	11					
5.	Bruce Powel Douglass, "Real-Time UML Workshop for Embedded S	Systems, Elsevier,2011					
6.	Advanced Computer architecture, By Rajiv Chopra, S Chand, 2010						
7.	Jorgen Staunstrup, Wayne Wolf, Hardware / Software Co-	Design Principles and					
8.	Shibu.K.V, "Introduction to Embedded Systems", Tata McGraw Hil	1,2009					
9.	Tammy Noergaard," Embedded System Architecture, A com Engineers and Programmers", Elsevier, 2006	prehensive Guide for					
10.	Giovanni De Micheli, Mariagiovanna Sami, Hardware / Softwar Academic Publishers, 2002	e Co- Design, Kluwer					
WEB F	EFERENCES:						
1.	https://www.ripublication.com/ijaer17/ijaerv12n18_113,						
2.	https://www.embedded.com/serial-protocols-compared/						
ONLIN	IE COURSES:						
1.	https://onlinecourses.nptel.ac.in/noc20_cs14/preview						
2.	https://onlinecourses.nptel.ac.in/noc21_cs08/preview						
VIDEC	REFERENCES:						
1.	https://www.youtube.com/watch?v=3RfqkVyvnnc						
2.	https://www.youtube.com/watch?v=U5CDf4TNARE						
3.	https://www.youtube.com/watch?v=Gkp753foAgE						

Mapping of COs with POs									
60			Р	0					
CO	PO1	PO2	PO3	PO4	PO5	PO6			
1	-	-	3	2	1	-			
2	2	-	1	2	-	-			
3	-	2	2	3	-	-			
4	2	-	3	3	-	-			
5	2	-	1	2	-	2			
Avg	2	2	2	2.4	1	2			
	1–Low, 2 –Medium, 3–High.								

ME	23ET302	SOFTWARE FOR EMBEDDED SYSTEMS	Version : 1						
Prog & Bi	gramme ranch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	CP 3	L 3	T 0	P 0	C 3		
Cou	rse Objec	tives:							
1	To expose	the students to the fundamentals of embedded Programm	ing						
2	To Introdu	ice the GNU C Programming Tool Chain in Linux.							
3	To study t	he basic concepts of embedded C.							
4	To teach t	he basics of Python Programming							
5	To involv acquired o	e Discussions/ Practice/Exercise onto revising & familion over the 5 Units of the subject for improved employability s	iarizir kills.	ng t	he	con	cepts		
UNI	T-I	BASIC C PROGRAMMING			9				
Typ Stru Con	ical C Pr uctured Pr ntrol(L2) -	ogram Development Environment - Introduction to C ogram Development in C (L2)- Data Types and Operat C Functions(L2) - Introduction to Arrays (L2).	Pro Pro: Pro:	grar .1) ·	nmii · C	ng(l Pro	.2) - gram		
UNI	T-II	EMBEDDED C			9				
Add Proj dela har	ling Struct ject and ays(L3) - dware time	ure to 'C' Code: Object oriented programming with C(Port(L2), Examples. Meeting Real-time constraints(L3) Need for timeout mechanism(L2) - Creating loop tim eouts(L3).	L2), : Cre eouts	Hea eatir s(L3)	der 1g) -	file harc Cre	s for Iware ating		
UNI	T– III	C PROGRAMMING TOOL-CHAIN IN LINUX			9				
C p (L3) Prot	reprocesso) - The Ma filing(L3) -	or(L2) - Stages of Compilation(L2) - Introduction to GCC(ke utility(L3) - GNU Configure and Build System(L3) - GNU using gprof(L3) - Introduction to GNU C Library(L2).	L2) - J Bina	De ary u	bugo utilit	ging ies(with L3) –		
UNI	T – IV	PYTHON PROGRAMMING			9				
Intr - Fu	oduction(L Inctions (L	 Parts of Python Programming Language(L2) - Control Strings Lists (L3)- Dictionaries (L3)- Tuples and Sets (L 	l Flow _3).	/ Sta	atem	nent	s(L3)		
UNI	T-V	MODULES, PACKAGES AND LIBRARIES IN PYTHON	9						
Pytl Libr Plot Libr	hon Modul raries for F tting Librar raries(L3).	es and Packages(L2) - Creating Modules and Packages(L3) Python(L3) - Library for Mathematical functionalities and Y(L3) - GUI Libraries for Python - Imaging Libraries for Pyt	- Pra Tools thon	actic (L3) (L3)	al E - N - Ne	xan lum etwo	nple - erical orking		
		Derjond Knowledge	Total : 45 PERIODS						
		OPEN ENDED PROBLEMS / QUESTIONS							
Cour prob the I	rse specifi lems can End semes	c Open Ended Problems will be solved during the class be given as Assignments and evaluated as Internal Assess ter Examinations.	s rooi smen	m te t on	each ly a	nd i	Such not for		
C ou	rse Outco	mes: his course, the students will demonstrate the ability to		BL	.00	M'S			
CO:	Demons 1 embedo	strate C programming and its salient features for led systems	L2	2 - U	nde	rsta	nd		
CO2	Deliver insight into various programming languages/software compatible to embedded process development with improved design & programming skills.					L3 - Apply			
CO	3 Develop	knowledge on C programming in Linux environment.	L2	2 - U	nde	rsta	nd		
CO4	4 Possess applicat	ability to write python programming for Embedded ions.	L3	8 - A	pply	,			
COS	Have in 5 due to progran	mproved Employability and entrepreneurship capacity knowledge up gradation on recent trends in embedded nming skills.	L3	8 - A	pply	,			

REFEF	RENCE BOOKS:
1.	Paul Deitel and Harvey Deitel, "C How to Program", 8th Edition, Pearson Education Limited, 2016.
2.	Michael J Pont, "Embedded C", Addison-Wesley, An imprint of Pearson Education, 2002.
3.	William von Hagen, "The Definitive Guide to GCC", 2nd Edition, Apress Inc., 2006.
4.	Gowrishankar S and Veena A, "Introduction to Python Programming", CRC Press, Taylor & Francis Group, 2019.
5.	Noel Kalicharan, "Learn to Program with C", Apress Inc., 2015.
6.	Steve Oualline, "Practical C programming", O'Reilly Media, 1997.
7.	Fabrizio Romano, "Learn Python Programming", Second Edition, Packt Publishing, 2018.
8.	John Paul Mueller, "Beginning Programming with Python for Dummies", 2nd Edition, John Wiley & Sons Inc., 2018.
9.	Mark Lutz, "Programming Python", 4th Edition, O'Reilly Media Inc., 2010.
WEB	REFERENCES:
1.	https://www.javatpoint.com/gcc-linux
2.	https://www.geeksforgeeks.org/python-set-3-strings-lists-tuples-iterations/
ONLI	INE COURSES:
1.	https://onlinecourses.nptel.ac.in/noc19_cs41/preview
2.	https://onlinecourses.nptel.ac.in/noc19_cs41/preview
VIDE	O REFERENCES:
1.	https://www.youtube.com/watch?v=XTiIiILOY8&list=PLEAYkSg4uSQ2k6GwNhpgSHodG T8wfvgwu
2.	https://www.youtube.com/watch?v=c235EsGFcZs
3.	https://www.youtube.com/watch?v=c235EsGFcZs
	The second second

Mapping of COs with POs										
60		PO								
CO	P01	PO2	PO3	PO4	PO5	PO6				
1	-	-	2	-	3	-				
2	1)0 -	1 1 1//	-/ /	2	-				
3	-	7)02/011	a (_)))	ron <u>r</u> edg	° 2	-				
4	1	<u>~</u>	1	1	1	-				
5	-	-	2	2	3	2				
Avg	1	2	1.5	1.5	2.2	2				
	1–Low, 2–Medium, 3–High.									

ME	23ET303	MICROCONTROLLER BASED SYSTEM DESIGN	Version : 1.0				D	
Prog & B	gramme ranch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	СР 3	L 3	Т 0	P 0	C 3	
Cou	Course Objectives:							
1	To teach t	he architecture of PIC Microcontroller and RISC processor.						
2	To compa	re the architecture and programming of 8, 16, 32 bit RISC p	rocess	sor.				
3	To teach t	he implementation of DSP in ARM processor.						
4	To discuss	on memory management, application development in RISC	proce	esso	r.			
5	To involv acquired o	e Discussions/ Practice/Exercise onto revising & familia over the 5 Units of the subject for improved employability ski	rizing Ils.	the	e c	onc	epts	
UN	IT-I	PIC MICROCONTROLLER			9			
Arc PIC Tim	hitecture(L programn ier program	2) – memory organization(L2) – addressing modes(L2) – i ning in Assembly & C(L3) –I/O port, Data Conversion, RAM nming, practice in MP-LAB(L3).	instru M & F	ctio ROM	n se All	et (l ocat	_3)- :ion,	
UN	IT-II	ARM ARCHITECTURE			9			
Arc mo Stru	hitecture(L del (L2)–R ucture(L2)	2) – memory organization(L2) – addressing modes(L2) –The Registers(L2) – Pipeline (L2)- Interrupts(L2) – Coprocess	e ARM ors (1 Pro [L2)-	ogra - I	amm nter	ier's rupt	
UN	IT– III	PERIPHERALS OF PIC AND ARM MICROCONTROLLER			9			
PIC Mer Cor	: ADC, DA mory (L3)- nmunicatio	AC and Sensor Interfacing(L3) –Flash and EEPROM memore - EEPROM (L3)– I/O Ports (L3)– SRAM(L3) –Timer (L3)- on with PC – ADC/DAC Interfacing(L3).	ories(-UART	L3). Г (L	AF 3)	RM: - S	I/O erial	
UN	IT – IV	ARM MICROCONTROLLER PROGRAMMING			9			
ARN Imp	4 general 3 plementation	Instruction set(L2) – Thumb instruction set (L2)–Introduction example of Filters(L3)	on to	DSF	or or	n AR	М –	
UN	IT-V	DESIGN WITH PIC AND ARM MICROCONTROLLERS	9					
PIC - C Acq tab	implemen Controlling Juisition Sy le- Block co	tation - Generation of Gate signals for converters and Inver DC/ AC appliances (L3)– Measurement of frequency(L3) stem(L3) –ARM Implementation(L3)- Simple ASM/C progra opy- subroutines-Hamming Code.(L3)	rters - St ms- L	- Mc and oop	otor aloı s -	Cor ne [Lool	ntrol Data < up	
			Tota	l : 4	5 F	PER	ODS	
Cour prob	rse specifie lems can	OPEN ENDED PROBLEMS / QUESTIONS c Open Ended Problems will be solved during the class be given as Assignments and evaluated as Internal Assess ter Examinations	room nent	tea only	chi an	ng. d no	Such ot for	
Cou	rse Outco At the end	of this course, the students will have the ability to		BL(Tax	00 one	M′S omy	1	
CO	1 Underst blocks.	and the basics and requirement of processor functional	L3	- A	pply	/		
CO	2 Observe	e the specialty of RISC processor Architecture.	L2	- U	nde	rsta	nd	
CO	3 Incorpo automa	rate I/O hardware interface of a processor based tion for consumer application with peripherals.	L3	- A	pply			
CO4	4 Incorpo	rate I/O software interface of a processor with peripherals.	L3	- A	pply	/		

CO5	Improved Employability and entrepreneurship capacity due to knowledge up gradation on recent trends in commercial embedded processors	L3 - Apply
REFER	RENCE BOOKS:	
1.	Steve Furber, 'ARM system on chip architecture', Addision Wesley, 20	010.
2.	Andrew N. Sloss, Dominic Symes, Chris Wright, John Rayfield 'ARM Guide Designing and Optimizing System Software', Elsevier 2007.	System Developer's
3.	Muhammad Ali Mazidi, Rolin D. Mckinlay, Danny Causey 'PIC Microco and Embedded Systems using Assembly and C for PIC18', Pearson E	ontroller Education 2008.
4.	John Iovine, 'PIC Microcontroller Project Book', McGraw Hill 2000	
5.	William Hohl, 'ARM Assembly Language' Fundamentals and Techniqu	ıes,2009.
6.	Rajkamal," Microcontrollers Architecture, Programming, Interfacing Pearson,2012	, & System Design,
7.	ARM Architecture Reference Manual, LPC213x User Manual	
8.	www.Nuvoton .com/websites on Advanced ARM Cortex Processors	
WEB I	REFERENCES:	
1.	https://piembsystech.com/arm-microcontroller/	
2.	https://www.elprocus.com/introduction-to-pic-microcontrollers-and	d-its-architecture/
ONLI	NE COURSES:	
1.	https://nptel.ac.in/courses/108102045	
2.	https://archive.nptel.ac.in/courses/106/105/106105193/	
VIDEC	D REFERENCES:	
1.	https://www.youtube.com/watch?v=0xgvINDxXJI&list=PLbRMhDVU On7DmSfuU	UMngcJu5oUhgpgYqt
2.	https://www.youtube.com/watch?v=y9RAhEfLfJs&list=PL419D0518	8A8E82285
3.	https://www.youtube.com/watch?v=30myM4-zuQw&t=1s	
	SRIEM	

Mapping of COs with POs									
<u> </u>			Р	0					
CO	P01	PO2	PO3	PO4	PO5	PO6			
1	-	1)011011	d 2/11	and odge	-	-			
2	1	-/	3	2	-	-			
3	-	-	1	3	1	-			
4	1	-	-	1	2	-			
5	-	-	2	-	-	-			
Avg	1	-	2	2	1.5	-			
		1-Low.	2 – Medium, 3	B-Hiah.					

ME	23ET304	VLSI DESIGN AND RECONFIGURABLE ARCHITECTURE	Version : 1				.0		
Prog & Bi	gramme ranch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	СР 3	C 3					
Cou	rse Objec	tives:							
1	1 To expose the students to the fundamentals of sequential system design, synchronous and Asynchronous circuits.								
2	To unders	tand the basic concepts of CMOS and to introduce the IC fab	ricat	ion	meth	nods			
3	To introd architectu	uce the Reconfigurable Processor technologies, To prov re significance of SOC.	ide	an	insig	ght a	and		
4	To introdu	ce the basics of analog VLSI design and its importance.							
5	To learn Language	about the programming of Programmable device using $ imes$	lardv	vare	des	script	tion		
U	NIT-I	INTRODUCTION TO ADVANCED DIGITAL SYSTEM DESIGN			9				
Moo Des Con Haz	deling of sign of A stroller(L3) ard free ci	Clocked Synchronous Sequential Network (CSSN)(L2), D Asynchronous Sequential Circuits (ASC)(L3), Designing , Races in ASC, Static and Dynamic Hazards, Essential rcuits(L3).	esig Ve Haz	n of endii ards	f CS ng 5, De	SN(I Mach esigr	_3), nine ning		
ι	JNIT-II	CMOS BASICS & IC FABRICATION			9				
Moo rati Trai Dia	ore's Law-N os- CMOS nsmission grams, Des	1OSFET Scaling(L2) - MOS Transistor Model-Determination of based combinational logic & sequential design(L3)- Gates(L3)- BiCMOS- Low power VLSI – CMOS IC Fabr sign Rules and Layout(L3).	of pu Dyr icati	ll up nami ons((/ pi c C (L2)	ull do MOS - S	own 5 – tick		
U	NIT- III	ASIC AND RECONFIGURABLE PROCESSOR AND SoC DESIGN			9				
Intr reco reco con	oduction onfigurable ent trends trol(L3).	to ASIC(L2), ASIC design flow- programmable ASICs(L processor- Architecture(L2) -Reconfigurable Computing(in Reconfigurable Processor & SoC, Reconfigurable process	2)- L2), sor l	Intr So base	oduo C Ov d D0	ction vervi C mo	to ew, otor		
U	NIT – IV	ANALOG VLSI DESIGN SALEM			9				
Intr and FPA	oduction t High fre	o analog VLSI(L2)- Design of CMOS 2stage(L3)-3 stage O equency op-amps-Super MOS- Analog primitive cells(L	p-Ar 3)-	np - Intr	-Higl oduc	n Sp ction	eed to		
	UNIT-V	DESIGN WITH PIC AND ARM MICROCONTROLLERS			9				
Ove con ahe	erview of cepts(L2)- ad adders,	digital design with VHDL, structural, data flow and b logic synthesis-simulation-Design examples, Ripple carry Multiplier, ALU, Shift Registers, Test Bench(L3).	oeha Add	viora ers,	al n Car	node ry L	ling ook		
		Г <u> </u>	Tot	al :	45 F	PERI	ODS		
		OPEN ENDED PROBLEMS / QUESTIONS							
Cour prob the I	rse specifie lems can l End semes	c Open Ended Problems will be solved during the class be given as Assignments and evaluated as Internal Assessr ter Examinations.	roon nent	n te : onl	achi y an	ng. d no	Such ot for		
Cou	rse Outco	mes:		BI T-	.00	M'S			
CO	Incorpo clocked	rate synchronous and asynchronous switching logics, with circuits design	L	3 - /	Apply	/			
co	2 Deliver fabricat	insight into developing CMOS design techniques and IC ion methods.	L	3 - /	Apply	/			
CO	B Explain Co desig	the need of reconfigurable computing, hardware-software on and operation of SoC processor.	L	3 - /	Apply	/			

Design and development of reprogrammable analog devices and its usage for Embedded applications.	L3 - Apply
Illustrate and develop HDL computational processes with improved design strategies.	L3 - Apply
RENCE BOOKS:	
Donald G. Givone, "Digital principles and Design", Tata McGraw Hill	2002.
Charles H. Roth Jr., "Fundamentals of Logic design", Thomson Learn	ing, 2004.
Nurmi, Jari (Ed.) "Processor Design System-On-Chip Computing fo Springer, 2007.	r ASICs and FPGAs"
Joao Cardoso, Michael Hübner, "Reconfigurable From FPGAs to Hardware/Software Codesign" Springe	Computing: er, 2011.
Pierre-Emmanuel Gaillardon, Reconfigurable Logic: Arch Applications, 1 st Edition, CRC Press, 2015	nitecture, Tools, and
Mohamed Ismail ,TerriFiez, "Analog VLSI Signal and information F Hill International Editions,1994.	Processing", McGraw
William J. Dally / Curtis Harting / Tor M. Aamodt," Digital De Systems Approach, Cambridge Univerity Press, 2015.	esign Using VHDL:A
Zainalatsed in Navabi, 'VHDL Analysis and Modelling of Digital Stata McGraw Hill, 1998.	ystems', 2n Edition,
REFERENCES:	
https://archive.nptel.ac.in/courses/108/106/108106177/	
https://nptel.ac.in/courses/117101058	
NE COURSES:	
https://onlinecourses.nptel.ac.in/noc20_cs14/	
https://onlinecourses.nptel.ac.in/noc21_ee39/	
D REFERENCES:	
https://www.youtube.com/watch?v=oL8SKNxEaHs&list=PLLy_2iUC0 TnFCUmM	687Bdulp9brz9AcvW_
https://www.youtube.com/watch?v=BoIOLczVulQ&list=PLyqSpQzTE	6M_dZdF7Bd-
	Design and development of reprogrammable analog devices and its usage for Embedded applications. Illustrate and develop HDL computational processes with improved design strategies. EENCE BOOKS: Donald G. Givone, "Digital principles and Design", Tata McGraw Hill 2 Charles H. Roth Jr., "Fundamentals of Logic design", Thomson Learn Nurmi, Jari (Ed.) "Processor Design System-On-Chip Computing fo Springer, 2007. Joao Cardoso, Michael Hübner, "Reconfigurable From FPGAs to Hardware/Software Codesign" Springer Pierre-Emmanuel Gaillardon, Reconfigurable Logic: Arch Applications, 1 st Edition, CRC Press , 2015 Mohamed Ismail ,TerriFiez, "Analog VLSI Signal and information F Hill International Editions,1994. William J. Dally / Curtis Harting / Tor M. Aamodt," Digital De Systems Approach, Cambridge Univerity Press,2015. Zainalatsed in Navabi, "VHDL Analysis and Modelling of Digital So Tata McGraw Hill, 1998. REFERENCES: https://archive.nptel.ac.in/courses/108/106/108106177/ https://nptel.ac.in/courses/117101058 VE COURSES: https://onlinecourses.nptel.ac.in/noc20_cs14/ https://onlinecourses.nptel.ac.in/noc21_ee39/ D REFERENCES: https://www.youtube.com/watch?v=0L8SKNxEaHs&list=PLLy_2iUCC TnFCUmM https://www.youtube.com/watch?v=BoIOLczVulQ&list=PLyqSpQzTE parts = 10/kYE

Mapping of COs with POs										
60	PO									
CO	PO1	PO2	PO3	PO4	P05	PO6				
1	-	_/	-	1	-	-				
2	2	-	2	2	-	-				
3	-	-	3	3	2	1				
4	2	-	2	3	1	-				
5	-	1	1	3	3	1				
Avg	2	1	2	2.4	2	1				
	1-Low, 2-Medium, 3-High,									

SALEW

N	1E23ET305	EMBEDDED SYSTEMS- I LABORATORY	Version : 1.0				.0			
Prog Bra	gramme & nch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	CP L T P 4 0 0 4							
Cou	Course Objectives:									
1	1 To involve the students to Practice on Workbench /Software Tools/ Hardware Processor Boards with the supporting Peripherals.									
2	To teach the o Digital process	concepts of algorithm development & programming ors with peripheral interfaces.	on so	oftwa	are t	:ools	s and			
3	To encourage s	students to practice in open source software / package	es /too	ols						
4	To train though	hands-on practices in commercial and licensed Hard	ware-	softv	ware	sui	tes			
5	Practicing thro students into t	ugh the subdivisions covered within experiments listener he revising the concepts acquired from theory subjects	ed bel s.	ow t	o ex	cpos	e the			
List	of Experimen	ts / Exercises								
1.	Programming i	n Embedded C / Higher Level Language								
2.	Programming i	n 8 bit Microcontrollers								
3.	I/O Programmi Interrupts &am	ng in 8 bit Microcontrollers I/O & Serial Program p; Motor Control, ADC/DAC, LCD.	ming,	Tim	ers,					
4.	Programming i	n 8 bit PIC Microcontrollers								
5.	I/O Programmi programming/I Interfacing	ng in AVR / PIC Microcontrollers Timers/ Interrupts/Se PWM Generation/Motor Control/ADC/DAC/ LCD/ RTC, 3	erial p Interfa	ort, acing	g/ S	enso	or			
6.	Programming i	n Arduino Microcontrollers								
7.	VHDL Program	ming in FPGA processors								
8.	Verilog HDL Pro	ogramming in FPGA processors								
9.	Programming 8	amp; Simulation in Simulators /Tools/others (Proteu	s / Or	CAD))					
10.	Programming 8	& amp; Simulation in simulators / Tools/others (LabVI	EW / I	MatL	AB)					
			То	tal :	60	PEF	RIODS			
C ou At th	r se Outcomes ne end of this co	ourse, the students will have the ability to		Bl Ta:	-00 xon	M'S omy	; Y			
со	Experiment 1 and RISC peripheral in	insight into various embedded processors of CISC architecture / computational processors with terface.	L1	- R	eme	mbe	er			
со	2 Understand controlled w	the fundamental concepts of how process can be th uC.	L2	- U	nder	star	nd			
СО	3 Experimentii software suit	ng on programming logic of Processor based on ces(simulators, emulators)	L2	- U	nder	star	nd			
СО	4 Incorporate peripherals.	I/O software interface of a processor with	L3	- A	pply					
со	Improved E 5 knowledge u of commerci	mployability and entrepreneurship capacity due to p gradation on recent trends in interfacing and use al embedded processors	L3	- A	pply					

REFE	RENCE BOOKS:
1.	Mohamammad Ali Mazidi&Mazidi ` 8051 Microcontroller and Embedded Systems', Pearson Education
2.	Mohammad Ali Mazidi, Rolind Mckinley and Danny Causey, 'PIC Microcontroller and Embedded Systems' Pearson Education
3.	Simon Monk," Make Action-with Arduino and Raspberry Pi,SPD ,2016.
4.	Wesley J.Chun,"Core Python Applications Programming,3 rd ed,Pearson,2016
5.	Kraig Mitzner, 'Complete PCB Design using ORCAD Capture and Layout', Elsevier
6.	Vinay K.Ingle,John G.Proakis,"DSP-A Matlab Based Approach", Cengage Learning,2010.
7.	Taan S.Elali,"Discrete Systems and Digital Signal Processing with Matlab",CRC Press2009.
8.	JovithaJerome," Virtual Instrumentation using Labview" PHI,2010.
9.	Woon-Seng Gan, Sen M. Kuo, 'Embedded Signal Processing with the Micro Signal Architecture', John Wiley & Sons, Inc., Hoboken, New Jersey 2007
10.	Dogan Ibrahim, 'Advanced PIC microcontroller projects in C', Elsevier 2008

Mapping of COs with POs								
<u> </u>			P	0				
CO	PO1	PO2	PO3	PO4	PO5	P06		
1	2	2 1	2	1	-	-		
2	-	-	1	10	2	1		
3	2	3	1	2	3	-		
4	2		2	1	2	-		
5	-	-	1	1	3	2		
Avg	2	2	S F1.48	1.2	2.5	1.5		

Beyond Knowledge

М	E23PT801	TECHNICAL SEMINAR / CASE STUDY PRESENTATION	Version : 1.0)	
		(COMMON TO ALL BRANCHES)						
Programme & Branch			СР	L	Т	Ρ	С	
		M.E. EMBEDDED STSTEM TECHNOLOGIES	2	0	0	2	0	
Co	urse Object	ives:						
1	To encoura	age the students to study advanced engineering developm	nents					
2	To prepare and present the technical and case study reports							
Method of Evaluation:								

The students need to identify an area of interest or topic in their programme of study or case study and prepare a 5-10 page report and a presentation. Based on the report and presentation, the course is evaluated for 100 marks. Minimum 50 marks is essential to pass. In case a student fails, he has to make such presentation in the subsequent semesters. The evaluation guidelines will be issued by the Head of the Department before the commencements of the course. The objectives are improving literature searching capabilities, comprehension and ability to write reports and to make presentations. It is assessed in Internal Assessment mode only and no End Semester Examination.

	3 68 43. 5	Total : 30 PERIODS
Cour Upon	rse Outcomes: completion of this course the students will be able to:	BLOOM'S Taxonomy
C01	Perform the review and present technological developments in their field	L3 - Apply
CO2	Interpret the case study report and make a decision	L3 - Apply

Beyond Knowledge									
		Mappi	ng of COs wi	th POs					
60			P	0					
0	PO1	PO2	PO3	PO4	PO5	P06			
1		3							
2		3							
Avg		3							
	1–Low, 2 –Medium, 3–High.								



ME	23ET306	REAL TIME OPERATING SYSTEM	Version : 1.0			D			
		(COMMON TO ALL BRANCHES)							
Prog Brai	gramme & nch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	CP 3	L 3	Т 0	P 0	С 3		
Cou	rse Object	ives:	-	-	-	-	-		
1	To expose	the students to the fundamentals of interaction of OS with	haco	ompi	uter a	ınd l	Jser		
2	2 To teach the fundamental concepts of how process are created and controlled with OS.								
3	3 To study on programming logic of modeling Process based on range of OS features								
4	To compare	e types and Functionalities in commercial OS, application dev	elopm	nent	using	RTC	S		
5	To involve over the 5	Discussions/ Practice/Exercise onto revising & familiarizing Units of the subject for improved employability skills	the	conc	epts	acqu	ired		
1	UNIT-I	REVIEW OF OPERATING SYSTEMS			9				
Ba Pr (L	asic Princip ocesses(L2) 2)– Introdu	les (L1)- Operating System structures (L2)- System C – Design and Implementation of processes – Communica ction to Distributed operating system – Embedded operating	Calls(L tion b syste	2) - etwe ms(L	- File een p .2)	es(L2 roce) – sses		
	UNIT-II	OVERVIEW OF RTOS			9				
RT Sy Se	TOS Task nchronizati maphores(and Task state(L2) –Multithreaded Preemptive s on- Message queues(L2)– Mail boxes(L2) -pipes(L2) – L2) – Classical synchronization problem(L2) – Deadlocks(L2).	chedu Critio	ller(l cal	_2)- sectio	Pro n(L2	cess) –		
I	JNIT- III	REALTIME MODELS AND LANGUAGES			9				
Ev Ta -	vent Based asks – RT so Memory Re	 Process Based and Graph based Models(L2) - Real Time cheduling(L2) - Interrupt processing(L2) - Synchronization (quirements(L2). 	e Lang L2)-	juag Cont	es(L2 rol Bl)– R ocks	TOS (L2)		
l	JNIT – IV	REALTIME KERNEL	9						
Pr Co Ex	inciples (L2 omparison a cecutive(L2))- Design issues(L2) - Polled Loop Systems(L2) - RTOS Po and Basic study of various RTOS like - VX works - Linux	orting < sup	to a porti	Targ ve R1	et (I TOS	_2)- - C		
	UNIT-V	APPLICATION DEVELOPMENT			9				
Di RT	scussions o FOS Applica	n Basics of Linux supportive RTOS(L2) – Ucos(L2)-C Execu tion(L3) – Case study(L3)	tive fo	or de	evelop	omer	ıt of		
			Т	otal	: 45	PER	IODS		
Cou	r se Outcor At the end	nes: of this course, the students will have the ability to		BI Ta	-OOM xono	l′S my			
СО	1 Outline (Operating System structures and types.	L2 – Understand						
CO	CO2 Insight into scheduling, disciplining of various processes execution.				L2 – Understand				
CO3 Illustrate knowledge on various RTOS support modelling				L2 – Understand					
CO	4 Demonst	rate commercial RTOS Suite features to work on real time s design.	L2 – Understand						
CO	Improve 5 knowled automat	d Employability and entrepreneurship capacity due to ge up gradation on recent trends in RTOS and embedded on design.	L3 - Apply						

REFERENCE BOOKS:					
1.	Silberschatz, Galvin, Gagne" Operating System Concepts, 6th ed, John Wiley, 2003				
2.	Charles Crowley, "Operating Systems-A Design Oriented approach" McGraw Hill, 1997				
3.	Raj Kamal, "Embedded Systems- Architecture, Programming and Design" Tata McGraw Hill,2006.				
4.	Karim Yaghmour, Building Embedded Linux System", O'reilly Pub, 2003				
5.	MukeshSighal and N G Shi "Advanced Concepts in Operating System", McGraw Hill, 2000				
WEB	REFERENCES:				
https	://nptel.ac.in/courses/106108101				
https	://docplayer.net/21051759-Real-time-operating-systems-lesson-10.html				
ONL	INE COURSES:				
https	://archive.nptel.ac.in/courses/106/105/106105172/				
https	://onlinecourses.nptel.ac.in/noc21_cs98/				
VIDE	O REFERENCES:				
https	://www.youtube.com/watch?v=a5n8TMNbyrg				
https	://www.youtube.com/watch?v=dHsHP9RrXBw&t=518s				
https	://www.youtube.com/watch?v=qfiSgisz6Ug				

Mapping of COs with POs and PSOs								
60			Р	0				
CO	1	2	3	4	5	6		
1	2	44	1		2	-		
2	-	-	S 2 - M		3	1		
3	2	-	2	1	2	2		
4	2	2	3	2	1	3		
5	-)/) -	1 1 1//	-///	3	1		
Avg.	2	DO21011	1.8	1011 15 00	(2.2	1.75		
1-Low, 2 -Medium, 3-High.								

ME23ET307

EMBEDDED SYSTEM NETWORKING

Version : 1.0

(COMMON TO ALL BRANCHES)

Programme & M.E. EMBEDDED SYSTEM TECHNOLOGIES Branch
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Course Objectives:

 To expose the students to the fundamentals of wired embedded networking techniques. To introduce the concepts of embedded ethernet. To expose the students to the fundamentals of wireless embedded networking. To discuss the fundamental building blocks of digital instrumentation. To introduce design of Programmable measurement & control of electrical Device.
 To expose the students to the fundamentals of wired embedded networking techniques. To introduce the concepts of embedded ethernet. To expose the students to the fundamentals of wireless embedded networking. To discuss the fundamental building blocks of digital instrumentation.
 To expose the students to the fundamentals of wired embedded networking techniques. To introduce the concepts of embedded ethernet. To expose the students to the fundamentals of wireless embedded networking.
 To expose the students to the fundamentals of wired embedded networking techniques. To introduce the concepts of embedded ethernet.
1 To expose the students to the fundamentals of wired embedded networking techniques.

Embedded networking: Introduction(L1) – Cluster of instruments in System(L2): Introduction to bus protocols (L2)– comparison of bus protocols – RS 232C, RS 422, RS 485 and USB standards (L2)– embedded ethernet (L2)– MOD bus, LIN bus and CAN bus(L2).

UNIT-II EMBEDDED ETHERNET

Elements of a network(L2) – Inside Ethernet – Building a Network : Hardware options – Cables, Connections and network speed – Ethernet controllers(L2) – Inside the internet protocol – Exchanging messages using UDP and TCP(L2) – Email for Embedded systems using FTP (L2)– Keeping devices and network secure(L2)

UNIT- III WIRELESS EMBEDDED NETWORKING

Wireless sensor networks – Introduction (L2)– Node architecture (L2)– Network topology(L2) -Localization (L2)– Time synchronization (L2)– Energy efficient MAC protocols(L2) – SMAC (L2)– Energy efficient and robust routing(L2) – Data centric routing(L2) - WSN Applications-Home Control - Building Automation - Industrial Automation(L3)

UNIT – IV BUILDING SYSTEM AUTOMATION 9

Sensor Types & Characteristics: Sensing Voltage, Current, flux, Torque, Position, Proximity, Accelerometer(L2) - Data acquisition system(L2)- Signal conditioning circuit design(L2)- Uc Based & PC based data acquisition (L2)- UC for automation and protection of electrical appliances (L3)-processor based digital controllers for switching Actuators: Stepper motors, Relays (L3)-System automation with multi-channel Instrumentation and interface(L3)

UNIT-V COMMUNICATION FOR LARGE ELECTRICAL SYSTEM

Data Acquisition, Monitoring, Communication, Event Processing, and Polling Principles(L2), SCADA system principles(L2) – outage management(L2)– Decision support application(L2) – substation automation(L2), extended control feeder automation(L2), Performance measure and response time, SCADA Data Models, need, sources, interface(L2)

Total: 45 PERIODS Course Outcomes: BLOOM'S At the end of this course, the students will have the ability to Taxonomy Analyze the different bus communication protocols used for CO1 L2 - Understand embedded networking CO2 Explain the basic concepts of embedded networking L2 - Understand CO3 Apply the embedded networking concepts in wireless networks L3 - Apply CO4 Relate different data acquisition concepts L3 - Apply

CO5	Build a system automation for different applications	L2 - Understand					
REFE	RENCE BOOKS:						
1.	Mohammad Ilyas And ImadMahgoub, 'Handbook of sensor Networks: and wired sensing systems', CRC Press,2005	Compact wireless					
2.	Peter W Gofton , "Understanding Serial Communication", Sybes Interr	national, 2000					
3.	Jan Axelson 'Embedded Ethernet and Internet Complete', Penram pub	lications					
4.	Krzysztof Iniewski, "Smart Grid , Infrastructure& Networking", TMcGH, 2	012					
5.	Control and automation of electrical power distribution systems, Jame Robert Wilson, CRC, Taylor and Francis, 2006	s Northcote-Green,					
WEB	REFERENCES:						
https	://archive.nptel.ac.in/courses/106/105/106105217/						
https	://archive.nptel.ac.in/courses/106/105/106105160/						
ONL	INE COURSES:						
https	://archive.nptel.ac.in/courses/106/105/106105217/						
https	://archive.nptel.ac.in/courses/106/105/106105081/						
VIDE	O REFERENCES:						
https	://www.youtube.com/watch?v=0RFYDNG6IU4						
https	://www.youtube.com/waStch?v=KCcdF4IVrQk&t=4s						
https Pc	https://www.youtube.com/watch?v=ycaz99NogS4&list=PLJ5C_6qdAvBHroAfekCO7K4xphEF74U Pc						

Pc

PO							
СО	1	2	3	4	5	6	
1	1	2	Coff - Way		3	1	
2	-	2	20	6	2	1	
3	3	2	2	3	2	3	
4	2		3	3	-	2	
5	3	-	5-3-M	3	-	2	
Avg.	2.25	2	2.7	3	2.3	1.8	
1-Low, 2 -Medium, 3-High.							
		Benon	d Ki	omleda	U		

ME23ET308 EMBEDDED CONTROL FOR ELECTRIC DRIVES					Version : 1.0				
		(COMMON TO ALL BRANCHES)							
Prog Brai	gramme & nch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	СР 3	L 3	T O	Р 0	C 3		
Cou	rse Objectives	:							
1	To provide the	control concept for electrical drives							
2	To emphasis th	e need for embedded system for controlling the electrication	al driv	/es					
3	To provide kno drives	wledge about various embedded system based control st	trateg	jy fo	r ele	ectri	cal		
4	To Impart the l	knowledge of BLDC Motor Control							
5	To familiarize t	he high performance computing for electrical drives.							
	UNIT-I	INTRODUCTION ELECTRICAL DRIVES			9				
	Electric drive a various factors Machine learni drives application	nd its classifications(L2), Four-quadrant drive, Depende (L2), Dynamics of motor-load combination-Solid State (ng and optimization techniques for electrical drives(L ons(L3).	nce c Contr .3)- I	of loa ollec oT f	ad t Dr or	orqu ives Elec	e on (L3)- trical		
	UNIT-II	OVERVIEW OF EMBEDDED PROCESSOR			9				
	Embedded Pro Programming w	ocessor architecture(L2)-RTOS(L2) – Hardware/soft ith SoC processors(L3).	ware	CO	-des	sign	(L2)-		
	UNIT– III	INDUCTION MOTOR CONTROL			9				
	Types(L2)- Spe motor- Fuzzy lo phase induction	ed control methods(L2)-PWM techniques(L2)- VSI fed to ogic Based speed control for three phase induction mo motor control(L3)	three tor-Fl	-pha PGA	se i bas	ndu ed t	ction hree:		
	UNIT – IV	BLDC MOTOR CONTROL	9						
	Overview of B processor based	LDC Motor(L2) -Speed control methods (L2)-PWM to BDLC motor control(L2)- ANN for BLDC Motor control a	echni Ind op	ques perat	(L2 cion)- A (L3)	\RM		
	UNIT-V	SRM MOTOR CONTROL			9				
	Overview of SR SRM motor con	M Motor(L2) -Speed control methods(L2) -PWM technic trol(L2)- DNN for SRM Motor control and operation(L3)	ques(L2)-	FPC	GA b	ased		
			Tota	hl : 4	5 P	ERI	ODS		
C ou	r se Outcomes : At the end of th	is course, the students will have the ability to		BLC Tax)ON ono	1′S mv			
СО	1 Interpret the	significance of embedded control of electrical drives		L3 -	- Ap	ply			
СО	2 Deliver insig	ht into various control strategy for electrical drives.	L3 – Apply						
СО	3 Developing k techniques fo	mowledge on Machine learning and optimization or motor control.	L3 – Apply						
СО	4 Develop emb as Electric ve	Develop embedded system solution for real time application such as Electric vehicles and UAVs.				L3 – Apply			
со	Improved En 5 knowledge u skills require	nployability and entrepreneurship capacity due to p gradation on recent trends in embedded system d for motor control strategy.	L3 – Apply						
REF	ERENCE BOOK	S:							
1.	Krishnan, "E Pvt. Ltd., Ne	lectric Motor Drives – Modeling, Analysis and Control",F w Delhi,2010.	Prenti	ce-H	all	of Ir	ndia		

2.	VedamSubramanyam, "Electric Drives – Concepts and Applications", Tata McGraw- Hill publishing company Ltd., New Delhi, 2002				
3.	K. Venkataratnam ,Special Electrical Machines, Universities Press, 2014.				
4.	Steve Furber, 'ARM system on chip architecture', Addision Wesley,2010.				
5.	Ron Sass and AnderewG.Schmidt, " Embedded System design with platform FPGAs: Principles and Practices", Elsevier, 2010.				
6.	Steve Kilts, "Advanced FPGA Design: Architecture, Implementation, and Optimization" Willey, 2007				
WEB REFERENCES:					
https:	//www.slideshare.net/udaywankar/arm-processor-based-speed-control-of-bldc-motor				
ONLINE COURSES:					
https:	//nptel.ac.in/courses/108104011				

https://onlinecourses.nptel.ac.in/noc22_ee94/

VIDEO REFERENCES:

https://www.youtube.com/watch?v=31hUDWjzLjY

https://www.youtube.com/watch?v=Gkp753foAgE

		Mapping of COs with POs and PSOs									
	РО										
1	2	3	4	5	6						
1	- //	2		2	-						
1	1 10	3	1 0	-	2						
2	- 0		- I	3	-						
1	2 4	3	1 2	-	-						
-			- O	3	-						
1.66	1.5	2.7	1 5	2.7	2						
	1 1 2 1 - 1.66	1 2 1 - 1 1 2 - 1 2 - - 1.66 1.5	1 2 3 1 - 2 1 1 3 2 - - 1 2 3 - - - 1.66 1.5 2.7	1 2 3 4 1 - 2 - 1 1 3 - 1 1 3 - 2 - - - 1 2 3 1 - - - - 1.66 1.5 2.7 1	1 2 3 4 5 1 - 2 - 2 1 1 3 - - 2 - - - 3 1 2 3 1 - - - - 3 1 2 3 1 - - - - 3 1.66 1.5 2.7 1 2.7						

Beyond Knowledge

I	ME23MC701	UNIVERSAL HUMAN VALUES AND ETHICS	Version: 1.0					
		(COMMON to ALL BRANCHES)						
Prog Brai	gramme & nch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	СР 3	L 2	T 1	P 0	C 3	
Cou	rse Objectives	:						
1.	To understand	the concept of Universal Human Values.						
2. To discuss theoretical and practical implications of UHV.								
3.	To relate the	se of harmony in the family and society.						
4.	To classify the	harmony in the nature methods.						
5.	To construct e	ffective human values in personal and professional in life.						
UNI	T-I	INTRODUCTION TO VALUE EDUCATION			9			
Right Educ as th Aspir Scen	Understanding ation) (L2) - U e Process for V ations (L1) - I ario (L2) - Meth	(L2), Relationship and Physical Facility (L2) (Holistic Developm Inderstanding Value Education (L2) - Sharing about Oneself (L alue Education (L2) - Continuous Happiness and Prosperity (L2 exploring Human Consciousness (L2) - Happiness and Prosp od to Fulfil the Basic Human Aspirations (L2) - Exploring Natur	nent 2) -) – t erity al Ac	and Self he B (L2) cept	the -exp asic) – ance	Role lorat Hum Curre	of ion an ent).	
UNI	T-II	HARMONY IN THE HUMAN BEING			9			
Unde the N Body Imag regul	rstanding Hum leeds of the Se as an Instrum ination in the ation and Healt	In being as the Co-existence of the Self and the Body (L2) - Di f and the Body (L2)- Exploring the difference of Needs of Self ent of the Self (L2)- Understanding Harmony in the Self (L2)- Self(L2) - Harmony of the Self with the Body (L2)- Program h (L2)- Exploring Harmony of Self with the Body (L2).	sting and Explo mme	uishi Body oring to e	ng b / (L2 Sou ensu	etwe 2) - 7 urces re so	een The s of elf-	
UNI	T– III	HARMONY IN THE FAMILY AND SOCIETY			9			
Harm Value - Exp (L2) Explo	oony in the Far e in Relationship oloring the Feel - Understandip oring Systems t	hily (L2) - the Basic Unit of Human Interaction (L2) - 'Trust (L2) - Exploring the Feeling of Trust (L2) - 'Respect' - as the ng of Respect (L2) - Other Feelings (L2), Justice in Human-to ng Harmony in the Society (L2)- Vision for the Universal H o fulfil Human Goal (L2).	' – t Right -Hun Iuma	he F : Eva nan I in O	oun luat Rela rder	datio on (l cions (L3	nal L3) hip) -	
UNI	T – IV	HARMONY IN THE NATURE/EXISTENCE	9					
Unde Fulfil Exist Explo	rstanding Harr ment among th ence as Co-exi pring Co-exister	nony in the Nature (L2) - Interconnectedness (L2), self-re e Four Orders of Nature (L3) - Exploring the Four Orders of Na stence at All Levels (L2) - The Holistic Perception of Harmony ce in Existence (L2).	gulat ture / in	ion (L2) Exist	and - R ence	Mut ealiz e (L2	ual ing) -	
UNI	т-v	IMPLICATIONS OF THE HOLISTIC UNDERSTANDING - A LOOK AT PROFESSIONAL ETHICS			9			
Natu Ethic Huma (L2) (L2)- Trans	Natural Acceptance of Human Values (L2) - Definitiveness of (Ethical) Human Conduct (L2) - Exploring Ethical Human Conduct (L2) - A Basis for Humanistic Education, Humanistic Constitution and Universal Human Order (L2) - Competence in Professional Ethics (L2) - Exploring Humanistic Models in Education (L2) - Holistic Technologies, Production Systems and Management Models (L2) - Typical Case Studies (L2)- Strategies for Transition towards Value-based Life and Profession (L2) - Exploring Steps of Transition towards Universal Human Order (L2)							
		OPEN ENDED PROBLEMS / QUESTIONS						
Cour be g	se specific Ope	n Ended Problems will be solved during the class room teaching nents and evaluated as IA only and not for the End semester Ex	g. Su kamii	ch pi natio	roble ns.	ems o	can	
		То	tal :	45	PER	[OD:	S	

Cours Upon	e Outcomes: completion of this course the students will be able to:	BLOOM'S Taxonomy				
1.	Interpret the concepts of Universal Human Values.	L2 - Understand				
2.	Summarize both theoretical and practical implications of Universal Human L2 - Understand Values.					
3.	Build the harmony in family and society.	L3 - Apply				
4.	Practice harmony in all human existence.	L3 - Apply				
5.	Relate human values in both personal and professional life.	L2- Understand				
TEXTE	OOKS:					
1.	R R Gaur, R Asthana, G P Bagaria, A Foundation Course in Human Values an Ethics, 2nd Revised Edition, Excel Books, New Delhi, 2019.	d Professional				
2.	A.N. Tripathi, Human Values, New Age Intl. Publishers, New Delhi, 2004.					
REFER	ENCE BOOKS:					
1.	R.R Gaur, R Sangal, G P Bagaria, A foundation course in Human Values and professional Ethics – Teachers Manual, Excel books, New Delhi, 2010.					
2.	B L Bajpai, 2004, Indian Ethos and Modern Management, New Royal Book Co., Lucknow, Reprinted 2008.					
3.	Frankl, Viktor E. Yes to Life In spite of Everything, Penguin Random House, I	_ondon, 2019.				
4.	Van Zomeren, M., & Dovidio, J. F. The Oxford Handbook of the Human Essence (Eds.), New York Oxford University Press, 2018.					
5.	B P Banerjee, Foundations of Ethics and Management, Excel Books, 2005.					
VIDEC Any re	REFERENCES:					
1.	https://www.youtube.com/c/UniversalHumanValues					
2.	2. https://www.youtube.com/watch?v=OgdNx0X923I					
WEB REFERENCES:						
1. http://www.storyofstuff.com						
2. https://fdp-si.aicte-india.org/UHVII.php						
ONLINE COURSES:						
1.	1. https://nptel.ac.in/courses/109104068					
2.	https://uhv.org.in/course					

Mapping of COs with POs and PSOs														
COs	POs								PSOs					
	P01	PO2	PO3	P04	P05	P06	P07	P08	P09	PO10	P011	PO12	PSO1	PSO2
CO1						2						2		
CO2								2						
CO3						3								
CO4								3				2		
CO5						3			2					
Average						2.6		2.5	2			2		
1–Low, 2 –Medium, 3–High.														

	EMBEDDED SYSTEMS- II LABORATORY				Version : 1.0			
Prog Bran	ramme & ch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	C P 4	L 0	Т 0	P 4	C 2	
Cour	Course Objectives:							
1	To involve the students to Practice on Workbench /Software Tools/ Hardware Processor Boards with the supporting Peripherals.							
2	To teach th Digital proc	e concepts of algorithm development & programming essors with peripheral interfaces.	on so	ftwa	ire t	ools	and	
3	To encoura	ge students to practice in open source softwares / pac	kages	/too	ols			
4	To train th suites	ough hands-on practices in commercial and license	d Ha	rdwa	are-	soft	ware	
5	Practicing t the student	hrough the subdivisions covered within experiments li is into the revising the concepts acquired from theory s	sted subjec	belo cts.	w to) ex	oose	
List o	of Experime	nts / Exercises						
1.	Programmi	ng ARM processor : ARM7 / ARM9/ARM Cortex						
2.	Programmi	ng with Rasberry Pi Microcontroller Board						
3.	I/O Prograi	mming with Arduino Microcontroller						
4.	Programming with DSP Processor Boards with Board							
5.	Designing o	of Filters in DSP Processor Boards.						
6.	Programmi	ng in Open source software's/ Platforms						
7.	Study of or	ne type of Real Time Operating Systems (RTOS)						
8.	Programming & Simulation in Python Simulators/Tools/others							
9.	Linux progi	ramming Tool chain						
10.	Programming & Simulation in GUI Simulators/Tools/others							
Total : 60 PERIODS								
C our s At the	rse Outcomes: BLOOM'S BLOOM'S Taxonomy							
C01	Experiment and demonstrate with simulators, in programming processor boards, processor interfacing/ L3 - Apply designing digital controllers.							
CO2	Design & simulate Arithmetic, Logic programs, Filters, Signal analysis with simulators/experiments ,in programming L3 - Apply processor boards, processor interfacing/ Tools.							
CO3	Develop rea	al time solution for embedded applications.		L	.3	Appl	у	
C04	Program ar	nd compile in various tools & software domains.		L	3 -	Appl	У	

C05	Improved Employability and entrepreneurship capacity due to knowledge up gradation on recent trends in commercial embedded processors and its programmable interfacing.	L3 - Apply				
REFE	RENCE BOOKS:					
1.	"The Definitive Guide to ARM® Cortex®-M3 and Cortex®-M4 Processors" by Joseph Yiu, Third Edition, Newnes, 2014.					
2.	"Raspberry Pi Cookbook: Software and Hardware Problems and Solutions" by Simon Monk, O'Reilly Media, 2016.					
3.	"Arduino Cookbook" by Michael Margolis, Second Edition, O'Reilly Media, 2011.					
4.	"Digital Signal Processing: Principles, Algorithms, and Applications" by Proakis and Manolakis, Fourth Edition, Pearson, 2006.					
5.	"Design of Digital Filters" by Charles S. Williams, PHI Learning, 2014.					
6.	"Python Programming: An Introduction to Computer Science" by John Zelle, Franklin, Beedle & Associates Inc., 2004.					
7.	"Mastering Embedded Linux Programming" by Chris Simmonds, Second Edition, Packt Publishing, 2018.					
8.	"Programming Embedded Systems: With C and GNU Development Tools" by Michael Barr, O'Reilly Media, 2006.					
9.	"Exploring Raspberry Pi: Interfacing to the Real World with Embedded Linux" by Derek Molloy, Wiley, 2016.					
10.	"Real-Time Operating Systems: Book 1 - The Theory" by Jim Cooling, Newnes, 2006.					

Mapping of COs with POs									
<u> </u>	PO								
CO	PO1	PO2	PO3	PO4	PO5	PO6			
1	1	3	1	1	2	1			
2	-	1	502 cm		-	-			
3	1	-	3	2	3	-			
4	2	2	3	3	3	3			
5	3)/) 2	3 1/1	3	3	3			
Avg	1.75	1)(2)(0))	2.4	2.25	2.75	1.75			
1–Low, 2–Medium, 3–High.									

				~ ~	-
Μ	E2	:3F	7	80	2

RESEARCH PAPER REVIEW AND PRESENTATION

Version : 1.0

(COMMON TO ALL BRANCHES)

Programme & Branch

M.E. EMBEDDED SYSTEM TECHNOLOGIES

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Course Objectives:

1	To Learn scientific paper reading and wiring skills
2	To Learn the literature review and report wiring skills
3	To understand the research gap and formulation of the research problem

The work involves the following steps:

Assigning the faculty supervisor

Selecting a subject, narrowing the subject into a topic

Stating an objective.

Collecting the relevant bibliography (atleast 20 research papers)

Studying the papers understanding the authors contributions and critically analysing each paper.

Preparing a 20-25 page literature review report

Preparing conclusions based on the literature review report.

Writing the Final Review Paper

Final Presentation to the review committee

Evaluation method:

A faculty supervisors will be assigned to each student. The supervisor will assign a topic to the student. The student has to review the literature pertaining to the topic, prepare a 20-25 page report and make a presentation. Minimum 20 research papers have to be reviewed out of which 60% have to be in the recent 05 years. The format for the research paper report and guidelines for assessment will be issued by the Head of the Department before the commencement of the course. The evaluation will be carried out based on the research paper report and presentation, and is evaluated for 100 marks. Minimum 50 marks is essential to pass. In case a student fails, he or she has to redo the course in the forthcoming semesters. Assessment is by Internal Assessment mode only no End Semester Examination.

	SALEM	Total : 30 PERIODS
C ours At the	e Outcomes: end of this course, the students will demonstrate the ability to	BLOOM'S Taxonomy
CO1	Write a scientific review paper in their field	L3 - Apply
CO2	Identify the research gap and formulate the research problem	L3 - Apply


M	E23AC701	ENGLISH FOR RESEARCH PAPER WRITING	NG Version: 1.0						
		(COMMON TO ALL BRANCHES)							
Prog Bra	gramme& nch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	CP L T P C 2 2 0 0 0						
Cour	se Objectives								
1	To teach how	w to improve writing skills and level of readability							
2	To tell about	t what to write in each section							
3	To summarize the skills needed when writing a Title								
4	To infer the	skills needed when writing the Conclusion							
5	To ensure th	ne quality of paper at very first-time submission							
	UNIT-I	INTRODUCTION TO RESEARCH PAPER WRITING			6				
Par and	agraphs and Solar and S	entences (L1), Being Concise and Removing Redundancy (L1) 2).), Av	oidin	g An	nbigu	ity		
	UNIT-II	PRESENTATION SKILLS			(5			
Cla Par	rifying Who D aphrasing and I	oid What (L2), Highlighting Your Findings (L1), Hedging Plagiarism (L1), Sections of a Paper (L1), Abstracts, Introductio	and on (L	Criti 1).	cizin	g (L:	1),		
	UNIT-III	TITLE WRITING SKILLS				5			
Key key Lite	 skills are need skills are need skills are need 	ded when writing a Title (L1), key skills are needed when wrided when writing an Introduction (L1), skills needed when wits, Results, Discussion, Conclusions, The Final Check (L1).	ting a	an Al a Re	ostra eview	ct (L: / of t	1), :he		
	UNIT-IV	RESULT WRITING SKILLS			(6			
Ski are	Skills are needed when writing the Methods (L1), skills needed when writing the Results (L2), skills are needed when writing the Discussion (L2), skills are needed when writing the Conclusions (L2).								
	UNIT-V VERIFICATION SKILLS 6								
Use the	eful phrases (L1 first- time sub), checking Plagiarism (L1), how to ensure paper is as good as mission (L1).	it co	ould p	ossit	bly be	9		
	TOTAL: 45 PERIODS								

OPEN ENDED PROBLEMS /QUESTIONS

Course specific open ended problems will be solved during the classroom teaching. Such problems can be given as assignments and evaluated as internal assessment only and not for the end semester examination

Cours Upon	Course Outcomes:BLOOMSUpon completion of this course the students will be able to:Taxonomy					
CO1	Understand that how to improve your writing skills and level of readability	L2 – Understand				
CO2	Learn about what to write in each section	L1 – Remember				
CO3	Understand the skills needed when writing a Title	L2 – Understand				
CO4	Understand the skills needed when writing the Conclusion	L2 – Understand				
CO5	Ensure the good quality of paper at very first-time submission	L2 – Understand				
TEXTE	300KS:					
1.	Adrian Wallwork , English for Writing Research Papers, Springer New York Dor Heidelberg London, 2011.	drecht				
2.	Day R How to Write and Publish a Scientific Paper, Cambridge University Press	2006.				
REFERENCE BOOKS:						
1.	1. Goldbort R Writing for Science, Yale University Press (available on Google Books) 2006.					
2.	Highman N, Handbook of Writing for the Mathematical Sciences, SIAM. Highman's book 1998.					



ME23AC702 DISASTER MANAGEMENT Ve					ersion: 1.0		
		(COMMON TO ALL BRANCHES)					
Prog	gramme&	M.F. EMBEDDED SYSTEM TECHNOLOGIES	СР	L	Т	Ρ	С
Bran	nch		2	2	0	0	0
Cour	se Objectives:						
1	Summarize b	asics of disaster					
2	Explain a criti response.	cal understanding of key concepts in disaster risk reduction	and h	uman	itaria	n	
3	Illustrate disa perspectives.	ster risk reduction and humanitarian response policy and pro-	actice	from	mult	iple	
4	Describe an u specific types	nderstanding of standards of humanitarian response and pra of disasters and conflict situations.	actical	l relev	/ance	in	
5	Develop the s	trengths and weaknesses of disaster management approach	es				
UN	NIT-I	INTRODUCTION				6	
Dis Na	saster: Definitic tural and Manm	on(L1), Factors and Significance(L1); Difference between H nade Disasters: Difference, Nature, Types and Magnitude(L1)	azard).	And	Disas	iter(L	2);
UN	NIT-II	REPERCUSSIONS OF DISASTERS AND HAZARDS		e	5		
Eco Dis An An	onomic Damage sasters: Earthq d Avalanches (d Spills, Outbre	e (L1), Loss of Human and Animal Life (L1), Destruction Of uakes, Volcanisms, Cyclones, Tsunamis, Floods, Droughts A L1), Man-made disaster: Nuclear Reactor Meltdown, Indust aks Of Disease And Epidemics, War And Conflicts (L1).	Ecosy And Fa rial A	stem amine ccide	(L1). es, La nts, C	Natu ndslic Dil Slic	ral les cks
UN	NIT-III	DISASTER PRONE AREAS IN INDIA		e	5		
Stı (L1 Dis	udy of Seismic 1); Areas Prone saster Diseases	Zones (L1); Areas Prone To Floods and Droughts (L1), Lar e To Cyclonic and Coastal Hazards with Special Reference and Epidemics (L1)	ndslide To Ts	es An sunan	d Ava ni (L1	alanch); Po	nes st-
UN	NIT-IV	DISASTER PREPAREDNESS AND MANAGEMENT			5		
Pre Ap Re	eparedness: Mo plication of Re ports: Governm	pnitoring Of Phenomena Triggering a Disaster or Hazard (emote Sensing (L1), Data from Meteorological And Othe mental and Community Preparedness (L1).	(L2); er Ag	Evalu encie	ation s (L1	of R), Me	isk: edia
	UNIT-V	RISK ASSESSMENT				6	
Dis Ris Wa	saster Risk: Col sk Situation (L1 arning (L1), Pec	ncept and Elements (L1), Disaster Risk Reduction (L1), Glo). Techniques of Risk Assessment (L1), Global Co-Operation ple's Participation in Risk Assessment. Strategies for Surviva	bal ar n in R al (L1)	nd Na isk As)	tional ssessi	Disa: nent	ster and
			тоти	4L: 4	5 PEF	RIOD	S
		OPEN ENDED PROBLEMS /OUESTIONS					
Cou can	irse specific op be given as as	en ended problems will be solved during the classroom tea signments and evaluated as internal assessment only and no	aching ot for	g. Suo the ei	ch pro nd se	blem meste	s er

examination						
Cours	Course Outcomes:					
Upon	Taxonomy					
CO1	Summarize basics of disaster	L1 – Remember				
CO2	Explain a critical understanding of key concepts in disaster risk reduction and humanitarian response.	L2 – Understand				
CO3	Illustrate disaster risk reduction and humanitarian response policy and practice from multiple perspectives	L2 – Understand				
CO4	Describe an understanding of standards of humanitarian response and	L2 – Understand				

	practical relevance in specific types of disasters and conflict situations.					
CO5	Develop the strengths and weaknesses of disaster management approaches	L2 – Understand				
TEXTE	300KS:					
1.	Goel S. L., Disaster Administration And Management Text And Case Studies", Deep & Deep Publication Pyt. Ltd., New Delhi, 2009.					
2.	NishithaRai, Singh AK, "Disaster Management in India: Perspectives, issues and strategies "/New Royal book Company, 2007.					
REFE	REFERENCE BOOKS:					
1.	Sahni, Pradeep Et.Al.," Disaster Mitigation Experiences And Reflections", Pren OfIndia, New Delhi, 2001.	tice Hall				



	ME23AC703 CONSTITUTION OF INDIA					Version: 1.0				
		(COMMON TO ALL BRANCHES)								
Prog	Jramme&	M.E. EMBEDDED SYSTEM TECHNOLOGIES	СР	L	Т	Ρ	С			
Brar	ich									
Cour	se Objectives	•								
1	To understa perspective.	nd the premises informing the twin themes of liberty and freedo	om fr	om a	civil	right	:S			
2	To address t	he growth of Indian opinion regarding modern Indian intellectu	als' c	onsti	tutio	nal				
3	To role and early years	entitlement to civil and economic rights as well as the emergen of Indian nationalism.	ce of	natic	nhoc	od in	the			
4	To address t And its impa	the role of socialism in India after the commencement of the Bo act on the initial drafting of the Indian Constitution	lshev	ik Re	evolu	tion 1	1917			
	UNIT-I	HISTORY OF MAKING OF THE INDIAN CONSTITUTION			6					
Н	istory(L1), Drai	fting Committee(L1), (Composition & Working)	•							
UNIT-II PHILOSOPHY OF THE INDIAN CONSTITUTION					6					
Pi	reamble (L1), S	Galient Features (L1).	•							
	UNIT-III	CONTOURS OF CONSTITUTIONAL RIGHTS AND DUTIES	6							
Fı	undamental Ric	ahts (L1), Right to Equality (L1), Right to Freedom (L1), Righ	t aga	ainst	Explo	oitati	on			
Fi (L Re	undamental Rig 1), Right to Fr emedies (L1), [ghts (L1), Right to Equality (L1), Right to Freedom (L1), Righ eedom of Religion (L1), Cultural and Educational Rights (L1), R Directive Principles of State Policy (L1), Fundamental Duties (L1	t aga light).	ainst to Co	Explo onstit	oitati	on 1al			
Fi (L Ri	undamental Rig 1), Right to Fr emedies (L1), I UNIT-IV	ghts (L1), Right to Equality (L1), Right to Freedom (L1), Righ eedom of Religion (L1), Cultural and Educational Rights (L1), R Directive Principles of State Policy (L1), Fundamental Duties (L1 ORGANS OF GOVERNANCE	t aga light).	inst to Co	Explo onstit	oitati	on 1al			
Fi (L Ri Pi (L ai	undamental Rig 1), Right to Fr emedies (L1), I UNIT-IV arliament (L1), 1), Executive (nd Transfer of J	Ants (L1), Right to Equality (L1), Right to Freedom (L1), Right eedom of Religion (L1), Cultural and Educational Rights (L1), R Directive Principles of State Policy (L1), Fundamental Duties (L1 ORGANS OF GOVERNANCE Composition (L1), Qualifications and Disqualifications (L1), F (L1), President (L1), Governor (L1), Council of Ministers (L1), Ju Judges (L1), Qualifications, Powers and Functions (L1).	t aga tight). Power udicia	ninst to Co rs an ary, A	Explo onstit 6 d Fu oppoi	nctio	on Ial			
Fi (L Ri Pa (L ai	undamental Rig 1), Right to Fr emedies (L1), I UNIT-IV arliament (L1), 1), Executive (nd Transfer of J UNIT-V	Ants (L1), Right to Equality (L1), Right to Freedom (L1), Right eedom of Religion (L1), Cultural and Educational Rights (L1), R Directive Principles of State Policy (L1), Fundamental Duties (L1 ORGANS OF GOVERNANCE Composition (L1), Qualifications and Disqualifications (L1), F (L1), President (L1), Governor (L1), Council of Ministers (L1), Ju Judges (L1), Qualifications, Powers and Functions (L1).	t aga tight). Power udicia	ninst to Co rs an ary, A	Explo onstit 6 d Fu oppoi	nctio	on hal ns nt			
Fi (L Ri Pa (L Distri Electe Panch Orgar (L1),	undamental Rig 1), Right to Fr emedies (L1), I UNIT-IV arliament (L1), 1), Executive (nd Transfer of J UNIT-V ct's Administra ed Represental nayat (L1). Elec nizational Hiera Importance of	Ants (L1), Right to Equality (L1), Right to Freedom (L1), Right eedom of Religion (L1), Cultural and Educational Rights (L1), R Directive Principles of State Policy (L1), Fundamental Duties (L1 ORGANS OF GOVERNANCE Composition (L1), Qualifications and Disqualifications (L1), F L1), President (L1), Governor (L1), Council of Ministers (L1), Ju Judges (L1), Qualifications, Powers and Functions (L1). LOCAL ADMINISTRATION tion head: Role and Importance (L1), Municipalities: Introduc tive, CEO, Municipal Corporation (L1). Pachayati raj: Introductive, CEO, Municipal Corporation (L1), CEO Zila Pachayat: Position ar irchy(Different departments) (L1), Village level:Role of Elected grass root democracy (L1).	t aga tight). Power udicia	May May Dn (I App	Explo onstit d Fu oppoi or ar _1), L). Bl ointe	nctio nctio ntme PRI: ock I d off	on nal ns nt le o Zila evel icials			
Fi (L R Pa (L an Distri Electe Panch Drgar (L1),	undamental Rig 1), Right to Fr emedies (L1), I UNIT-IV arliament (L1), 1), Executive (nd Transfer of J UNIT-V ct's Administra ed Representat nayat (L1). Elec nizational Hiera Importance of UNIT-VI	Ants (L1), Right to Equality (L1), Right to Freedom (L1), Right eedom of Religion (L1), Cultural and Educational Rights (L1), R Directive Principles of State Policy (L1), Fundamental Duties (L1) ORGANS OF GOVERNANCE Composition (L1), Qualifications and Disqualifications (L1), F L1), President (L1), Governor (L1), Council of Ministers (L1), Ju Judges (L1), Qualifications, Powers and Functions (L1). LOCAL ADMINISTRATION tion head: Role and Importance (L1), Municipalities: Introductive, CEO, Municipal Corporation (L1). Pachayati raj: Introductive, CEO, Municipal Corporation (L1), Pachayati raj: Introductive, CEO, Municipal Corporation (L1), Village level:Role of Elected grass root democracy (L1).	t aga tight). Power udicia	May May May Dn (L1 App	Explo onstit d Fu oppoi or ar 1), Bl ointe	nctio nctio ntme nd ro PRI: ock l d off	on nal ns nt Zila evel icial			
Fi (L Ra Pa (L an Distri Electe Panch Drgar (L1), El Cu	undamental Rig 1), Right to Fr emedies (L1), I UNIT-IV arliament (L1), 1), Executive (nd Transfer of J UNIT-V ct's Administra ed Representat nayat (L1). Elec nizational Hiera Importance of UNIT-VI ection Commi	And the end of the end	t aga tight). Power udicia	Mayon (L Apperent (L1)	Explo onstit d Fu oppoi or an (1), Bl ointe 6 nd E	nctio nctio ntme nd ro PRI: ock l d off	on nal ns nt Zila evel icials			
Fi (L Ri Pa (L ai Distri Electe Panch Drgar L1), El Cu	undamental Rig 1), Right to Fr emedies (L1), I UNIT-IV arliament (L1), 1), Executive (nd Transfer of J UNIT-V ct's Administra ed Represental nayat (L1). Elec nizational Hiera Importance of UNIT-VI ection Commi ommissioners (And the end of the end	t aga tight). Power udicia tion, duction duction duction duction duction duction duction duction duction duction duction duction duction duction	Mayon (L Appo er an (L1) - 45	Explo onstit d Fu oppoi or ar 1), Bl ointe 6 nd E	nctio nctio ntme nd ro PRI: ock l d off	on nal ns nt Zila evel icial:			
Fi (L Rd Pa (L an Distri Electe Panch Drgar (L1), El Cu	undamental Rig 1), Right to Fr emedies (L1), I UNIT-IV arliament (L1), 1), Executive (nd Transfer of J UNIT-V ct's Administra ed Representat nayat (L1). Elec nizational Hiera Importance of UNIT-VI ection Commi ommissioners (Ants (L1), Right to Equality (L1), Right to Freedom (L1), Right eedom of Religion (L1), Cultural and Educational Rights (L1), R Directive Principles of State Policy (L1), Fundamental Duties (L1) ORGANS OF GOVERNANCE Composition (L1), Qualifications and Disqualifications (L1), F L1), President (L1), Governor (L1), Council of Ministers (L1), Ju udges (L1), Qualifications, Powers and Functions (L1). LOCAL ADMINISTRATION tion head: Role and Importance (L1), Municipalities: Introduc tive, CEO, Municipal Corporation (L1). Pachayati raj: Introduc tive, CEO, Municipal Corporation (L1). Pachayati raj: Introduc tived officials and their roles (L1), CEO Zila Pachayat: Position ar irrchy(Different departments) (L1), Village level:Role of Elected grass root democracy (L1). ELECTION COMMISSION ssion: Role and Functioning (L1). Chief Election Commis L1) - Institute and Bodies for the welfare of SC/ST/OBC and wo	t aga tight). Power udicia	Mayon (L Appo (L1) - 45	Explo onstit d Fu oppoi or ar 1), 1). Bl ointe 6 nd E PER	nction nction ntme nd ro PRI: ock l d off	on nal ns nt le o Zili icial on			

Course Outcomes: BLOOMS						
Upon c	completion of this course the students will be able to:	Taxonomy				
CO1	Discuss the growth of the demand for civil rights in India for the bulk of Indians before the arrival of Gandhi in Indian politics.	L2 – Understand				
CO2	Discuss the intellectual origins of the framework of argument that informed the conceptualization of social reforms leading to revolution in India.	L2 – Understand				
CO3	Discuss the circumstances surrounding the foundation of the Congress Socialist Party [CSP] under the leadership of Jawaharlal Nehru and the eventual failure of the proposal of direct elections through adult suffrage in the Indian Constitution.	L2 – Understand				
CO4	Discuss the passage of the Hindu Code Bill of 1956.	L2 – Understand				
TEXT	BOOKS:					
1.	The Constitution of India, 1950 (Bare Act), Government Publication					
2.	Dr.S.N.Busi, Dr.B. R.Ambedkar framing of Indian Constitution,1 st Edition, 201	5.				
REFERENCE BOOKS:						
1.	M.P. Jain, Indian Constitution Law, 7 th Edn., LexisNexis,2014.					
2.	D.D. Basu, Introduction to the Constitution of India, LexisNexis, 2015.					



м	E23AC704	நற்றமிழ் இலக்கியம்	Version: 1.0							
		(COMMON TO ALL BRANCHES)								
Pro Bra	ogramme& Inch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	CP L T P C 2 2 0 0 0							
Cou	Course Objectives:									
1	1 சங்க இலக்கியம் பற்றி மாணவர்களுக்கு எடுத்துரைத்தல்									
2	நீதி நூல்க	கள் வாயிலாக அறக்கருத்துகளை எடுத்து கூறுதல்.								
3	சிலப்பதி	காரம், மணிமேகலை காப்பியங்களை எடுத்துரை	த்தல்	υ.						
4	இலக்கிய	ங்களில் காணப்படும் அருள்நெறிக் கதைகளைப் ப	பற்ற	റ്റി ഖ്	ிளச்	குத	ல்.			
5	தற்காலத்	5 தமிழ் இலக்கியங்களை மாணவர்களுக்கு தெரிய	ப்ப(டுத்த	துத	່ນ.				
	UNIT-I	சங்க இலக்கியம்			6					
1.	தமிழின் துவ	பக்க நூல் தொல்காப்பியம் - எழுத்து, சொல், பொரு) को (_1)						
2.	அகநானூறு குறிக்குப்ப	(82) - இயறலைக் இல்லாலைச் அரங்கம் (L1) பட்டின் மலர்ச்சாட் இ (L1)								
3. 4.		'95, 195) – போரை நிறுக்கிய வையைார் (ப)								
	UNIT-II	அறநெறித்தமிழ்			6					
1.	அறநெறி வ	குத்த திருவள்ளுவர் - அறம் வலியுறுத்தல், அன்	புடை	_ഞ	ம,					
	ஒப்புறவு அற	ற்தல், ஈகை, புகழ் (L2)	•		•					
2.	பிற அறநூ சிசலால்	லகள் – இலக்கிய மருந்து - ஏலாதி, சிறுபடு ஆசாரர்சோதைப் சாய்கும்கைய வலியலுர்சால் சால்	መቻሮ እርጉ	ழல	ம,					
	தாரக்டுக்ய,	ஆசாரககோலை (தாயலாமலாம் வலாயுறுத்துய நால ரை கடிகாப்பியங்கள்) (LZ)	6					
1.	கண்ணகியி	ன் பாட்சி- சிலப்பகிகாா வடிக்குளை காகை (L1)			•					
2.	சமூக சே	ை இலக்கியம் மணிமேகலை – ச	ிறை)க்ே	காட	ட்டம்)			
	அறக்கோட்ட	_மாகிய காதை (L1)								
	UNIT-IV	அருள்நெறித்தமிழ்			6					
1.	சிறுபாணாற்	ற்றப்படை – பாரி முல்லைக்கு தேர் கொடு	த்த	<u>되,</u>	പേ പറച	கன்	-			
	மயிலுக்குப	போரவை கொடுத்தது, அதுயமான ஔவைக்கு	5 61	நல	லக	கன				
2	്രത്വവ്രക്കള്ള്, നന്നിതത്ത –	அரசர் பண்டிகள். (டீ2) அன்னைக்குரிய பன்னை கிறப்ப (ப2)								
3.	கிருமந்தாம்	(617.618) இயமம் நியமம் விகிகள் (L2)								
4.	தர்மசாலை	லய நிறுவிய வள்ளலார் (L2)								
5.	புறநானூறு -	- சிறுவனே வள்ளலானான் (L2)								
6.	அகநானூறு	(4) – ഖഞ്ഡ്) (L2)								
7.	நற்றிணை (11) - 匠砌(h) (L2) F (11) - 世田の可 (12)								
о. 9	லந்தினை உ	க் (11) – யால்லா, புறா (ட2) ப்பகு (27) – மான் (L2)								
5.	ஆகியவை ப	பற்றிய செய்திகள் (L2)								
	UNIT-V	நவீன தமிழ் இலக்கியம்			6	5				
1.	உரைநடைச்	தமிழ் (L1)								
	– தமிழின் மு	தல் புதினம் (L1)								
	– தமிழின் மு	தல் திறுகதை (L1)								
	– கடடுரை இ))的东东IIIIID (L1) ນຕໍ່ຕົມແລ້ (L1)								
	– പവംഗാ, യ്യം - നല കറ്റി 1	ഗത്തിലല് (L1))								
2. г	நாட்டு விடுக	, லை போராட்டமும் கமிழ் இலக்கியமும் (L1)								
3. 2	சமுதாய விடு)தலையும் தழிழ் இலக்கியமும் (L1)			-		_			
4. (பெண் விடுத	லையும் விளிம்பு நிலையினரின் மேம்பாட்டில் தமி	ழ் இ	ៀលខំ	கிய	பமுட	Ď			
(L1)	ചനിവിധാസം									
Э. с	அறுவாறை இ	unth (rr)								

6. இணையத்தில் தமிழ் (L1) 7. சுற்றுச்சூழல் மேம்பாட்டில் தமிழ் இலக்கியம் (L1)

Total: 30 PERIODS

Cou Upo	Course Outcomes:BLOOMSUpon completion of this course the students will be able to:Taxonomy						
C01	சங்க இலக்கியம் மாணவர்கள் முழுமையாக அறிந்து பயன்பெறுதல்.	L1 - நினைவில் கொள்ளுதல்					
CO2	அறநெறி இலக்கியம் வாயிலாக வாழ்வியலுக்குத் தேவையான தூய்மைப் பணிகளை மேற்கொள்ளுதல்.	L2 - புரிந்து கொள்ளுதல்					
CO3	சிலப்பதிகாரம், மணிமேகலை காப்பியங்களில் உள்ள நீதிக்கருத்துகளை மாணவர்கள் தெரிந்துகொள்ளுதல்.	L1 - நினைவில் கொள்ளுதல்					
CO4	இலக்கியங்களில் காணப்படும் அருள்நெறிக் கதைகளைப் பற்றி விளக்குதல்.	L2 – புரிந்து கொள்ளுதல்					
CO5	தற்காலத் தமிழ் இலக்கியங்களை மாணவர்கள் தெரிந்து அவற்றின் வாயிலாக பயன் அடைதல்.	L1 – நினைவில் கொள்ளுதல்					
TEX	гвоокs: தமிழ் இலக்கிய வெளியீடுகள் புத்தகங்கள்						
1.	தமிழ் இணைய கல்விக்கழகம் (Tamil Virtual University) - wv	vw.tamilvu.org.					
2.	தமிழ் விக்கிப்பீடியா (Tamil Wikipedia) -https://ta.wikipedia.org].					
3.	தர்மபுர ஆதீன வெளியீடு.						
4.	வாழ்வியல் களஞ்சியம் <mark>– தமிழ்ப் பல்கலைக்கழக</mark> ம், தஞ்	சாவூர்.					
5.	தமிழ்க்கலைக்களஞ்சியம் - தமிழ் வளர்ச்சித்துறை (tham	ilvalarchithurai.com).					
6.	6. அறிவியல் களஞ்சியம் - தமிழ்ப் பல்கலைக்கழகம், தஞ்சாவூர்.						

Beyond Knowledge

Professional Elective Courses I & II

Beyond Knowledge

TUTS

ME23ET401		Wireless And Mobile Communication		Ver	sion	: 1.0)	
		(COMMON TO ALL BRANCHES)						
Prog Brai	gramme & nch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	СР 3	L 3	Т 0	P 0	C 3	
Cou	rse Object	ives:						
1	To study th	ne Channel planning for Wireless Systems						
2	2 To study Mobile Radio Propagation and Equalization and Diversity							
3	To study th	ne Equalization and Diversity						
4	To study th	ne Wireless multiple access and IP.						
5	To provide	insight into wideband code division-based access.						
UNI	T-I	THE CELLULAR CONCEPT			9			
Int pla int Sys	erference, nning for V erference(L3)-C	and system capacity –Co-channel Interference and system cap Vireless Systems(L2), Adjacent Channel interference(L3), Power Co 3), Trunking and Grade of Service(L3), Improving Coverage & C Cell Splitting, Sectoring(L3).	acit ontro Capa	y(L3 ol fo city), C or Re in (chanr educi Cellu	nel ng lar	
UNI	T-II	MOBILE RADIO PROPAGATION: LARGE-SCALE PATH LOSS:			9			
Ele kni Ok Flo Mo	ctric Field(l fe-edge D umura Mode ors, Log-di del(L3), Sig	2), Diffraction-Fresnel Zone Geometry(L3), Knife edge Diffraction iffraction(L2), Scattering(L2), Outdoor Propagation Models-Lor el, Hata Model(L3), Indoor Propagation Models-Partition losses, Parti- stance path loss model, Ericsson Multiple Breakpoint Model, nal penetration into buildings, Ray Tracing and Site Specific Modellin	Mod nglev tion Atte g(L3	el(L2 y-Ry loss nuat 8)	2), N ce es be tion	Aultig Mod etwe Fact	ole el, en cor	
UNI	T– III	MOBILE RADIO PROPAGATION			9			
Sm sca Ba of and Sp slo Eq	nall –Scale I ale fading, E ndwidth and Mobile Multi d Coherence read, Flat f w fading(L ualizers in a	Fading and Multipath(L2): Small Scale Multipath propagation-Factor Doppler shift, Impulse Response Model of a multipath channel(L2)-Re d Received power(L3), Small-Scale Frequency Domain Channels So path Channels(L2)-Time Dispersion Parameters, Coherence Bandwic e Time, Types of Small-Scale Fading(L3)-Fading effects Due to Mu ading, Frequency selective fading, Fading effects Due to Doppler S 2), Fundamentals of Equalization(L2), Training A Generic Adap communication Receiver(L3), Linear Equalizers, Nonlinear Equalization	s inf elation undi lth, ultipa Spre otive	iluen onsh ng, Dopp ath ad-F Equ _3)	cing ip b Para pler Time ast ualiz	sma etwe mete Spre Del fadir er(L	ill- en ad ay ig, 3),	
UNI	т – і	WIDEBAND CODE DIVISION MULTIPLE ACCESS			9			
CD mu coo est	MA system Iltiplexing a des-uplink-c ablishing a	n overview(L1) -air interface (L2)-physical and logical chann and channel coding (L2)-spreading and modulation(L2): frame si lownlink(L2) – 33 physical layer procedures: cell search and connection-power control handover-overload control(L3).	nel-s truct d s	spee cure, ynch	ch spr nroni	codir eadi zatic	ng, ng n-	
UNI	т-v	IP MOBILITY FRAMEWORK	9					
Ch Do Arc	allenges of main Name chitecture Fi	IP Mobility -Address Management(L1) -Dynamic Host Configure Server Interfaces(L2) -Security(L2) -Mobility-Based AAA Protoc amework(L2) -x Access Network -IPv6 Challenges for IP Mobility(L3)	atior col(L).	ר Pr 2) -	otoc IP N	ol a 1obil	nd ity	
			То	tal:	45 I	PERI	ODS	
Cou	se Outcomes:					M'S		

Upon	Taxonomy	
C01	Understand Cellular communication concepts	L3 - Apply
C02	Explain the mobile radio propagation	L3 - Apply
CO3	Perceive the wireless network's different types of MAC protocols	L3 - Apply
CO4	Analyze the Equalization and Diversity	L3 - Apply
C05	Build the Wireless multiple access and IP	L3 - Apply
REFEF	ENCE BOOKS:	
1.	Wireless Communications, Principles, Practice - Theodore, S. Rappaport, 2nd	Ed., 2002, PHI.
2.	Wireless Communications Andrea Goldsmith, 2005 Cambridge University Pres	SS.
3.	Principles of Wireless Networks -KavehPahLaven and P. Krishna Murthy, 200	2, PE
4.	Mobile Cellular Communication –GottapuSasibhushana Rao, Pearson Education	on, 2012
5.	Wireless Digital Communications –KamiloFeher, 1999, PHI	
6.	Wireless Communication and Networking –William Stallings, 2003, PHI	
WEB	REFERENCES:	
https	://archive.nptel.ac.in/courses/108/106/106106167/	
https	://archive.nptel.ac.in/courses/117/102/117102062/	
ONL	NE COURSES:	
https	://onlinecourses.nptel.ac.in/noc23_ee79	
https	://nptel.ac.in/courses/117104115	
VIDE	O REFERENCES:	
https	://www.youtube.com/watch?v=1Ag6ZGnFIFo&t=3s	
https	://www.youtube.com/watch?v=CUyF0YGIA5Y	

Mapping of COs with POs and PSOs									
60	PO								
CO	1	2	3	4	5	6			
CO1	3	Bur 3 md	C 2	whether					
CO2	3	3	2	2					
CO3	3	3	2	3	2	2			
CO4									
CO5									
AVG	3	3	2	2	2	2			
		1-Low, 2	-Medium, 3-	High.					

ME23ET402		02 VIRTUAL INSTRUMENTATION			Version: 1.0				
		(COMMON TO ALL BRANCHES)							
Pro Bra	gramme & nch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	СР 3	L 3	Т 0	P 0	C 3		
Cou	rse Object	ives:							
1	1 Understanding the difference between conventional and graphical programmin								
2	Introducing	g the basics of Lab VIEW and programming concepts.							
3	Differentia	ting the real-time and virtual instrument							
4	Represent	and review signals acquire process in the digital domain.							
5	Analyzing VIEW.	the basics of data acquisition and learning the concepts of data	acqı	uisiti	on v	vith	Lab		
נאט	T-I	FUNDAMENTALS OF VIRTUAL INSTRUMENTATION			9				
	Fundament instruments instruments Properties (al Concepts of Virtual Instrumentation (VI) and Graphical Program and Traditional instruments(L2), Hardware and Soft ation(L2), Data Flow Programming (L2)- Data Types (L2)- Cu (L3)- VI Documentation(L1)	nmir ware istor	ng(L2 e miza	2) - in tion	Virtu virtu of	ial ial VI		
נאט	T-II	PROGRAMMING STRUCTURES			9				
	Software E Registers (I Clusters (L2	nvironment (L2)- Modular programming (L2)- Formula Nodes (L2) L2)- Local and Global Variables(L2) – Case and Sequence Structure 2)- Graphs and Charts (L2)- State Machines (L3)- String and File I/O	- Lo es(L2 (L2)	ops 2) -	(L2) Arra	- Sh ys ai	ift nd		
נאט	T– III	DATA ACQUISITION AND INTERFACING STANDARDS	9						
	PC-based c configuratic counter/tim RS485(L2) of MOD bus	lata acquisition (L2)- DAQ hardware and software architecture(L2 on, sampling methods and grounding techniques, analog her(L2) - Communication(L2): Interfacing of external instruments - GPIB (L2)- System Interface Buses: USBPCI, PXI(L2); Introduction and CAN bus (L2)- Industrial Ethernet(L2).) – I/O, to a on t	DAC , di PC o bu) ha igital - R s pr	rdwa I/ 5232 otoco	re O, - ols		
נאט	T – IV	ADVANCED PROGRAMMING			9				
	Introduction File Input , Sample VIs String Fund application Developme	n(L1), Definition of State Machine(L1), A Simple State Machine, Ev / Output: Introduction(L1), File Formats, File I/O Functions(L2), F s to Demonstrate File WRITE and READ Function String Handling ctions(L2), Lab VIEW String Formats(L2), Typical examples Use of of VI: Fourier transforms, Power spectrum, Simulation of s nt of Control system, Image acquisition and processing(L3)	ent Path : Ir ana syste	Stru Fur atrod alysis ems	cture oction uctio uctio s too usir	es(L2 ns(L2 on(L1 ols ar ng V	<u>'</u>), <u>'</u>),), nd 'I:		
נאט	T-V	CASE STUDIES			9				
	Temperature Monitoring System using PC-based Data Acquisition System - Machine vision, Motion control(L3), Configuration of Real-Time I/O Hardware in MAX (L3)- Host & Target VI (L3)- Prioritization of Tasks- Timed Programming Structures in Lab VIEW (L3)- Real-Time Application Deployment using my RIO (L3)- Run-time Interaction with Deployed Applications (L3)- Running Web Services in my RIO(L2).								
			То	tal:	45 F	PERI	ODS		
Cou Upo	rse Outcon	nes: on of this course, the students will be able to:	BLOOM'S Taxonomy						
СО	CO1 Infer and Interpret the fundamentals of Virtual Instrumentation and Data Acquisition				Vata L3 - Apply				

C02	Explain the difference between traditional and virtual instrumentation	L3 - Apply					
CO3	Illustrate the theoretical concepts to realize practical systems.L2 - Understand						
CO4	Analyze and evaluate the performance of Virtual Instrumentation System L3 - Apply s						
CO5	Build a VI system to solve real-time problems using data acquisition.	L3 - Apply					
REFER	RENCE BOOKS:						
1.	Jovitha Jerome, -Virtual Instrumentation using Lab VIEWI, PHI Learning Pvt	. Ltd., 2010.					
2.	Sanjay Gupta and Joseph John, "Virtual Instrumentation Using Lab VIEW", Tata McGraw Hill, 2008						
3.	Gary Johnson and Richard Jennings, -Lab VIEW Graphical ProgrammingI, McGraw Hill Inc., Fourth Edition, 2006						
4.	Rick Bitter, Taqi Mohiuddin, and Matt Nawrocki, "Lab VIEW Advance Techniques", CRC Press, 2009	d Programming 35					
5.	Lisa. K. Wills, "Lab VIEW for Everyone", Prentice Hall of India, 2nd Edition, 2	008					
6.	William Buchanan, -Computer Buses Design and ApplicationII, CRC Press, 20	000					
WEB	REFERENCES:						
https	://mycourses.aalto.fi/course/view.php?id=32114						
https	://learn.ni.com/learn/article/labview-tutorial						
ONLI	INE COURSES:						
https	://nielit.gov.in/calicut/calicut/content/online-course-labview-industrial-applicat	tions					
https	://www.ni.com/en/shop/services/education-services/customer-education-cour	ses/labview-core-1-					
VIDE							
bttpc	V REFERENCES:						
https	//www.youtube.com/watch?v=/SAyvigyCi4						
nups	https://www.youtube.com/watch?v=DmgGgDzLgI0						

	Мар	ping of CO	s with POs	and PSO	S		
PO							
	1)/)	2	3 / .	4	5		
CO1	300	11021d	11/1	and z edeg	10		
CO2			2	1			
CO3	1	3	3	3	1		
CO4	2	2	3	3	2		
CO5	3	3	3	3	3		
AVG	2	2.5	2.4	2.75	2		

2.4 1-Low, 2 -Medium, 3-High. 6

1 2 3

ramme nch se Objec To learn	(COMMON TO ALL BRANCHES) M.E. EMBEDDED SYSTEM TECHNOLOGIES	СР						
ramme nch se Objec To learn	M.E. EMBEDDED SYSTEM TECHNOLOGIES	СР						
se Objec To learn		2	L 3	T	P	C		
To learn	Course Objectives:							
	To learn about basic concepts of embedded systems.							
To learn	about ARM architecture							
To learn	C language and assembly programming.							
To learn	Object orientation for programming and C++							
To learn	software modeling fundamentals.							
-I	EMBEDDED CONCEPTS			9				
ystems(L ystems(L lardware Software(2), Overview of embedded system architecture(L2), Special 2), recent trends in embedded systems(L2), Architecture of emb architecture(L2), Software architecture(L2), Application Software(L2), Development and Debugging Tools(L2) 	ties eddeo L2), (of d sy Com	emt sten mun	icati	ed 2), on		
-11	ARM ARCHITECTURE AND OVERVIEW OF CORTEX			9				
13 (L2), Program (Stack Mei nstructio nterfaces	Cortex-M3 Basics: Registers, General Purpose Registers, Stack P Counter, Special Registers, Operation Mode, Exceptions and Interru mory Operations, Reset Sequence. Instruction Sets: Assembly Bas n Descriptions(L2). Cortex-M3 Implementation Overview: Pipeline, on Cortex-M3, I-Code Bus, D-Code Bus, System Bus, External PPB a	ointe ipts, ' ics, I Block and D	r, Ll Vect nstru Dia AP E	< Re or. 7 uctio Igrar Bus(1	giste Fable n Lis n, B _2)	er, es, st, us		
– III	CORTEX-M3/M4 PROGRAMMING				9			
Overview(nterface Exception Protection Nanagem	(L1), Typical Development Flow, Using C, CMSIS (Cortex Micro Standard) (L3), Using Assembly Exception Programming: /Interrupt Handlers, Software Interrupts, Vector Table Reloc Unit and other Cortex-M3 features: MPU Registers, Setting U ent, Multiprocessor Communication(L2).	Usir Usir cation Ip th	roller ng (L2) e M	⁻ So Inte . M PU,	oftwa rrupi lemc Pow	re ts, ory /er		
- IV	UNIFIED MODELING LANGUAGE			9				
Connectin L2)– UMI lefinition ypes and n UML(L2	g the object model with the use case model (L2)– Key strategies for basics(L2). Object state behavior (L2)– UML state charts (L2)– Rol of behavior – Timing diagrams (L3)– Sequence diagrams(L3) – Eve strategies of operations(L2) – Architectural design in UML concurrer 2).	obje e of s ent hie ncy de	ct id scena eraro esigr	entif arios chies n – t	icati in t (L2 hrea	on he ()– ds		
- v	EMBEDDED SOFTWARE DEVELOPMENT TOOLS AND RTOS			9				
The comp ystems(L RTOS(L3)	vilation process (L2)– libraries (L2)– porting kernels(L2) – C exten .2)(L2) – emulation and debugging techniques(L2) – RTOS(L2) - s	sions syster	for n de	emt esign	oedd Uusi	ed ng		
		To	tal:	45 F	PERI	OD		
se Outco comple	omes: tion of this course, the students will be able to:		BL Tax	00M	1′S mv			
	-I htroducti ystems(L ardware oftware(-II ackgroun hstructio 13 (L2), rogram (tack Men hstructio nterfaces - III verview(hterface xception rotection lanagem - IV onnectin L2)- UMI efinition /pes and n UML(L2 -V he comp ystems(L TOS(L3) - COS(L3)	-I EMBEDDED CONCEPTS Itroduction to embedded systems(L1), Application Areas(L2), Categorystems(L2), Overview of embedded system architecture(L2), Special ystems(L2), recent trends in embedded systems(L2), Architecture of emb ardware architecture(L2), Software architecture(L2), Application Software(oftware(L2), Development and Debugging Tools(L2) -II ARM ARCHITECTURE AND OVERVIEW OF CORTEX ackground of ARM Architecture(L2), Architecture Versions(L2), Procenstruction Set Development(L2), Thumb-2, and Instruction Set Architecture. I3 (L2), Cortex-M3 Basics: Registers, General Purpose Registers, Stack Program Counter, Special Registers, Operation Mode, Exceptions and Interrutack Memory Operations, Reset Sequence. Instruction Sets: Assembly Basistruction Descriptions(L2). Cortex-M3 Implementation Overview: Pipeline, therfaces on Cortex-M3, I-Code Bus, D-Code Bus, System Bus, External PPB artification Descriptions(L2). Cortex-M3 features: MPU Registers, Setting U anagement, Multiprocessor Communication(L2). - III CORTEX-M3/M4 PROGRAMMING verview(L1), Typical Development Flow, Using C, CMSIS (Cortex Micronaterface Standard) (L3), Using Assembly Exception Programming: xception/Interrupt Handlers, Software Interrupts, Vector Table Reloc rotection Unit and other Cortex-M3 features: MPU Registers, Setting U anagement, Multiprocessor Communication(L2). - IV UNIFIED MODELING LANGUAGE onnecting the object model with the use case model (L2) - Key strategies for 2) - UML basics(L2). Object state behavior (L2) - UML state charts (L2) - Rol effinition of behavior - Timing diagrams (L3) - Sequence diagrams(L3) - Everpse and strategies of operations(L2) - Architecturral design in UML concurrent	-I EMBEDDED CONCEPTS itroduction to embedded systems(L1), Application Areas(L2), Categories ystems(L2), Overview of embedded system architecture(L2), Specialties ystems(L2), recent trends in embedded systems(L2), Architecture of embedded ardware architecture(L2), Software architecture(L2), Application Software(L2), oftware(L2), Development and Debugging Tools(L2) -II ARM ARCHITECTURE AND OVERVIEW OF CORTEX ackground of ARM Architecture(L2), Architecture Versions(L2), Processor struction Set Development(L2), Thumb-2, and Instruction Set Architecture. Overn's ackground of ARM Architecture, and an anticetable ardware achitecture (L2), Thumb-2, and Instruction Set Architecture. Overn's architectore operations, Reset Sequence. Instruction Sets: Assembly Basics, I astruction Descriptions(L2). Cortex-M3 Implementation Overview: Pipeline, Block trefaces on Cortex-M3, I-Code Bus, D-Code Bus, System Bus, External PPB and D - III CORTEX-M3/M4 PROGRAMMING •verview(L1), Typical Development Flow, Using C, CMSIS (Cortex Microcontrinterface Standard) (L3), Using Assembly Exception Programming: Usir roception/Interrupt Handlers, Software Interrupts, Vector Table Relocation rotection Unit and other Cortex-M3 features: MPU Registers, Setting Up the lanagement, Multiprocessor Communication(L2). - IV UNIFIED MODELING LANGUAGE onnecting the object model with the use case model (L2)- Key strategies for objec. .2)- UML basics(L2). Object state behavior (L2) - UML state charts (L2)- Role of sefinition of behavior - Timing diagrams (L3) - Sequence diagrams(L3) - Event hi / ppes and strategies of operations(L2) - Architectural design in UML concurrency defin (DML(L2). <th>-I EMBEDDED CONCEPTS htroduction to embedded systems(L1), Application Areas(L2), Categories of ystems(L2), Overview of embedded system architecture(L2), Specialties of systems(L2), recent trends in embedded systems(L2), Architecture of embedded sy ardware architecture(L2), Software architecture(L2), Application Software(L2), Com oftware(L2), Development and Debugging Tools(L2) -II ARM ARCHITECTURE AND OVERVIEW OF CORTEX ackground of ARM Architecture(L2), Architecture Versions(L2), Processor N istruction Set Development(L2), Thumb-2, and Instruction Set Architecture. Overview 13 (L2), Cortex-M3 Basics: Registers, General Purpose Registers, Stack Pointer, L1 rogram Counter, Special Registers, Operation Mode, Exceptions and Interrupts, Vect tack Memory Operations, Reset Sequence. Instruction Sets: Assembly Basics, Instrustruction Descriptions(L2). Cortex-M3 Implementation Overview: Pipeline, Block Day Barder, I-CORTEX-M3/M4 PROGRAMMING - III CORTEX-M3/M4 PROGRAMMING verview(L1), Typical Development Flow, Using C, CMSIS (Cortex Microcontroller treface Standard) (L3), Using Assembly Exception Programming: Using xception/Interrupt Handlers, Software Interrupts, Vector Table Relocation(L2). - IV UNIFIED MODELING LANGUAGE onnecting the object model with the use case model (L2)- Key strategies for object id uML2, Object state behavior (L2) - UML state charts (L2)- Role of scenaries (L2). Object state behavior (L2) - UML state charts (L2)- Role of scenaries (L2), Object state behavior (L2) - UML state charts (L2)- Role of scenaries (L2), Object state behavior (L2) - Drolting kernels(L2) - C extensions for systems(L2). -V EMBEDDED SOFTWARE DEVELOPMENT</th> <th>-I EMBEDDED CONCEPTS 9 itroduction to embedded systems(L1), Application Areas(L2), Categories of emt ystems(L2), Overview of embedded system architecture(L2), Specialties of emt ystems(L2), recent trends in embedded systems(L2), Architecture of embedded system ardware architecture(L2), Software architecture(L2), Application Software(L2), Commun oftware(L2), Development and Debugging Tools(L2) 9 -II ARM ARCHITECTURE AND OVERVIEW OF CORTEX 9 ackground of ARM Architecture(L2), Architecture Versions(L2), Processor Namir nstruction Set Development(L2), Thumb-2, and Instruction Set Architecture. Overview of C1 (3) (L2), Cortex-M3 Basics: Registers, General Purpose Registers, Stack Pointer, L & Re rogram Counter, Special Registers, Operation Mode, Exceptions and Interrupts, Vector. T tack Memory Operations, Reset Sequence. Instruction Sets: Assembly Basics, Instruction struction Descriptions(L2). Cortex-M3 Implementation Overview: Pipeline, Block Diagrar tuefraces on Cortex-M3, I-Code Bus, D-Code Bus, System Bus, External PPB and DAP Bus(I - III CORTEX-M3/M4 PROGRAMMING 9 verview(L1), Typical Development Flow, Using C, CMSIS (Cortex Microcontroller So tuefrace Standard) (L3), Using Assembly Exception Programming: Using Inte xception/Interrupt Handlers, Software Interrupts, Vector Table Relocation(L2). M rotection Unit and other Cortex-M3 features: MPU Registers, Setting Up the MPU, lanagement, Multiprocessor Communication(L2). 9 onnecting the object model with the use case model (L2)- Key strategies for object identif (L2)- UML basics(L2). Object state behavior (L2)- UML state charts (L2)- Role of scenarios efinition of behavior - Timing diagrams (L3)- Sequence diagrams(L3) - Event hierarchies types and strategies of operations(L2) - Architectural design in UML</th> <th>-I EMBEDDED CONCEPTS 9 itroduction to embedded systems(L1), Application Areas(L2), Categories of embedd ystems(L2), Overview of embedded system architecture(L2), Specialties of embedd ystems(L2), recent trends in embedded systems(L2), Architecture of embedded systems(L2) ardware architecture(L2), Software architecture(L2), Application Software(L2), Communicati oftware(L2), Development and Debugging Tools(L2) 9 -II ARM ARCHITECTURE AND OVERVIEW OF CORTEX 9 ackground of ARM Architecture(L2), Architecture Versions(L2), Processor Naming(L2 isstruction Set Development(L2), Thumb-2, and Instruction Set Architecture. Overview of Corte I3 (L2), Cortex-M3 Basics: Registers, General Purpose Registers, Stack Pointer, Lk Register rogram Counter, Special Registers, Operation Mode, Exceptions and Interrupts, Vector. Table tack Memory Operations, Reset Sequence. Instruction Set: Assembly Basics, Instruction Li isstruction Descriptions(L2). Cortex-M3 Implementation Overview: Pipeline, Block Diagram, B terfaces on Cortex-M3, I-Code Bus, D-Code Bus, System Bus, External PPB and DAP Bus(L2) 9 - III CORTEX-M3/M4 PROGRAMMING 9 verview(L1), Typical Development Flow, Using C, CMSIS (Cortex Microcontroller Softwar terface Standard) (L3), Using Assembly Exception Programming: Using Interrup rotection Unit and other Cortex-M3 features: MPU Registers, Setting Up the MPU, Pow lanagement, Multiprocessor Communication(L2). 9 onnecting the object model with the use case model (L2)- Key strategies for object identificati 1.2)- UML basics(L2). Object state behavior (L2)- UML state charts (L2)- Role of scenarios in t efinition of behavior - Timing diagrams (L3) - Sequence diagrams(L3) - Event hierarchies (L2) types and strategies of operations(L2)</th>	-I EMBEDDED CONCEPTS htroduction to embedded systems(L1), Application Areas(L2), Categories of ystems(L2), Overview of embedded system architecture(L2), Specialties of systems(L2), recent trends in embedded systems(L2), Architecture of embedded sy ardware architecture(L2), Software architecture(L2), Application Software(L2), Com oftware(L2), Development and Debugging Tools(L2) -II ARM ARCHITECTURE AND OVERVIEW OF CORTEX ackground of ARM Architecture(L2), Architecture Versions(L2), Processor N istruction Set Development(L2), Thumb-2, and Instruction Set Architecture. Overview 13 (L2), Cortex-M3 Basics: Registers, General Purpose Registers, Stack Pointer, L1 rogram Counter, Special Registers, Operation Mode, Exceptions and Interrupts, Vect tack Memory Operations, Reset Sequence. 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Object state behavior (L2) - UML state charts (L2)- Role of scenaries (L2), Object state behavior (L2) - UML state charts (L2)- Role of scenaries (L2), Object state behavior (L2) - Drolting kernels(L2) - C extensions for systems(L2). -V EMBEDDED SOFTWARE DEVELOPMENT	-I EMBEDDED CONCEPTS 9 itroduction to embedded systems(L1), Application Areas(L2), Categories of emt ystems(L2), Overview of embedded system architecture(L2), Specialties of emt ystems(L2), recent trends in embedded systems(L2), Architecture of embedded system ardware architecture(L2), Software architecture(L2), Application Software(L2), Commun oftware(L2), Development and Debugging Tools(L2) 9 -II ARM ARCHITECTURE AND OVERVIEW OF CORTEX 9 ackground of ARM Architecture(L2), Architecture Versions(L2), Processor Namir nstruction Set Development(L2), Thumb-2, and Instruction Set Architecture. 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Object state behavior (L2)- UML state charts (L2)- Role of scenarios efinition of behavior - Timing diagrams (L3)- Sequence diagrams(L3) - Event hierarchies types and strategies of operations(L2) - Architectural design in UML	-I EMBEDDED CONCEPTS 9 itroduction to embedded systems(L1), Application Areas(L2), Categories of embedd ystems(L2), Overview of embedded system architecture(L2), Specialties of embedd ystems(L2), recent trends in embedded systems(L2), Architecture of embedded systems(L2) ardware architecture(L2), Software architecture(L2), Application Software(L2), Communicati oftware(L2), Development and Debugging Tools(L2) 9 -II ARM ARCHITECTURE AND OVERVIEW OF CORTEX 9 ackground of ARM Architecture(L2), Architecture Versions(L2), Processor Naming(L2 isstruction Set Development(L2), Thumb-2, and Instruction Set Architecture. 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Object state behavior (L2)- UML state charts (L2)- Role of scenarios in t efinition of behavior - Timing diagrams (L3) - Sequence diagrams(L3) - Event hierarchies (L2) types and strategies of operations(L2)		

C01	Demonstrate basic concepts of embedded system	L2 - Understand					
C02	Build ARM architecture	L2 - Understand					
CO3	Understand C language and assembly programming L3 - Apply						
C04	Build and compile Object orientation for programming and C++.	L3 - Apply					
C05	Create software modeling	L3 - Apply					
REFEF	RENCE BOOKS:						
1.	The Definitive Guide to the ARM Cortex-M3, Joseph Yiu, Second Edition, Els	sevier Inc. 2010.					
2.	Embedded/Real-Time Systems Concepts, Design and Programming Black E	Book, Prasad, KVK					
3.	David Seal "ARM Architecture Reference Manual", 2001 Addison Wesl Kaufmann Publishers	ey, England; Morgan					
4.	Andrew N Sloss, Dominic Symes, Cohris Wright, "ARM System Developer's Guide -Designing and Optimizing System Software", 2006, Elsevier						
5.	Steve Furber, "ARM System-on-Chip Architecture", 2nd edition, Pearson Ec	lucation.					
6.	Cortex-M series-ARM Reference Manual						
7.	Cortex-M3 Technical Reference Manual (TRM). 8. STM32L152xx ARM Cort Reference Manual	ex M3 Microcontroller					
8.	ARM Company Ltd. "ARM Architecture Reference Manual-RM DDI 0100E".						
9.	David E. Simon, "An Embedded Software Primer", Pearson Education, 2003	3.					
10.	Arnold. S. Berger, "Embedded Systems Design -An introduction to Techniques", Easwer Press.	Processes, Tools and					
11.	ARM v7-M Architecture Reference Manual (ARM v7-M ARM)						
12.	Ajay Deshmukh, "Microcontroller - Theory & Applications", Tata McGraw Hil	l.					
WEB	REFERENCES:						
https	://www.tutorialspoint.com/uml/index.htm						
https	://www.arm.com/architecture						
ONL	INE COURSES:						
https	://onlinecourses.nptel.ac.in/noc22_cs93						
https	://onlinecourses.nptel.ac.in/noc19_cs48/						
VIDE	O REFERENCES:						
https	://www.youtube.com/watch?v=30myM4-zuQw						
https	://www.youtube.com/watch?v=uFhDGagZzjs						
https	https://www.youtube.com/watch?v=t5SuR0rbAxA&list=PLraz73xxhUkPBK2de3CuRb7F3zKh_saUp						

Mapping of COs with POs and PSOs									
60			PO						
0	1	2	3	4	5	6			
CO1	2	3	1	1		3			
CO2	3		3	3	2				
CO3			2	2	3				
CO4			3		3				
CO5	2		3	2	3				
AVG	2.33	3	2.4	2	2.75	3			
	1–Low, 2 –Medium, 3–High.								

ME23ET404		AUTOMOTIVE EMBEDDED SYSTEM				Version: 1.0			
		(COMMON TO ALL BRANCHES)			-				
Prog &Br	gramme anch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	СР 3	L 3	Т 0	P 0	C 3		
Cou	rse Objec	tives:							
1	To expose	e the students to the fundamentals and building of Electronic Engine (Contr	rol s	syste	ms.			
2	To teach f	functional components and circuits for vehicles.							
3	To discus	s programmable controllers for vehicle management systems							
4	To teach l	ogic of automation & and commercial techniques for vehicle commun	icati	on.					
5	To introdu	ice the embedded systems concepts for E-vehicle system developme	nt.						
UNI	T-I	BASIC ELECTRONIC ENGINE CONTROL SYSTEMS			9				
and vehic Hardware ECU- RTOS Society SA system cor		e performance(L2); Automotive microcontrollers(L2)- Electronic & software selection and requirements for Automotive applications(L - Concept for Engine management(L3); Introduction to AUTOSAR a E(L2)- Functional safety ISO 26262(L2)- Simulation and modelin ponents(L3). SENSORS AND ACTUATORS FOR AUTOMOTIVES	cont _2) – nd Ir ng o	rol op ntro f a	Uni en s duct utom	t(L2) ourc ion t notiv)- :e :0 'e		
	 Review of	sensors(12)- sensors interface to the ECU, conventional sensors and	actu	ato	rs M		rn		
	sensors a actuators f	nd actuators (L2) LIDAR sensor(L2) smart sensors MEMS/N for automotive applications(L3).	/NEMS sensors and				nd		
UNI	T– III	VEHICLE MANAGEMENT SYSTEMS			9				
	Electronic control, e braking sy body cont Manageme manageme system(L2	Engine Control-engine mapping, air/fuel ratio spark timing con- lectronic ignition(L2)- Adaptive cruise control (L2)- speed control stem(L2)-electronic suspension - electronic steering(L2), Automatic rol system; Vehicle system schematic for interfacing with EMS, ent system for electric vehicles(L2)- Battery management system (L2)-electrically assisted power steering system)- Safety and Collision Avoidance(L2).	trol ol(L2 wipe ECU /sten adap	stra 2)-a er c J(L2 n(L2 n(L2	nti-la ontro 2). E 2), e li	r, fu ockir ol(L2 Energ pow ghtir	iel ng 2)- 9y er ng		
UNI	T – IV	ONBOARD DIAGNOSTICS AND TELEMATICS			9				
	Onboard c Vehicle cc KWP2000 technology Instrumen	liagnosis of vehicles(L2) -System diagnostic standards and regula ommunication protocols Bluetooth(L2), CAN(L2), LIN(L2), FlexRa (L2) and recent trends in vehicle communications- Navigation(L2) (L2) – Tracking- Security for data communication(L2)- dashboard of tation, multimedia electronics(L2)- Role of IOT in Automotive system	ition y(L2)- Co displa s(L3)	rec), onno ay a	quire MOS ecteo and	men T(L2 J Ca Virtu	ts 2), rs al		
UNIT-V		ELECTRIC VEHICLES			9				
	Electric vehicles (L2)-Components(L2)- Plug-in Electrical Vehicle(L2)- Charg Aggregator(L2) - Autonomous vehicles(L2)					[L2)	-		
	Total: 45 PERIOD								
Cou Upo	rse Outco n complet	mes: ion of this course, the students will be able to:		BL Tax	.00 <mark>1</mark> xonr	4′S omv			
CO	1 Insight automo	into the significance of the role of embedded systems for otive applications.	r L3 - Apply						
СО	D2 Illustrate the need, selection of sensors and actuators, and interfacing L3 - Apply				,				

	with ECU	
CO3	Develop the Embedded concepts for vehicle management and control systems	L2 - Understand
CO4	Demonstrate the need for Electrical vehicles and able to apply the embedded system technology for various aspects of EVs	L3 - Apply
CO5	Improved Employability and entrepreneurship capacity due to knowledge gradation on recent trends in embedded systems design and its application in automotive systems.	L2 - Understand
REFER	RENCE BOOKS:	
1.	William B. Ribbens," Understanding Automotive Electronics", Elsevier, 2012	
2.	Ali Emedi, Mehrdedehsani, John M Miller, "Vehicular Electric power system Space Vehicles" Marcel Decker, 2004.	- land, Sea, Air and
3.	L.Vlacic, M.Parent, F.Harahima," Intelligent VehiclTechnologies", SAE Interna	ational,2001
4.	Jack Erjavec, JeffArias," Alternate Fuel Technology-Electric, Hybrid& F Cengage,2012	Fuel Cell Vehicles",
5.	Electronic Engine Control technology – Ronald K Jurgen Chilton's guide to Fu	iel Injection – Ford
6.	Automotive Electricals / Electronics System and Components, Tom Denton,	3rd Edition, 2004
WEB	REFERENCES:	
https	://archive.nptel.ac.in/courses/108/102/108102121/	
https	://archive.nptel.ac.in/courses/108/106/108106170/	
ONLI	INE COURSES:	
https	://onlinecourses.nptel.ac.in/noc22_ee53/	
https	://onlinecourses.nptel.ac.in/noc21_ee112/	
VIDE	O REFERENCES:	
https	://www.youtube.com/watch?v=UgtjRob5qMg&list=PLyqSpQzTE6M9spod-UH7	Q69wQ3uRm5thr
https	://www.youtube.com/watch?v=V004WUdpHeA&list=PLIYm0-ZdZRLYSylFinxks	spWmcgN∨btl
https	://www.youtube.com/watch?y=L2HbpEMfryM&list=PLp6ek2hDcoNCROoObG0	5xNfiBEY7492Vn

Mapping of COs with POs and PSOs											
60		PO									
CO	1)R	2 /	3	4	5	6					
CO1	1 20	20	1000	anneag	00	2					
CO2	2	3	2	2	2	3					
CO3	3	3	3	3	3	2					
CO4	3	3	3	3	3	2					
CO5	3	3	3	3	3	2					
AVG	2.75	2.8	2.4	2.4	2.75	2.2					
	1-Low, 2 -Medium, 3-High.										

ME	23ET405	405 INTELLIGENT CONTROL AND AUTOMATION				Version: 1.0				
		(COMMON TO ALL BRANCHES)								
Prog &Bra	gramme anch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	СР 3	L 3	Т 0	P 0	С 3			
Cou	rse Objec	tives:		-	•					
1	1 To Impart knowledge of various optimization techniques and hybrid schemes.									
2	To introd	uce the concept, Analysis, and implementation of ANN and Fuzzy log	gic c	ontr	oller	s				
3	To Empha	asize the need for Genetic algorithms and their role in automation.								
4	To provid	e the basics of automation and its requirements								
5	To demor	nstrate the role of Intelligent controllers in automation applications.								
UNI	T-I	ARTIFICIAL NEURAL NETWORK & FUZZY LOGIC:			9					
	ARTIFICIA perceptron Adaptive n controller	L NEURAL NETWORK: Learning with ANNs, single-layer net ns, Back propagation algorithm (BPA) ANNs for identification, AN neuro controller. Fuzzy Logic Control: Introduction, fuzzy sets, fuzz design, Fuzzy Modelling & and identification, Adaptive Fuzzy Contro	worl Ns f zy la l De	ks, or co ogic, sign	mult ontro fuzz	ti-lay ol, a y lo <u>q</u>	er nd jic			
UNI	T-II	-II GENETIC ALGORITHM								
	Basic con Solution f technique	cept of Genetic algorithm and detail algorithmic steps- Hybrid or typical control problems using genetic algorithm. Concept on s like Tabu search, Ant-colony search, and Particle Swarm Optimiza	genetic algorithm - n some other search zation				- ch			
UNI	T– III	III HYBRID CONTROL SCHEMES								
	Fuzzificati function a	on and rule base using ANN–Neuro-fuzzy systems-ANFIS–Optimiza nd rule base using Genetic Algorithm and Particle Swarm Optimizat	tion ion	of m	nemt	persł	nip			
UNI	T – IV	AUTOMATION	9							
	Introducti Automatic of Automa Automatic	on to Automation - Automation in Production System, Principles on, Basic Elements of an Automated System, Advanced Automatio ation- Industrial Automation -computer vision for automation- PLC on- IoT for automation- Industry 4.0.	ano n Fu Cano	d St Inctio d SC	rateg ons, ADA	gies Leve bas	of els ed			
UNI	T-V	INTELLIGENT CONTROLLER FOR AUTOMATION APPLICATION			9					
	Application Appliances Power Sys	ns of Intelligent controllers in Industrial Monitoring, optimization, s- Automation concept for Electrical vehicle- Intelligent controller a stems.	and and	con Auto	trol- mat	Sma ion 1	art [:] or			
			То	tal:	45 F	PERJ	ODS			
Cou	Course Outcomes: Upon completion of this course, the students will be able to:			BL	.00I	M'S				
CO	1 Demo	Demonstrate the basic architectures of NN and Fuzzy logic			L1 – Understand					
CO	2 Desigr	Design and implement GA algorithms and know their limitations.			L2 - Understand					
CO	3 Explain	n and evaluate hybrid control schemes and PSO	L2 - Understand				d			
CO	4 Interp	ret the significance of Automation concepts.	L	3 – A	naly	ze				

CO5	CO5 Develop the intelligent controller for automation applications. L3 - Apply								
REFER	RENCE BOOKS:								
1.	1. Laurene V.Fausett, "Fundamentals of Neural Networks, Architecture, Algorithms, and Applications", Pearson Education, 2008								
2.	Timothy J.Ross, "Fuzzy Logic with Engineering Applications", Wiley, Third	Edition, 2010							
3.	3. David E.Goldberg, "Genetic Algorithms in Search, Optimization, and Machine Learning", Pearson Education, 2009.								
4.	W.T.Miller, R.S.Sutton and P.J.Webrose, "Neural Networks for Control", M	IT Press, 1996							
5.	Srinivas Medida, Pocket Guide on Industrial Automation for Engineers a Technologies	and Technicians, IDC							
6.	ChanchalDey and Sunit Kumar Sen, Industrial Automation Technologie Press, 2022.	es, 1st Edition, CRC							
WEB	REFERENCES:								
https	://archive.nptel.ac.in/courses/127/105/127105006/								
https	://archive.nptel.ac.in/courses/117/105/117105084/								
ONLI	NE COURSES:								
https	://onlinecourses.nptel.ac.in/noc21_ge07/								
https	://nptel.ac.in/courses/117105084								
VIDE	O REFERENCES:								
https	://www.youtube.com/watch?v=xwUKQcT1bKc&list=PLbRMhDVUMngeASctg	zkLEIpgFNZmWwqRl							
https	://www.youtube.com/watch?v=IZWTduVCrf8&list=PLBEDalwGmREACEgLEg	Eefy6PXRN5aZCW_							
https	://www.youtube.com/watch?v=xbYgKoG4x2g&list=PL3EA65335EAC29EE8								

	Mapping of COs with POs and PSOs									
0	E	-	PO		h					
CO	1	2	3	4	5	6				
CO1	1	1	1	1		1				
CO2	2	2 0	3	3	3	2				
CO3	3	2	2	2						
CO4	3	2	2	2						
CO5	3)/)	/	3 / '	3		2				
AVG	2.4	1/1.75	2.2 //	0111 2.2 (1)	((3	1.67				
	1–Low, 2 –Medium, 3–High.									

ME23ET406		T406 UNMANNED AERIAL VEHICLE)			
		(COMMON TO ALL BRANCHES)								
Pro &Bi	gramme ranch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	CP 3	L 3	Т 0	P 0	C 3			
Cοι	irse Obje	ctives:								
1	To make	the students understand the basic concepts and components of UAV	syste	ems	•					
2	To teach	the UAV design concepts								
3	To provid	le an insight into the hardware structure for UAVs								
4	To emph	asize the communication protocol requirements and control strategy	for U	AVs						
5	To highli real-time	ght the need and the role of UAVs for real-time applications and t UAVs	he d	evel	opm	ent	: of			
UN	IT-I	INTRODUCTION TO UAV			9					
	Overview future ou System A	and background(L1) - History of UAV(L1) -classification(L1) - so tlook Unmanned Aerial System (UAS) components (L2)-models and pplications(L2)	cieta prot	l im otyp	ipact bes(l	ar 2)	nd –			
UN	IT-II	THE DESIGN OF UAV SYSTEMS			9					
	Introduct Configura and regul	tion to Design and Selection of the System(L2)- Aerodynamic tions(L2) - Characteristics of Aircraft Types(L2)- Design Standards ations(L2) - Design for Stealth- control surfaces-specifications(L3).	namics and Airframe dards(L2)-Regulatories 3).							
UN	IT– III	III HARDWARE FOR UAVs				9				
	Real-time actuators testing (L	eal-time Embedded processors for UAVs(L2) - sensors-servos-accelerometer (L2)-gyro ctuators(L2)- power supply(L2) - integration(L2), installation(L2), configuration(L2) esting (L2)-MEMS/NEMS sensors and actuators for UAVs(L2)- Autopilot(L2) - AGL(L2)								
UN	IT – IV	· IV COMMUNICATION PAYLOADS AND CONTROLS			9					
	Payloads(radio co test(L2)-a	L2)-Telemetry-tracking(L2)-Aerial photography(L2) -controls(L2)-P ntrol frequency range(L2) -modems-memory system(L2)-simu analysis-trouble shooting(L2)	ID fe lation	eedl n(L3	oack 3)-gr	(L2 our)- nd			
UN	IT-V	V THE DEVELOPMENT OF UAV SYSTEMS				9				
	Waypoint flight Test Disaster N	s navigation-ground control software(L2)- System Ground Testing ting(L2)- Mini, Micro, and Nano UAVs(L2)- Case study: Agriculture- H Management and Defense(L3).	(L2)- lealth	י Sy ו- Sי	sten urve	ו I yin	n- g-			
		-	Tota	l: 4	5 PE	RI	ODS			
Cou Upo	irse Outco on comple	omes: otion of this course, the students will be able to:	-	BL0 Tax	DOM ono	l′S my				
CC	CO1 Identify different hardware for UAV		L2	– L	Inde	rsta	and			
CO2 Determine vehicle		mine preliminary design requirements for an unmanned aerial e	rial L3 - Apply		pply	ply				
CO3 Design UAV system.		n UAV system.	L2 - Understand			nd				
СС	04 Identi	fy and Integrate various systems of unmanned aerial vehicles.	L3	- A	pply					
СС	05 Desigr Demo	n micro aerial vehicle systems by considering practical limitations. nstrate the basic architectures of NN and Fuzzy logic.	ons. L3 - Apply							

REFEF	RENCE BOOKS:
1	Reg Austin "Unmanned Aircraft Systems UAV design, development and deployment", Wiley,
1.	2010. 2. 3. 4. 5
2.	Paul G Fahlstrom, Thomas J Gleason, "Introduction to UAV Systems", UAV Systems, Inc, 1998
3	Dr. Armand J. Chaput, "Design of Unmanned Air Vehicle Systems", Lockheed Martin
5.	Aeronautics Company, 2001
4	Kimon P. Valavanis, "Advances in Unmanned Aerial Vehicles: State of the Art and the Road to
ч.	Autonomy", Springer, 2007
	Robert C. Nelson, Flight Stability and Automatic Control, McGraw-Hill, Inc, 1998. Laurene
5.	V.Fausett, "Fundamentals of Neural Networks, Architecture, Algorithms, and Applications",
	Pearson Education, 2008
WEB	REFERENCES:
https	://archive.nptel.ac.in/courses/101/104/101104083/
https	://geopard.tech/blog/how-to-use-drones-in-precision-agriculture/
ONL	INE COURSES:
https	://nptel.ac.in/courses/117105082
https	://onlinecourses.nptel.ac.in/noc21_ae14/
VIDE	O REFERENCES:
https	://www.youtube.com/watch?v=j9y0gfN9WMg&list=PL5873EDBDFB69BAD8

https://www.youtube.com/watch?v=9c769xiEXn0&list=PLFW6IRTa1g83B1HdU2mece6QLeBrtspL7

https://www.youtube.com/watch?v=Sfg7cbfSUdc&list=PL_Vndgv2m9Hzifu5K32-BY5ILAI8Z7IGE

6

Mapping of COs with POs and PSOs										
60			PO							
0	1 3	2	3	4	5	6				
CO1	10	3	2	2		2				
CO2	3	3	3			2				
CO3	3	3	3	3	3	3				
CO4	1		2	3	3	2				
CO5	3		3	3	3	3				
AVG	2.5	3	2.6	3	3	2.4				
	1-Low, 2-Medium, 3-High,									

Beyond Knowledge

ME23ET407		DSP-BASED SYSTEM DESIGN	Version: 1.0						
		(COMMON TO ALL BRANCHES)							
Prog &Bra	Jramme anch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	СР 3	L 3	Т 0	Р 0	C 3		
Cou	rse Objec	tives:							
1	1 To understand various representation methods of the DSP system								
2	To provid	e insight into different DSP algorithms							
3	To familia	rize the various architectures of the DSP system							
4	To perfor programn	m analysis of DSP architectures and to learn the implementation nable hardware	n of	DSP	sys	tem	s in		
5	To learn t	he details of DSP system interfacing with other peripherals							
UNI	T-I	REPRESENTATION OF DSP SYSTEM			9				
	power, sn systems(L Technique	nall code size, embedded applications(L2). Representation of digita 2) - block diagrams, signal flow graphs, data-flow graphs, dependent s for enhancing computational throughput(L2) - parallelism and pip	al sig nden elinir	inal ce g ng(L2	proc rapł 2).	essii is(L2	ng 2).		
UNI	T–II	-II DSP ALGORITHMS							
	converters Computat of signals-	s, DCT, Decimator, Expander, and Filter Banks(L3). DSF ional characteristics of DSP algorithms and applications(L3), Nume word length effect and its impact, Carry-free adders, Multiplier(L3).	er Banks(L3). DSP applications(L3). oplications(L3), Numerical representation adders, Multiplier(L3).						
UNI	T– III	III SYSTEM ARCHITECTURE				9			
	Introducti Architectu Programm architectu MIPS(L2), Prediction architectu	on(L2), Basic Architectural Features(L2), DSP Computational Build re and Memory(L2), Data Addressing Capabilities(L2), Address G ability and Program Execution(L2), Features for External Int re(L2). Basic performance issues in pipelining(L2), Simple Instruction Level Parallelism(L2), Dynamic Scheduling(L2), I (L2), and Memory hierarchy(L2).Study of FIxed point and f res(L2)	ing E ener erfac imple Dyna loatii	Block atior ing(eme mic ng	s(L2 n Un L2). ntati Hai poin), B it(L2 VLI on dwa t DS	us 2), W of FP		
UNI	Τ – ΙV	ARCHITECTURE ANALYSIS ON PROGRAMMABLE HARDWARE			9				
	Analysis o Lattice fil Convolutio systems, o	of basic DSP Architectures on programmable hardware(L2). Algor ter structures, architectures for real and complex fast Fourier ons, Winograd minimal filtering algorithm(L3). FPGA: Architect design flow for DSP system design, mapping of DSP algorithms onto	ithm trans ure, FPG	s fo sforr diffe A(L2	r FII ns, eren [:] 2).	R, II 1D/2 : su	R, 2D b-		
UNI	T-V	SYSTEM INTERFACING			9				
	Examples of digital signal processing algorithms suitable for parallel architect and multi GPUs(L2). Interfacing: Introduction, Synchronous Serial Interface C Interface Circuit, ADC interface(L2).			suc (L2)	h as , A (GPI CODI	Js EC		
							ODS		
Cou Upo	Course Outcomes: Upon completion of this course, the students will be able to:			BLOOM'S Taxonomy					
CO	Evalua	te the DSP system using various methods.	L2 - Understand				d		
coz	CO2 Design algorithm suitable for different DSP applications			L3 – Apply					

CO3	Explain various architectures of the DSP system L2 - Understan						
CO4	Implement a DSP system in programmable hardware	L3 – Apply					
CO5	Build interfacing of the DSP system with various peripherals.	L2 - Understand					
REFE	RENCE BOOKS:						
1.	Sen M Kuo, Woon Seng S Gan, Digital Signal Processors						
2.	Digital Signal Processing and Application with C6713 and C6416 DSI Worcester Polytechnic Institute, A Wiley Interscience Publication	K, Rulph Chassaing,					
3.	Architectures for Digital Signal Processing, Peter Pirsch John Weily, 2007						
4.	DSP Processor and Fundamentals: Architecture and Features. Phil Lapsle Edward A Lee; Wiley IEEE Press	y, JBier, AmitSohan,					
5.	K. K. Parhi - VLSI Digital Signal Processing Systems - Wiley - 1999.						
6.	RulphChassaing, Digital signal processing, and applications with C6713 an 2005	d C6416 DSK, Wiley,					
7.	Keshab K Parhi, VLSI Digital Signal Processing Systems: Design and Imp Edition, Wiley, 1999.	lementation, student					
8.	Nasser Kehtarnavaz, Digital Signal Processing System Design: Lab Programming, Academic Press, 2008	VIEW-Based Hybrid					
WEB	REFERENCES:						
https	://archive.nptel.ac.in/courses/108/106/108106151/						
https	://archive.nptel.ac.in/courses/108/101/108101174/						
ONL	INE COURSES:						
https	https://nptel.ac.in/courses/117102060						
https	https://onlinecourses.nptel.ac.in/noc21_ee20/						
VID	EO REFERENCES:						
https	://www.voutube.com/watch?v=6dFnpz_AEvA&list=PL9567DFCA3A66F299						

https://www.youtube.com/watch?v=0ENnxVXEv_U&list=PLOzRYVm0a65cU4xstihnbnrCPHenmJJ7f

		5	ALEW							
Mapping of COs with POs and PSOs										
<u> </u>			PO		2					
co	Bo	10 20	3	1.11400	005	6				
CO1		3			1					
CO2	3	3	3	2	3	2				
CO3		3								
CO4	3		3	3	3	3				
CO5	2		3	2	3	3				
AVG	2.67	3	3	2.33	3	2.67				
	1-Low, 2 -Medium, 3-High.									

м	E23ET408	ET408 MACHINE LEARNING AND DEEP LEARNING							
		(COMMON TO ALL BRANCHES)			-				
Pro	gramme &	M.E. EMBEDDED SYSTEM TECHNOLOGIES	СР	L	Т	P	C		
Cou	rse Objective	25:	3	U	U	U	3		
1	Understanding	g about the learning problem and algorithms							
2	Providing insi	ght about neural networks							
3	Introducing th	ne machine learning fundamentals and significance							
4	Enabling the s	students to acquire knowledge about pattern recognition							
5	Motivating the infrastructure	e students to apply deep learning algorithms for solving rea	l life p	orob	lems	. met	ering		
נאט	T-I	LEARNING PROBLEMS AND ALGORITHMS			9				
Vari algo	ous paradigm rithms(L2)	ns of learning problems(L2), Supervised, Semi-supervi	sed	and	Un	super	vised		
UNI	T-II	NEURAL NETWORKS			9				
Diffe Activ Star Hete Lear	erences betwe vation Functio Idard Back pro ero associative ning Vector Q	en Biological and Artificial Neural Networks(L2) - Typical ns, Multi-layer neural network, Linear Separability, Hebb N ppagation Training Algorithms for Pattern Association (L2)- H e, Auto associative, Kohonen Self Organising Maps, Exar uantization, Gradient descent, Boltzmann Machine Learning.	l Arcł let, P lebb i nples (L2)	nitec erce rule of	ture ptroi and Feat	, Com n, Ada Delta ure N	imon aline, rule, 1aps,		
נאט	T- III	MACHINE LEARNING – FUNDAMENTALS & FEATURE SELECTIONS & CLASSIFICATIONS	9						
Clas dim stop redu clas	sifying Sample ensionality, tra ping, regular oction, Classifi sification, clus	es: The confusion matrix, Accuracy, Precision, Recall, F1(L aining, testing, validation, cross validation, overfitting, unde ization, bias and variance. Feature Selection, norma iers: KNN, SVM, Decision trees, Naïve Bayes, Binary cl tering(L2).	_2)- 9 er-fitt lizatio assifio	Score ing on, catio	e, th the o dim n, r	e cur data, ensioi nulti	se of early nality class		
UNI	T – IV	DEEP LEARNING: CONVOLUTIONAL NEURAL NETWORKS			9				
Feed batc CNN	forward netwhere the set of the s	works(L2), Activation functions(L2), back propagation in Con, convolution layers, pooling layers, fully connected layer	CNN(L s, dro	2), (opou	optin t, E>	nizers kampl	(L2), es of		
UNI	T-V	DEEP LEARNING: RNNS, AUTOENCODERS AND GANS			9				
Stat Auto GAN	e, Structure encoders: Co s: The discrim	of RNN Cell, LSTM and GRU(L2), Time distributed la nvolutional Autoencoders, Denoising autoencoders, Variat inator, generator, DCGANs(L2).	yers, ional	Ge aut	nera oenc	ting oders	Text, (L2),		
			То	tal	: 45	PERI	ODS		
Cou Upo	rse Outcome n completior	s: • of this course the students will be able to:		Bl Ta	.00 xon	M′S omy			
CO	CO1 Illustrate the categorization of machine learning algorithms.			– U	nder	stand			
CO	CO2 Compare and contrast the types of neural network architectures, activation functions			– U	nder	stand			
CO	CO3 Acquaint with the pattern association using neural networks				L2 – Understand				
CO	Elaborate v architecture	arious terminologies related with pattern recognition and es of convolutional neural networks	L2	– U	nder	stand			
CO:	Construct d advanced r and GANs	ifferent feature selection and classification techniques and neural network architectures such as RNN, Autoencoders,	L2	– U	nder	stand			

DEEE							
1.	J. S. R. Jang, C. T. Sun, E. Mizutani, Neuro Fuzzy and Soft Computing - A Computational Approach to Learning and Machine Intelligence, 2012, PHI learning.						
2.	Deep Learning, Ian Good fellow, YoshuaBengio and Aaron Courville, MIT Press, ISBN: 9780262035613, 2016.						
3.	The Elements of Statistical Learning. Trevor Hastie, Robert Tibshirani and Jerome Friedman. Second Edition. 2009.						
4.	Pattern Recognition and Machine Learning. Christopher Bishop. Springer. 2006						
5.	Understanding Machine Learning. Shai Shalev-Shwartz and Shai Ben-David. Cambridge University Press. 2017.						
WEB	REFERENCES:						
https:	//archive.nptel.ac.in/courses/106/106/106106139/						
https:	//archive.nptel.ac.in/courses/106/106/106106202/						
ONLI	NE COURSES:						
https:	//nptel.ac.in/courses/117105084						
https:	//onlinecourses.nptel.ac.in/noc23_ee87/						
VIDE	D REFERENCES:						
https:	//www.youtube.com/watch?v=KshIEHQn5ZM						
https:	//www.youtube.com/watch?v=TIFFfLejkcA						
https: ndex=	//www.youtube.com/watch?v=4TC5s_xNKSs&list=PLyqSpQzTE6M9gCgajvQbc68Hk_JKGBAYT&i 2						

			\$ M.	2						
Mapping of COs with POs and PSOs										
60		14	PO							
CO	1	2	3	4	5	6				
CO1	1	3 9	ma in							
CO2	2	3	2							
CO3	3		3		3					
CO4	2	2 3	3	/ /						
CO5	3	201/3/10	3.110	meage	3					
AVG	2.42	3	2.57		3					
	1–Low, 2 –Medium, 3–High.									

Open Elective Courses I & II

Beyond Knowledge

м	IE23ET501	IOT FOR SMART SYSTEMS	v	ersi	ion	: 1.(D
		(COMMON TO ALL BRANCHES)					-
Prog Brar	gramme & nch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	CP 3	L 3	Т 0	P 0	C 3
Cou	rse Objective	S:					
1	To study about	t Internet of Things technologies and its role in real time appli	catio	ons.			
2	To introduce th	ne infrastructure required for IoT					
3	To familiarize	the accessories and communication techniques for IoT.					
4	To provide insi	ght about the embedded processor and sensors required for I	оТ				
5	To familiarize	the different platforms and Attributes for IoT					
UNI	T-I	INTRODUCTION TO INTERNET OF THINGS			9		
Over drive	view(L2), Harc er(L2)s, Busine	ware and software requirements for IOT(L2), Sensor and ac ss drivers(L2), Typical IoT applications(L3), Trends and implic	tuat atior	ors, is(L	Teo 3).	chno	logy
UNI	T-II	IOT ARCHITECTURE			9		
IoT Com stan	reference m munication, P dards(L2), Clou	odel and architecture (L2)-Node Structure(L2) - Se owering, Networking(L2) - Topologies(L2), Layer/Stack a d computing for IoT(L2), Bluetooth(L2), Bluetooth Low Energ	ensin rchit y be	g, ectu acor	Pro re(l 1s(L	cess _2) , 2).	sing, IoT
UNI	T– III	PROTOCOLS AND WIRELESS TECHNOLOGIES FOR IOT PROTOCOLS:	CHNOLOGIES FOR IOT 9				
NFC, smal ZigB	SCADA and R cell(L2). Wir	FID, Zigbee, MIPI, M-PHY, UniPro, SPMI, SPI, M-PCIe, GSM reless technologies for IoT: WiFi (IEEE 802.11), Bluetoo art, UWB (IEEE 802.15.4), 6LoWPAN, Proprietary systems-Rec	M, CDMA, LTE, GPRS, ooth/Bluetooth Smart, ecent trends (12)				
UNI	T – IV	IOT PROCESSORS			9	(/	
Serv Maint Emb RASP	ices/Attribute tainability. (L2) edded proces PERRY PI and A	es: Big-Data Analytics for IOT, Dependability, Intero ssors for IOT :Introduction to Python programming(L2) rduino(L3)	pera -Bu	oility ildin	/, g I	Secu OT	urity, with
UNI	T-V	CASE STUDIES			9		
Indu char	strial IoT, Hor ging, Environm	me Automation, smart cities, Smart Grid, connected vehic ent, Agriculture, Productivity Applications, IOT Defense(L3)	les,	elec	ctric	veł	nicle
		Deyond Oxnowledge	otal	: 4	5 P	ERIC	DDS
C ou At th	r se Outcomes ne end of this c	: ourse, the students will have the ability to		BL Tax	00l	M′S omv	
CO	Analyze the	concepts of IoT and its present developments.		L3	- Ar	ply	
CO2	Compare an for IoT	d contrast different platforms and infrastructures available	L2	- Ur	nder	stan	ldS
COS	B Explain diffe	rent protocols and communication technologies used in IoT	L2	: - U	nde	rsta	nd
CO4	CO4 Analyze the big data analytic and programming of IoT			L3	- Ar	ply	
COS	5 Implement I	IoT solutions for smart applications		L3	- Ar	ply	
REF	ERENCE BOOK	(S:					
1.	1. ArshdeepBahga and VijaiMadisetti : A Hands-on Approach "Internet of Things", Universitie					ities	
2.	Oliver Herse	nt , David Boswarthick and Omar Elloumi " The Internet of Th	ingsʻ	', Wi	iley	,201	6.
3.	Samuel Gree	engard, " The Internet of Things", The MIT press, 2015.					
4.	Adrian McEw	ven and Hakim Cassimally"Designing the Internet of Things "V	lley	,201	4.		
Г	Jean- Philip	Jean- Philippe Vasseur, Adam Dunkels, "Interconnecting Smart Objects with IP: The Next					

	Internet" Morgan Kuffmann Publishers, 2010.						
6.	Adrian McEwen and Hakim Cassimally, "Designing the Internet of Things", John Wiley and sons, 2014.						
7.	Lingyang Song/DusitNiyato/ Zhu Han/Ekram Hossain,"Wireless Device-to-Device Communications and Networks, CAMBRIDGE UNIVERSITY PRESS,2015.						
8.	OvidiuVermesan and Peter Friess (Editors), "Internet of Things: Converging Technologies for Smart Environments and I ntegrated Ecosystems", River Publishers Series in Communication, 2013.						
9.	Vijay Madisetti, ArshdeepBahga, "Internet of Things (A Hands on-Approach)", 2014.						
10.	Zach Shelby, Carsten Bormann, "6LoWPAN: The Wireless Embedded Internet", John Wiley and sons, 2009.						
11.	Lars T.Berger and Krzysztof Iniewski, "Smart Grid applications, communications and security", Wiley, 2015.						
12.	JanakaEkanayake, KithsiriLiyanage, Jianzhong Wu, Akihiko Yokoyama and Nick Jenkins, " Smart Grid Technology and Applications", Wiley, 2015.						
13.	UpenaDalal, "Wireless Communications & Networks, Oxford, 2015.						
WEB I	WEB REFERENCES:						
https:,	https://archive.nptel.ac.in/courses/106/105/106105166/						
https:,	https://www.geeksforgeeks.org/architecture-of-internet-of-things-iot/						

ONLINE COURSES:

https://onlinecourses.nptel.ac.in/noc22_cs53/

https://www.udemy.com/course/internet-of-things-iot-fundamentals

-

VIDEO REFERENCES:

https://www.youtube.com/watch?v=WUYAjxnwjU4&list=PLE7VH8RC_N3bpVn-e8QzOAHziEgmjQ2qE

https://www.youtube.com/watch?v=urUBLmXFKI0&list=PLgMDNELGJ1CaBrefq-0eYatfOnoncW0y-

https://www.youtube.com/watch?v=hdZzNOQV5vU

Mapping of COs with POs and PSOs										
<u> </u>	.)	Derjond	PO	medge						
CO	1	2	3	4	5	6				
CO1	1	2	1							
CO2		2								
CO3	1	2		1	3					
CO4	2		3	3	3	3				
CO5	3	2	3	3	3	3				
AVG	1.75	2	2.33	2.33	3	2				
		1-Low, 2	–Medium, 3–I	High.						

ME23ET502		T502 MACHINE LEARNING AND DEEP LEARNING				Version : 1.0					
		(COMMON TO ALL BRANCHES)									
Pro Bra	gramme & nch	M.E. EMBEDDED SYSTEM TECHNOLOGIES	<u>СР</u> 3	L	Т 0	Р 0	С 3				
Cou	rse Objective	25:		•	•	•					
1 Understanding about the learning problem and algorithms											
2 Providing insight about neural networks											
3	Introducing th	ne machine learning fundamentals and significance									
4	Enabling the s	students to acquire knowledge about pattern recognition									
5	Motivating the infrastructure	e students to apply deep learning algorithms for solving rea	l life ı	orob	lems	. met	ering				
נאט	T-I	LEARNING PROBLEMS AND ALGORITHMS			9						
Vari algo	ous paradigm rithms(L2)	ns of learning problems(L2), Supervised, Semi-supervi	sed	and	Un	super	vised				
UNI	T-II	NEURAL NETWORKS			9						
Activ Star Hete Lear	erences betwee vation Functio Idard Back pro ero associative ning Vector Q	en Biological and Artificial Neural Networks(L2) - Typica ns, Multi-layer neural network, Linear Separability, Hebb N pagation Training Algorithms for Pattern Association (L2)- H e, Auto associative, Kohonen Self Organising Maps, Exar uantization, Gradient descent, Boltzmann Machine Learning.	I Arci let, P lebb I nples (L2)	rule of	ture, ptror and Feat	, Con n, Ada Delta ure N	nmon aline, rule, 1aps,				
UNI	T– III	SELECTIONS & CLASSIFICATIONS	9								
Clas dime stop redu	sifying Samplensionality, tra ping, regular oction, Classifi sification, clussifi	es: The confusion matrix, Accuracy, Precision, Recall, F1(l aining, testing, validation, cross validation, overfitting, und ization, bias and variance. Feature Selection, norma iers: KNN, SVM, Decision trees, Naïve Bayes, Binary cl tering(12).	_2)- S er-fitt lizatio assifio	Score ing on, catio	e, th the o dim n, r	e cur data, ensioi nulti	se of early nality class				
UNI	Τ – ΙV	DEEP LEARNING: CONVOLUTIONAL NEURAL NETWORKS			9						
Feed bato CNN	l forward net h normalizatio s(L2).	works(L2), Activation functions(L2), back propagation in C on, convolution layers, pooling layers, fully connected layer	CNN(L s, dro	2), (opou	optin t, E>	nizers kampl	(L2), es of				
UNI	T-V	DEEP LEARNING: RNNS, AUTOENCODERS AND GANS			9						
Stat Auto GAN	e, Structure encoders: Co s: The discrim	of RNN Cell, LSTM and GRU(L2), Time distributed la nvolutional Autoencoders, Denoising autoencoders, Variat inator, generator, DCGANs(L2).	yers, ional	Ge aut	nera oenc	ting oders	Text, (L2),				
			То	tal	: 45	PER]	ODS				
Cou Upo	rse Outcome <u>n completior</u>	s: • of this course the students will be able to:		Bl Ta:	.00 xon	M′S omy					
CO	CO1 Illustrate the categorization of machine learning algorithms.			L2 – Understand							
CO2 Compare and contrast the types of neural network architectures, activation functions				L2 – Understand							
CO	CO3 Acquaint with the pattern association using neural networks					L2 – Understand					
CO	Elaborate v architecture	arious terminologies related with pattern recognition and es of convolutional neural networks	d L2 – Understand								
CO:	Construct d advanced r and GANs	ifferent feature selection and classification techniques and neural network architectures such as RNN, Autoencoders,	L2	– U	nder	stand					

REFE	RENCE BOOKS:
1.	J. S. R. Jang, C. T. Sun, E. Mizutani, Neuro Fuzzy and Soft Computing - A Computational Approach to Learning and Machine Intelligence, 2012, PHI learning.
2.	Deep Learning, Ian Good fellow, YoshuaBengio and Aaron Courville, MIT Press, ISBN: 9780262035613, 2016.
3.	The Elements of Statistical Learning. Trevor Hastie, Robert Tibshirani and Jerome Friedman. Second Edition. 2009.
4.	Pattern Recognition and Machine Learning. Christopher Bishop. Springer. 2006
5.	Understanding Machine Learning. Shai Shalev-Shwartz and Shai Ben-David. Cambridge University Press. 2017.
WEB	REFERENCES:
https:	//archive.nptel.ac.in/courses/106/106/106106139/
https:	//archive.nptel.ac.in/courses/106/106/106202/
ONLI	NE COURSES:
https:	//nptel.ac.in/courses/117105084
https:	//onlinecourses.nptel.ac.in/noc23_ee87/
VIDE	O REFERENCES:
https:	//www.youtube.com/watch?v=KshIEHQn5ZM
https:	//www.youtube.com/watch?v=TIFFfLejkcA
https: ndex=	//www.youtube.com/watch?v=4TC5s_xNKSs&list=PLyqSpQzTE6M9gCgajvQbc68Hk_JKGBAYT&i 2

Mapping of COs with POs and PSOs									
<u> </u>	7	e -	PO	5					
co	1	2	3	4	5	6			
CO1	1	3	1						
CO2	2	3 5	BLE21						
CO3	3		3		3				
CO4	2	3	3						
CO5	CO5 3 3 3 3 3								
AVG	2.42	3/10	2.57	meage	3				
1-Low, 2 -Medium, 3-High.									

ME23ET503		RENEWABLE ENERGY AND GRID INTEGRATION	Version : 1.0						
	(COMMON TO ALL BRANCHES)								
Programme & Branch		M.E. EMBEDDED SYSTEM TECHNOLOGIES	СР 3	L 0	Т 0	P 0	C 3		
Course Objectives:							-		
1 1	1 To provide knowledge about the different types of renewable energy technologies								
2 ¹	Fo provide kr systems	nowledge on standalone operation, grid connected operatio	n of	rene	wab	le e	nergy		
UNIT	I -I	INTRODUCTION	9						
Class Renev impac Emiss Applic	ification of e wable energy cts of renew sion(L2) - cations(L2)	energy sources(L2) – Co2 Emission (L2)- Features of Re y scenario in India(L2) -Environmental aspects of electr wable energy generation on environment Per Capital importance of renewable energy sources, Potentia	enewa ric er Con Is -	able nerg sum - A	ene y co ptior chie	rgy(nve n - vem	L2) - rsion: CO2 ents-		
UNIT	-II	SOLAR PHOTOVOLTAICS			9				
Solar solar Photo I-V diode	Energy: Sur collector(L2) ovoltaic cell c characteristic (L2).	n and Earth(L1)-Basic Characteristics of solar radiation(L2) -Estimating Solar Radiation Empirically (L2)- Equivalent haracteristics: P-V and I-V curve of cell-Impact of Tempera s(L2), Shading Impacts on I-V characteristics(L2)-By)- an circu ature pass	gle it of and dio	of su PV Inso de	unra Cel olati -Blc	ys on I(L2)- on on ocking		
UNIT	– III	PHOTOVOLTAIC SYSTEM DESIGN			9				
Block and t classi conne	diagram of souck-boost configuration (L2)- fication(L2)- ection issues(solar photo voltaic system: Line commutated converters (ir onverters(L2) - selection of inverter, battery sizing, array s standalone PV systems(L2) - Grid tied and grid interact L2).	iversi izing ive i	on r (L2) nver	node)- P\ ters(e) - / sys (L2) [,]	Boost stems - grid		
UNIT	I – IV	WIND ENERGY CONVERSION SYSTEMS	9						
Origin limit Vertio Solidi syste integ	n of Winds: G Power availa cal axis wind ity-Blade Cou ms: Type A, rated SCIG a	Global and Local Winds(L2)- Aerodynamics of Wind turbine(L ble in wind(L2)-Classification of wind turbine: Horizontal d turbine(L2)- Aerodynamic Efficiency(L3)-Tip Speed(L2) unt-Power curve of wind turbine (L2)- Configurations of w Type B, Type C and Type D Configurations(L2)- Grid conne nd PMSG based WECS(L3).	_3)-D Axis -Tip vind e ection	eriva wind Spe energ Issi	ation d tur ed f gy c ues(l	of l rbine Ratic onve L2)	Betz's e and o(L3)- ersion - Grid		
UNIT	-V	OTHER RENEWABLE ENERGY SOURCES	9						
Quali syste Geoth	tative study ms, Fuel ce nermal Energ	of different renewable energy resources: ocean(L2), Biom Ils, Ocean Thermal Energy Conversion (OTEC)(L2), Tid y Resources(L2).	nass, al ai	Hyd nd N	roge vave	en e e en	nergy Iergy,		
			Tot	al :	45 I	PER	IODS		
Cour Upor	se Outcome <u>completior</u>	s: • of this course the students will be able to:		BL Tax	.00I conc	Ч′S omy			
CO1	Demonstrat	e the need for renewable energy sources.	L2	2 – U	nde	rstar	nd		
CO2	Develop a stand-alone photo voltaic system and implement a maximum power point tracking in the PV system			a L2 – Understand			and		
CO3	Design a stand-alone and Grid connected PV system			L2 – Understand			and		
CO4	Analyze the different configurations of the wind energy conversion systems.			n L3 - Apply			/		
CO5 Realize the basic of various available renewable energy sources					L2 – Understand				
REFE	RENCE BOO	KS:	<u> </u>						
1.	S.N.Bhadra 2009.	, D. Kastha, & S. Banerjee "Wind Electrical Systems", C	Oxfor	d Ur	niver	sityl	^{>} ress,		

3.	Rai. G.D, "Non conventional energy sources", Khanna publishes, 1993.						
4.	Rai. G.D," Solar energy utilization", Khanna publishes, 1993.						
5.	Chetan Singh Solanki, "Solar Photovoltaics: Fundamentals, Technologies and Applications", PHI Learning Private Limited, 2012						
6.	John Twideu and Tony Weir, "Renewal Energy Resources" BSP Publications, 2006						
WEB	WEB REFERENCES:						
https: ETSAF	https://www.irena.org/-/media/Files/IRENA/Agency/Publication/2015/IRENA- ETSAP Tech Brief Power Grid Integration 2015.pdf						

https://www.nrel.gov/docs/fy15osti/63033.pdf

ONLINE COURSES:

https://www.coursera.org/learn/renewable-power-electricity-systems

https://nptel.ac.in/courses/103103206

VIDEO REFERENCES:

https://www.youtube.com/watch?v=mh51mAUexK4&list=PLwdnzIV3ogoXUifhvYB65ILJCZ74o_fAk

https://www.youtube.com/watch?v=cGHIV0EavaQ

Mapping of COs with POs and PSOs									
<u> </u>		40	PO	10					
CO	1	4 2	3	4	5	6			
CO1	3	0	2	2	2	1			
CO2	3		2	3	3	3			
CO3	3 🧹		2	3	3	3			
CO4	3		2	3	3	2			
CO5	3	9 4	2	2	2	1			
AVG	3		2						

1-Low, 2 -Medium, 3-High.



Beyond Knowledge

ME2	3ET504	SMART GRID	,	Vers	sio	n : 1	.0				
(COMMON TO ALL BRANCHES)											
Pro	ogramme &	M.E. EMBEDDED SYSTEM TECHNOLOGIES	СР	L	T	Р	С				
Cou	Branch	2 6 .	3	0	0	0	3				
1	To Study ab	To Study about Smart Grid technologies, different smart meters and advanced n nfrastructure.									
2	To know abou	o know about the function of smart grid									
3	To familiarize the power quality management issues in Smart Grid										
4	To familiarize	the high performance computing for Smart Grid applications									
5	To get familia	rized with the communication networks for Smart Grid applicatio	ons								
UNI	T-I	INTRODUCTION TO SMART GRID			9						
Evol func Grid in Si	ution of Elect tions, opport (L2), Compari <u>mart Grid, Sm</u>	ric Grid(I2), Concept, Definitions and Need for Smart Grid(I2), unities, challenges and benefits(I2), Difference between cor son of Micro grid and Smart grid(I2), Present development & I art Grid Initiative for Power Distribution Utility in India(I2) – Cas	Sm nven inter e St	art g tiona natio udy(gric al ona (L2	d driv & Si il pol).	/ers, nart icies				
UNI	T-II	SMART GRID TECHNOLOGIES			9						
Auto area Dete Distr (PHE	mation(L2), F monitoring(L ection(L2), Is ribution Trans EV(L2)) (L2) –	Feeder Automation(L2), Transmission systems: EMS, FACTS a .2), Protection and control, Distribution systems: DMS(L2), Vo olation and service restoration(L2), Outage management(I sformers(L2), Phase Shifting Transformers(L2), Plug in Hybr Grid to Vehicle and Vehicle to Grid charging concepts(L2)	nd H lt/Va L2), rid E	HVD ar co Hig Elect	C(L ont gh- ric	2), N rol, I Effici Veh	Vide Fault ency icles				
UNI	T– III	SMART METERS AND ADVANCED METERING INFRASTRUCTURE	9								
Intro AMI Unit resp Prici	oduction to Sr protocols, sta (PMU) & their onse progran ng(L2).	mart Meters(L1), Advanced Metering infrastructure (AMI) drive andards and initiatives(L2), AMI needs in the smart grid(L2), F application for monitoring & protection(L2). Demand side manages ns(L2), Demand pricing and Time of Use, Real Time Price	rs a Phase geme ing(l	nd b or M ent a _2),	ben leas and Pe	efits(surer I dem eak	(L2), nent nand Fime				
UNI	T – IV	POWER QUALITY MANAGEMENT IN SMART GRID	9								
Pow Soui mon	er Quality & E ces(L2), Pov itoring(L2), Po	MC in Smart Grid(L2), Power Quality issues of Grid connected wer Quality Conditioners for Smart Grid(L2), Web bas ower Quality Audit (L2).	d Re sed	new Pov	abl ver	e En Qu	ergy ality				
UNI	T-V	HIGH PERFORMANCE COMPUTING FOR SMART GRID APPLICATIONS	9								
Arch Netv of W	itecture and S vork (WAN), E eb Service an	Standards(L2) -Local Area Network (LAN), House Area Networ Broadband over Power line (BPL), PLC, Zigbee, GSM, IP based F d CLOUD Computing(L2), Cyber Security for Smart Grid(L2).	k (H Proto	AN) cols	, W s(L2	/ide / 2), Ba	Area asics				
Total : 45 PERIODS											
Course Outcomes: BLOOM Upon completion of this course the students will be able to: Taxonor						M'S omy	,				
C01	CO1 Relate with the smart resources, smart meters and other smart devices.					L2 – Understand					
CO2	D2 Explain the function of Smart Grid					L2 – Understand					
CO3	Experiment	the issues of Power Quality in Smart Grid.	L2 – Understand				and				
C04	4 Analyze the performance of Smart Grid					L2 – Understand					

CO5	Recommend suitable communication networks for smart grid applications	L2 – Understand							
REFERENCE BOOKS:									
1.	Stuart Borlase 'Smart Grid: Infrastructure, Technology and Solutions', CRC Press 2012.								
2.	JanakaEkanayake, Nick Jenkins, KithsiriLiyanage, Jianzhong Wu, Akihiko Yokoyama, 'Smart Grid: Technology and Applications', Wiley, 2012								
3.	Mini S. Thomas, John D McDonald, 'Power System SCADA and Smart Grids',	CRC Press, 2015							
4.	Kenneth C.Budka, Jayant G. Deshpande, Marina Thottan, 'Communication Networks for Smart Grids', Springer, 2014								
5.	SMART GRID Fundamentals of Design and Analysis, James Momoh, IEEE press, A John Wiley & Sons, Inc., Publication.								
WEB	REFERENCES:								
https:	//www.researchgate.net/publication/224078022_Power_Quality_and_EMC_i	n_Smart_Grid							
https:	//amity.edu/icactm/Proceeding/Paper%20Index%20Content/24%20T4%20F	9%20ID%209.pdf							
ONLI	NE COURSES:								
https://onlinecourses.nptel.ac.in/noc21_ee68									
https://onlinecourses.nptel.ac.in/noc23_ee124/									
VIDEO REFERENCES:									

https://www.youtube.com/watch?v=KgVFJnmJvKk&list=PLSJzHGpGe6IP5biCvZrtQdHf80tnSXRBr

https://archive.nptel.ac.in/noc/courses/noc20/SEM2/noc20-ee65/

		Constant of the second s							
Mapping of COs with POs and PSOs									
60		3	PO						
CO	1	2	3	4	5	6			
C01	3	2		2	2	2			
C02	3		2	2		2			
CO3	2	1 5	e em			2			
CO4	1			3	3	1			
CO5		2	2	2	2	3			
AVG	2.25	2 2	1.66	2.25	2.3	2			
1-Low, 2 -Medium, 3-High.									



Syllabus for courses offered from 2nd to 4th Semester will be added after the approval of Board of Studies (BoS) and Academic Council (AC) in due course.

